

A simple, robust and adaptable strategy for ballistic landings on small binary bodies.

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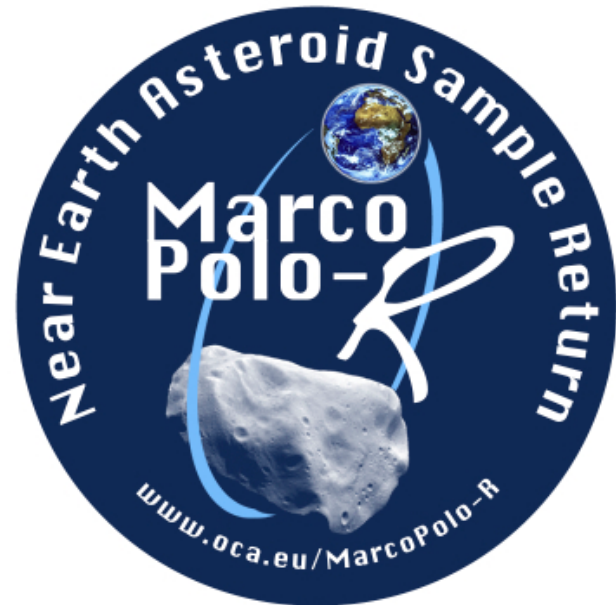
An increased interest for binary asteroids

Discovery mission proposal BASiX



P.I. Dr Daniel Scheeres

ESA Cosmic Vision Marco Polo R.



P.I. Dr A. Barucci & Dr P. Michel

We need robust ways for delivering unpowered landers to the surface of asteroids, while ensuring the safety of the mothership.

Summary of the Presentation



SYSTEM DESCRIPTION

- Jacobi integral
- 0-Velocity surfaces
- e.g. 1999 KW4

STRATEGY DESIGN

FEASIBILITY OF STRATEGY

- Periapses maps
- R.T.O.
- Manifold deliveries

LANDING FROM L2

- Linearizing
- Conley criterion
- Release margins

GROUNDING THE LANDER

The exemple: 1999 KW4

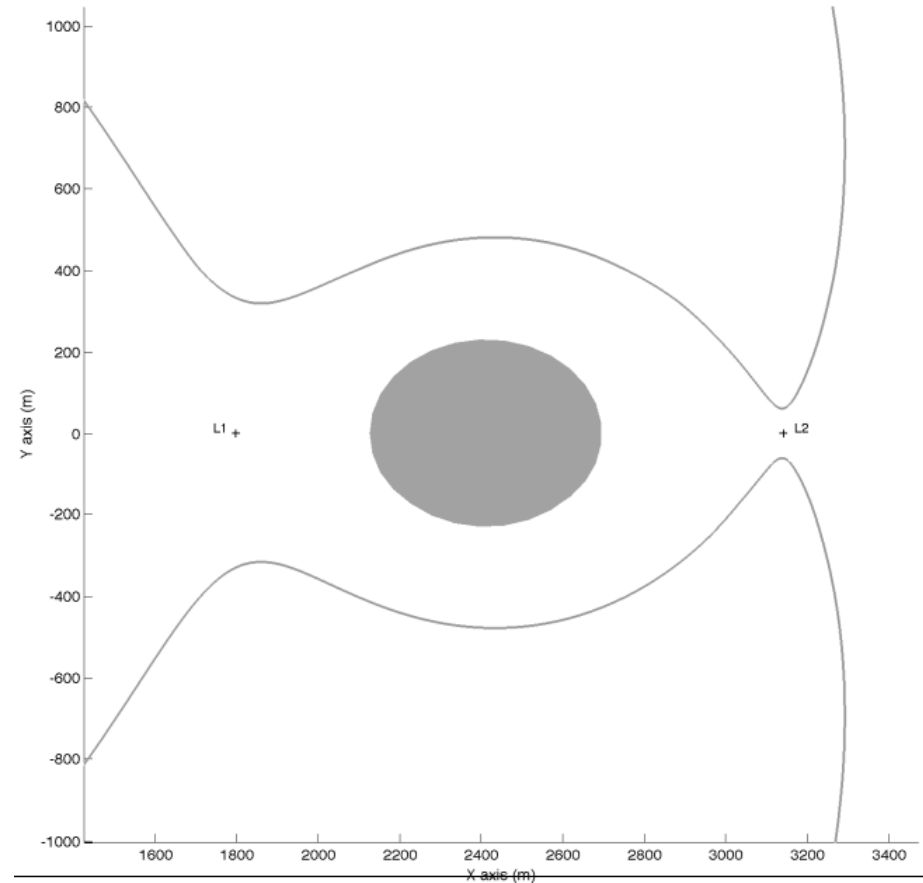
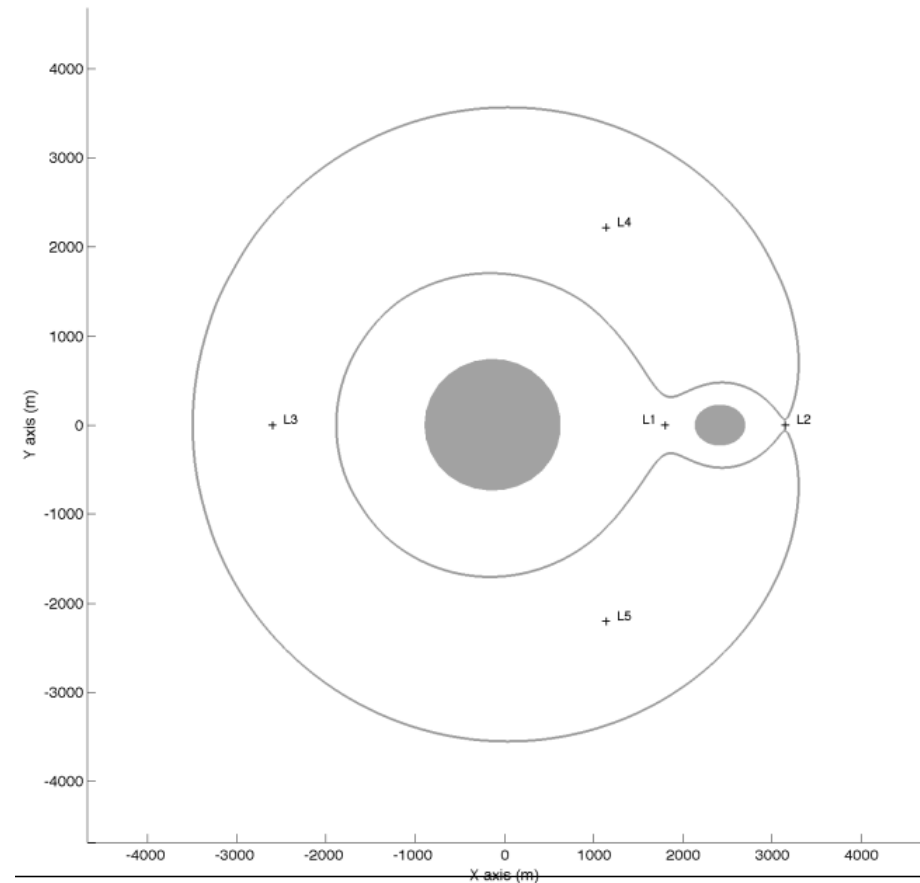


- Binary asteroid system:
 - Alpha (1.5km)
 - Beta (500m prolate)
tidally-locked with Alpha
 - Mutual orbit parameters:
 - $a = 2.5\text{km}$
 - $e = 0$
- Extensively studied
- Representative of binaries
(and very similar to 1996 FG3)

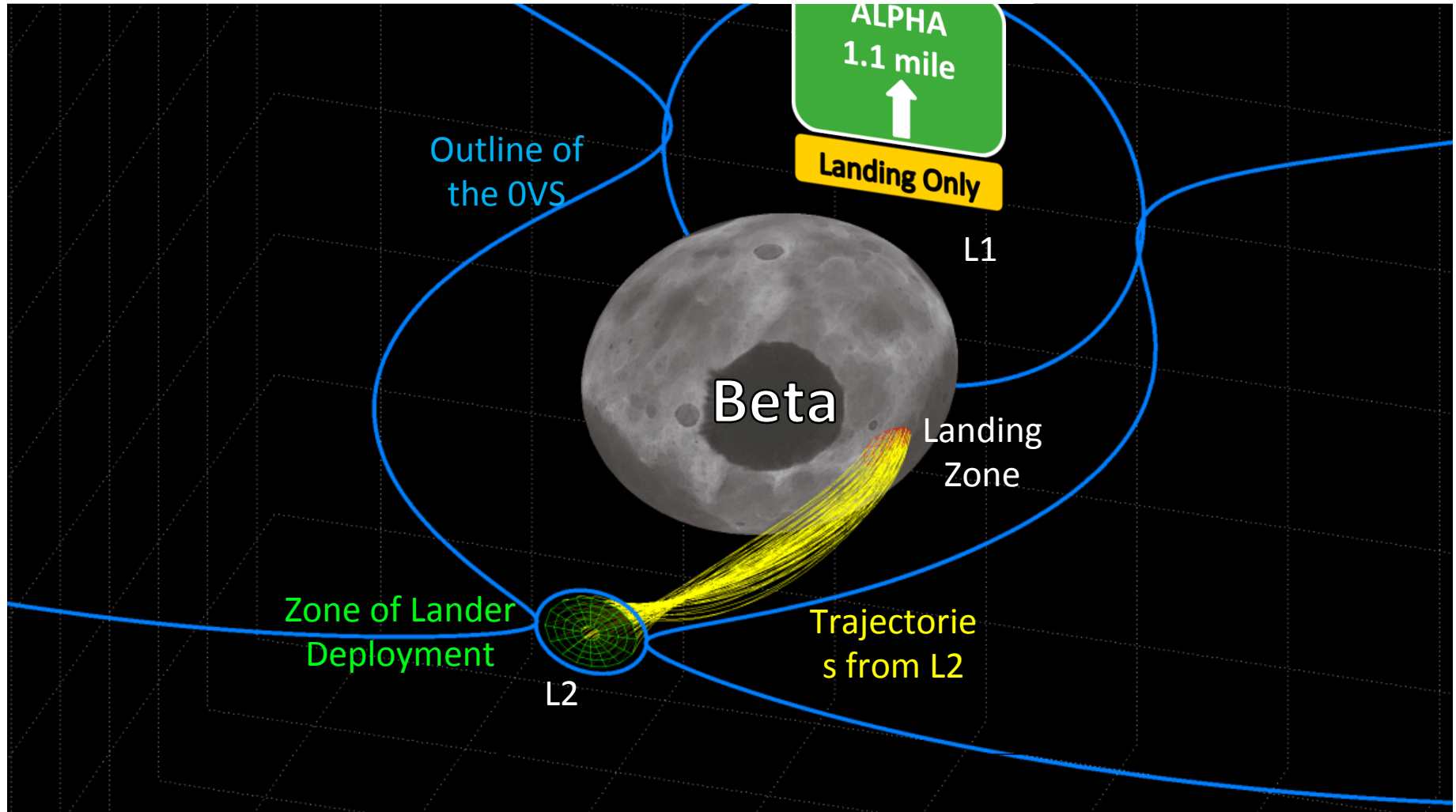


Zero-Velocity Surfaces

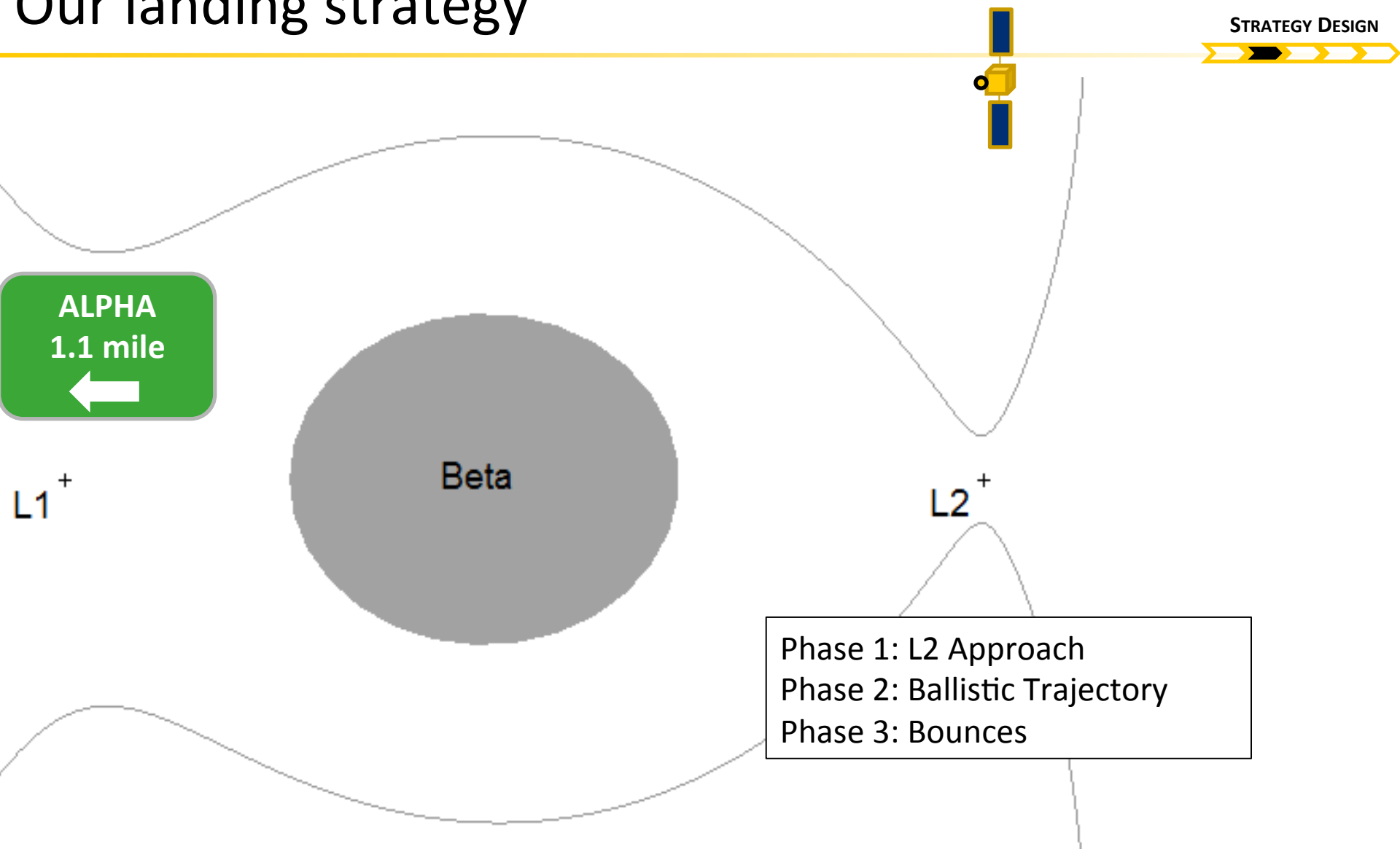
The ZVS separate accessible and forbidden zone of state space



A typical trajectory bundle



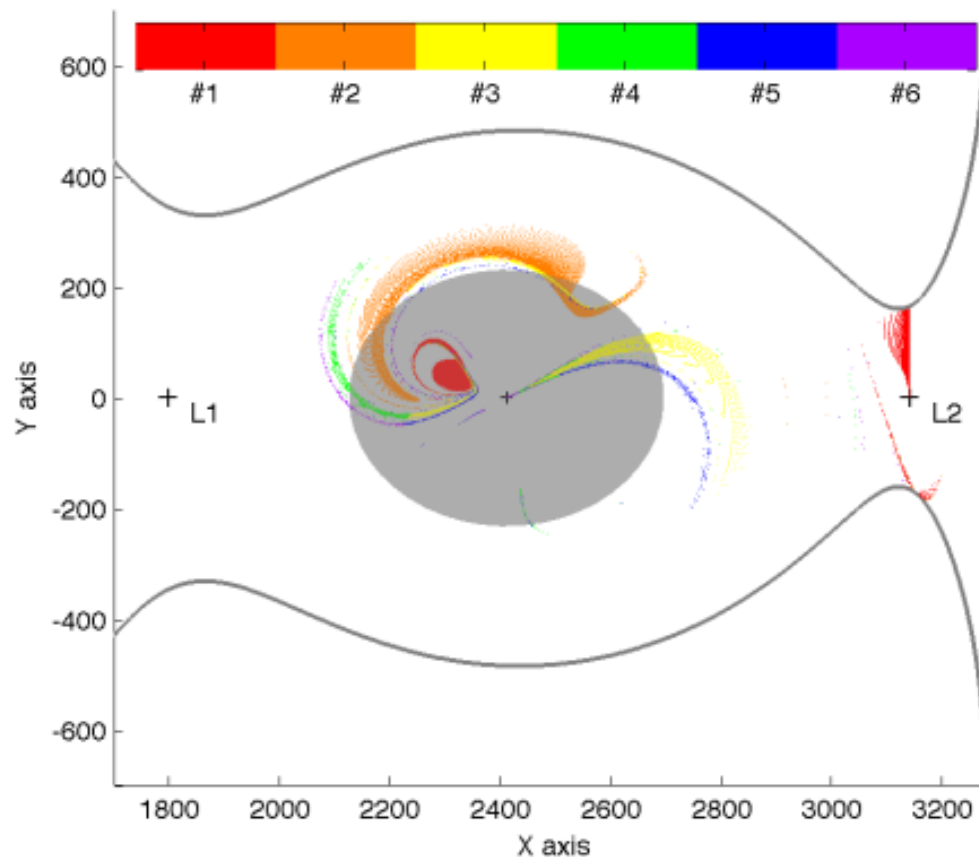
Our landing strategy



Introducing periapses Poincaré maps

FEASIBILITY

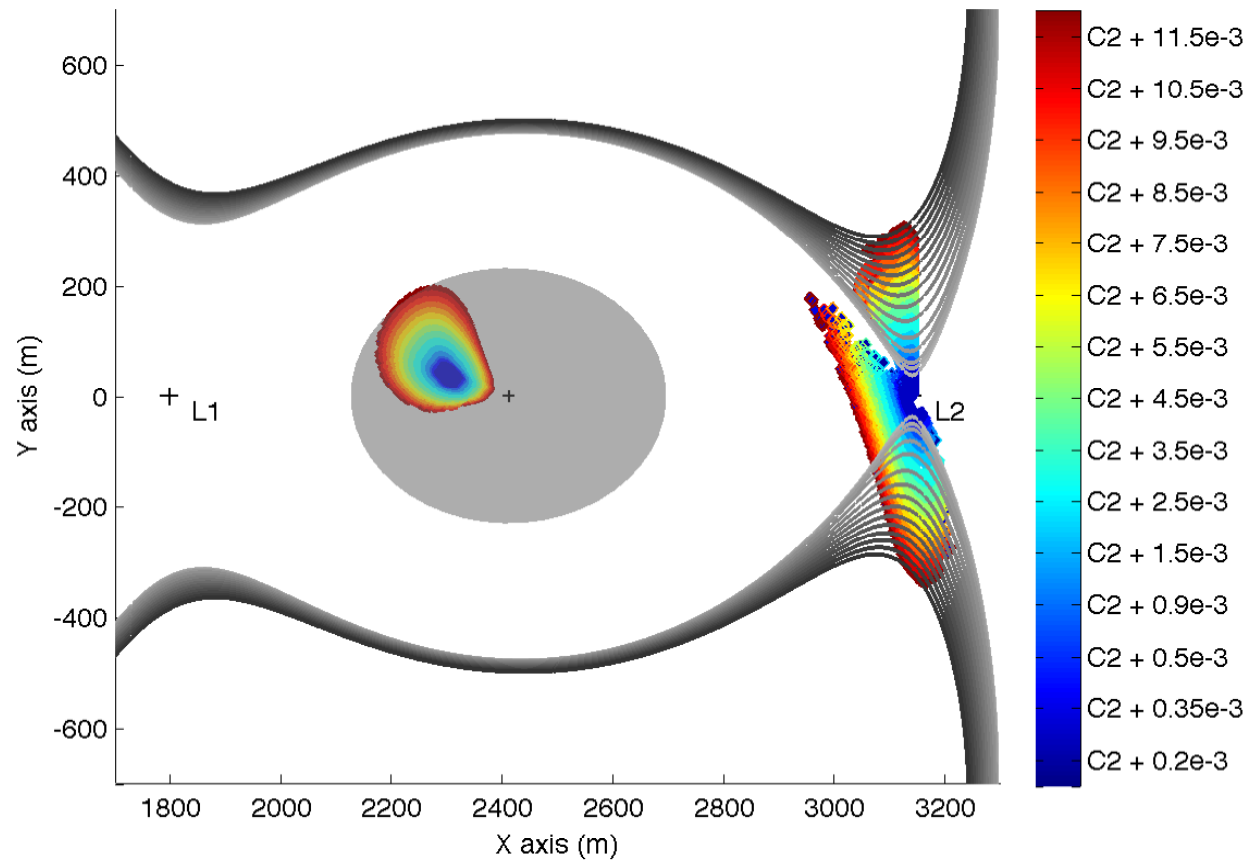
An acceptable landing trajectory is defined as a trajectory whose **1st periapsis** lies under the asteroid surface.



The shape of the first periapsis region

FEASIBILITY

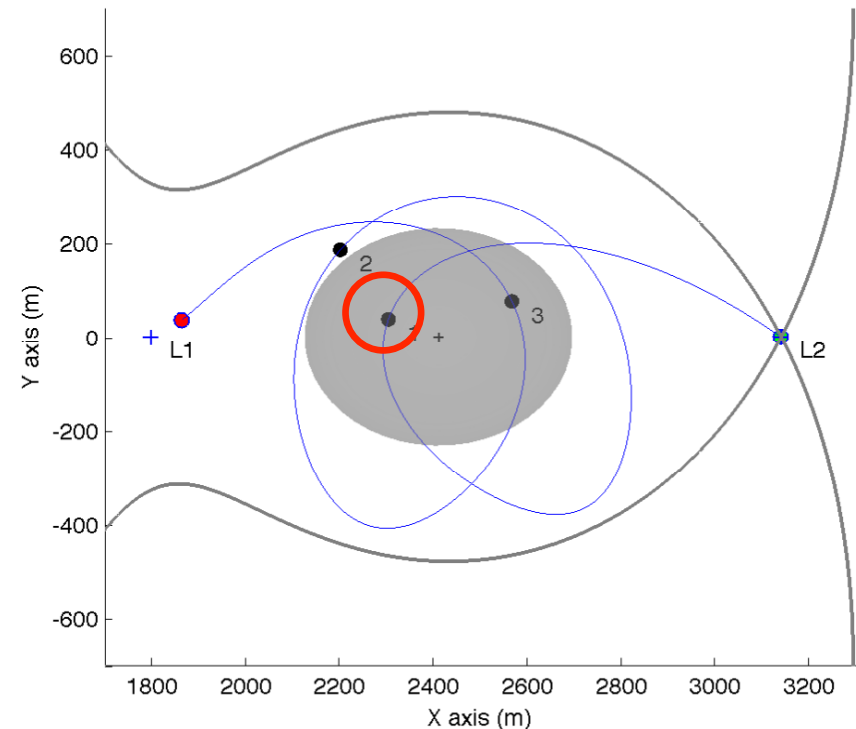
The 1st periapsis region grows with energy



Manifold deliveries and RTO

FEASIBILITY

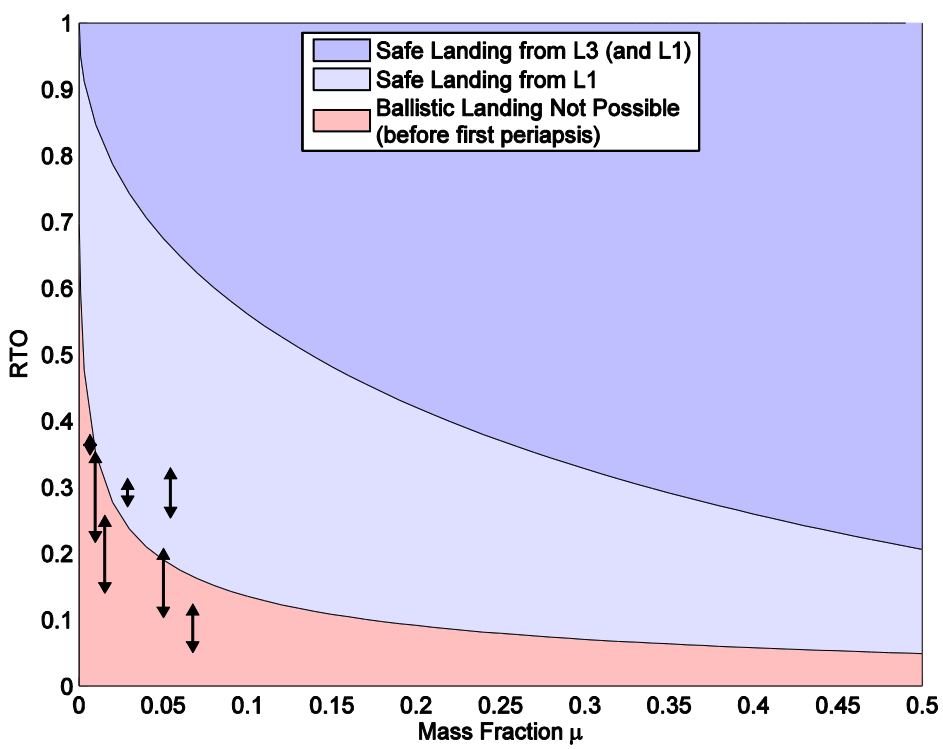
- Problem has too many variables:
 - Mass fraction μ
 - Energy C
 - Shape and size of the asteroid
- RTO : Radius-To-Orbit ratio is the radius in normalized units (e.g. , 6.9% for 1999 KW4)
- Manifold delivery reduces to two variables: μ and RTO .
 - If 1st periapsis < RTO
then **OK for some range of C**
 - If 1st periapsis > RTO
then **dangerous for any range of C**



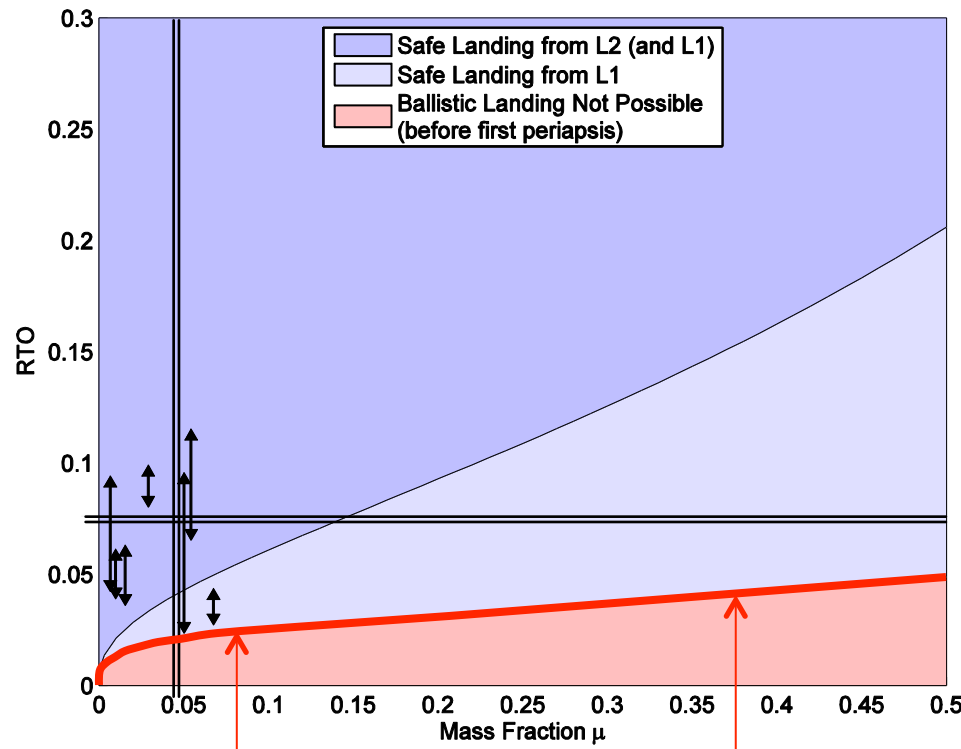
Feasibility of the strategy

FEASIBILITY

Landing on the primary (Alpha)



Landing on the secondary (Beta)



If your secondary fits above **this line**, the strategy works!

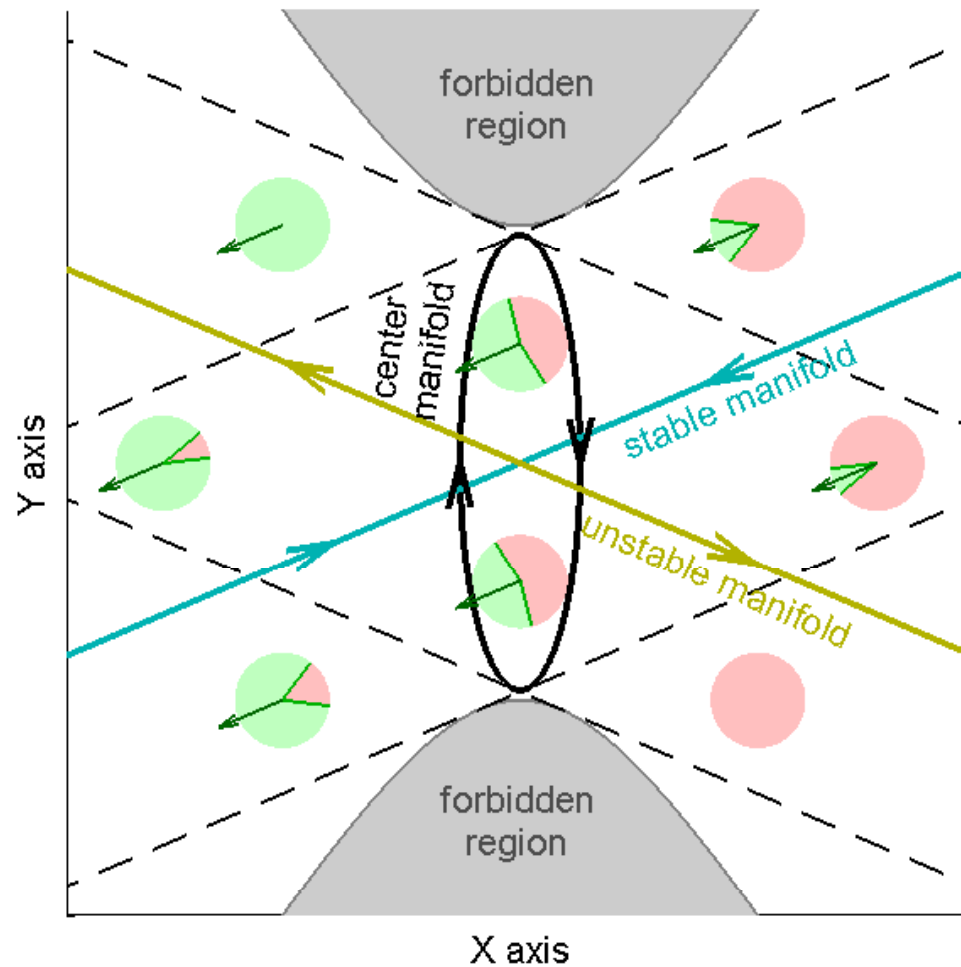
All trajectories that enter the secondary's region will impact...

... how can we ensure that our lander will enter this region ?

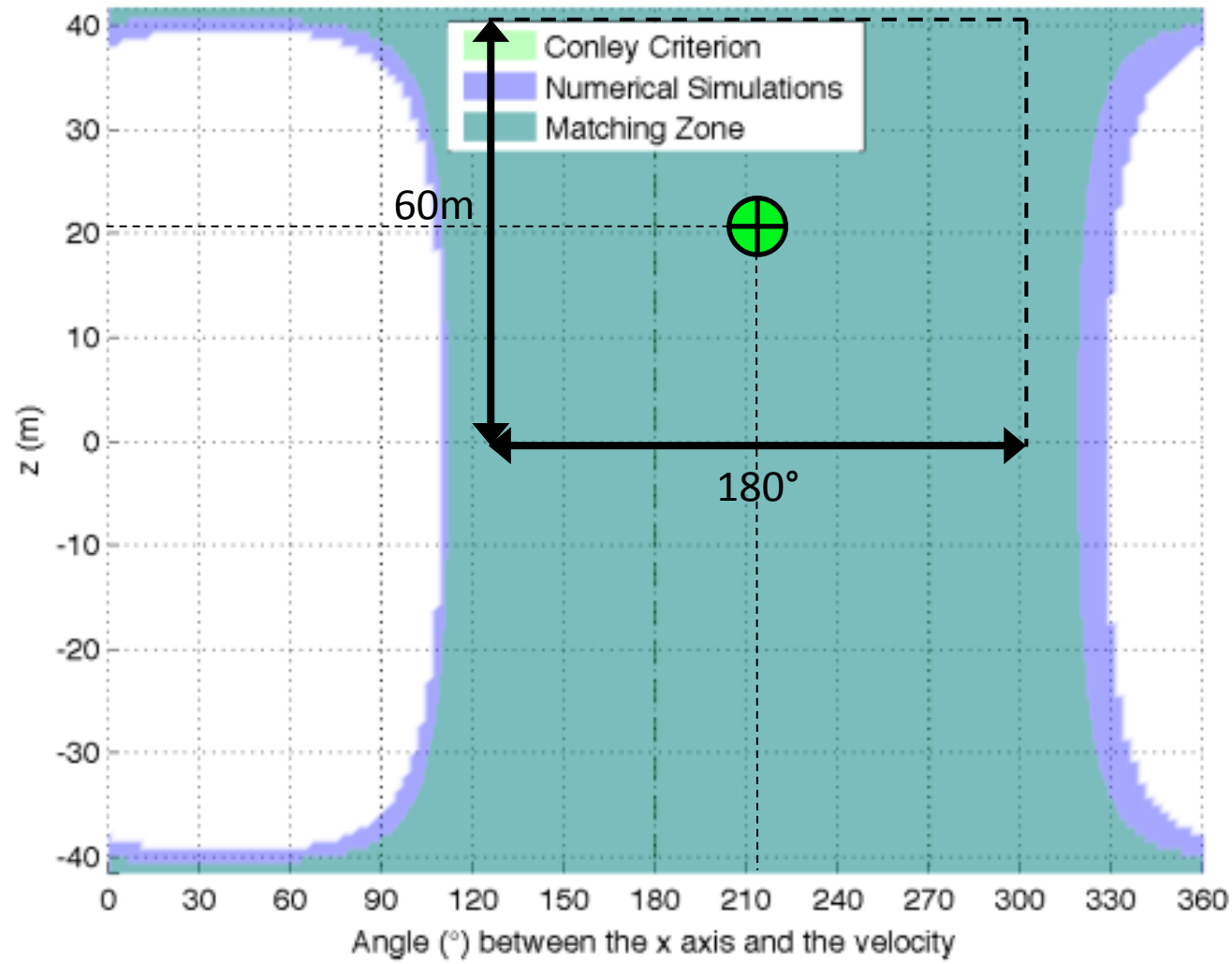
➔ Following Conley (1968), linearizing at L2, we obtain a criterion on the polar angle of velocity at the neck.

A representation of Conley's criterion

LANDING FROM L2

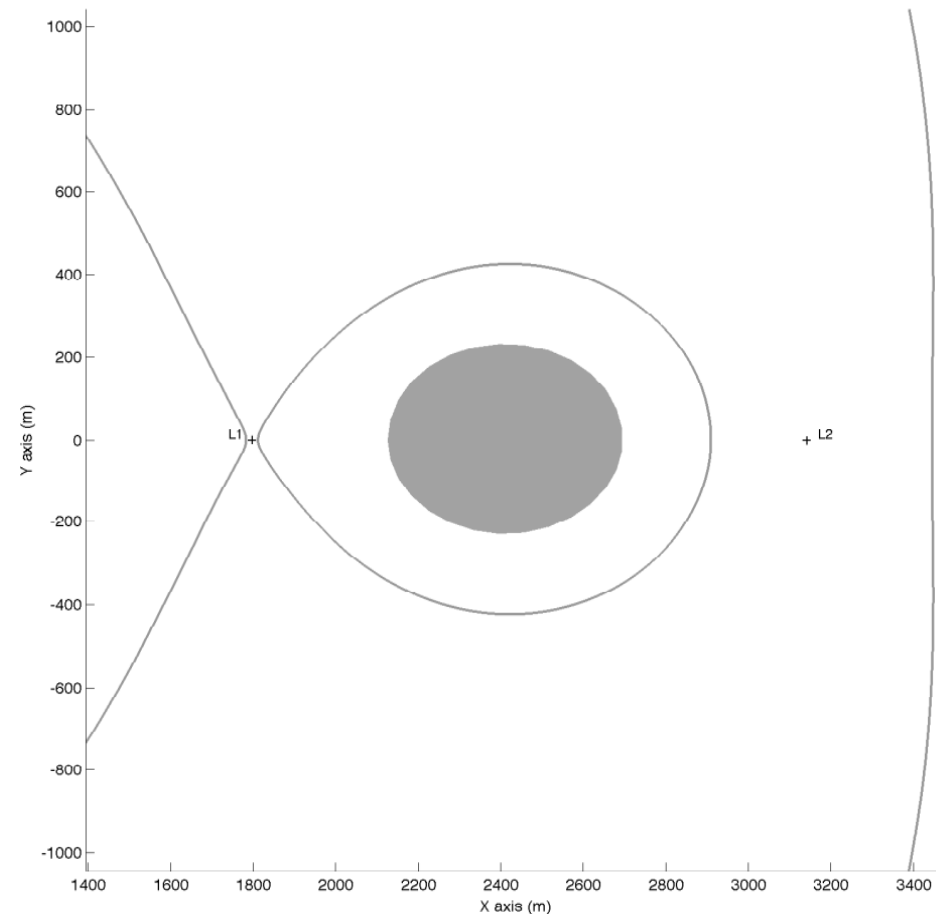


Matching analytics with simulations



Grounding the lander

- We reach the surface...
but do we land ?
 - Neck closure criterion
- ➔ 7% speed damping at impact
is sufficient



Main features of the landing strategy

- Landing on the secondary is feasible for the vast majority of binary NEOs.
- The deployment consists in releasing the lander in the L2 neck with a designated velocity direction and speed.
- No GNC needed for the lander.
- No risk for the mothership.
- Margins that applies on deployment conditions are (for KW4) :
 - -100m to +100m on the nominal y-axis release position
 - 0% to 500% error the nominal deployment speed
 - -90° to +90° on the nominal velocity direction

Questions?

