9<sup>th</sup> International Planetary Probe Workshop Toulouse, France June 2012

## Technology Development toward Mars Aeroflyby Sample Collection

K. Fujita\*,

T. Ozawa\*, K. Okudaira†, T. Mikouchi‡, T. Suzuki\*, H. Takayanagi\*, Y. Tsuda\*, N. Ogawa\*, S. Tachibana‡, and T. Satoh\*

\* Japan Aerospace Exploration Agency
 † University of Aizu
 ‡ University of Tokyo

## Background

### Mars Exploration with Landers & Orbiters Synergy (MELOS)

- Currently entertained in Japan (2020 launch)
- Conglomerate mission where orbiters, landers, rovers, and/or airplanes are used for aeronomical, meteorological, and geoscientific researches as well as life search
- To reveal why Mars is now in red the fate of ancient water and carbon dioxide on the course of Martian history

#### Mission scenario

- MELOS system is first inserted into primary orbit altogether
- Entry systems are flown into Martian atmosphere using orbiter as a service module
- Orbiter is maneuvered to final orbit for scientific operation
- $\rightarrow$  Great potential for a variety of probe vehicles incorporated into MELOS



## Mars Aeroflyby Sample Collection (MASC)

#### Mission concept

• Collection of Martian dust & gas samples during aeroflyby and return to Earth

25 km (av)

• Originally proposed by Leshin et al. as a candidate for Mars Scout mission

#### Scenario

#### Dust fluence for V = 4 km/s (count/cm<sup>2</sup>.sec) MOI o Altitude (km) Diam. = $0.5 - 1.5 \,\mu m$ 1.5–2.5 μm 2.5–3.5 μm 1–10 µm 45 0.05 0.04 0.02 0.23 40 3 1.4 16 4 nal orbit 35 56 48 23 252 Ad 30 367 312 148 1650 rs may V 25 1331 1129 536 5984 em) b 20 3526 2991 1420 15849 е Parking Sample retu analysis oved instruments Sample retu Return to Earth



# **Fundamental Design Parameters for MASC**

## Critical keys

- Successful insertion to an orbit appropriate for earth return : precise GNC using lifting aeroshell is needed to cope with uncertainties in atmospheric density, aerodynamics of vehicle, & orbit/attitude determination
- Minimization of total ΔV required for AOT, post-AOT maneuver, and earth return
- Accessible lowest altitude < 40 km for sample collection
- Minimization of TPS for aerodynamic heating



#### ЬX

# **Fundamental Mission Design**

#### Design criteria

- Minimize total system mass (minimum dry mass of earth return subsystem may be almost determined by heritages of past systems)
- Decrease propellant mass for earth return to minimize mass of orbiter subsystem
- Increase apoapsis altitude of parking orbit to decrease  $\Delta V$  for earth return
- Decrease  $\beta$  for reduction of TPS mass
- Increase  $\beta$  to enlarge ATO corridor

Orbit design		Aeroshell			
Primary elliptic orbit (orb1)	300 × 7 $R_m$ altitude	Structure	CFRP honeycomb with TPS		
AOT target orbit (orb2)	150 × 500 km altitude	Area density	7.5 kg/m <sup>2</sup>		
Theoretical $\Delta V$ for orb1 $ ightarrow$ orb2	–1.10 km/s	TPS bulk density	0.25 g/cm <sup>3</sup>		
Nominal flight path angle	-11.54 <sup>o</sup>	Aeroshell shape	Sphere-cone		
Allowed deviations	±0.20°	Half-cone angle	20 deg		
Expected lowest altitude	34.0±5.0 km	Base diameter, $D_B$	1.63 m		
Post-AOT ΔV	< 60 m/s	Nose radius, R <sub>n</sub>	0.38 m		
Final parking orbit (orb3)	500 × 500 km altitude	Aerodynamic characteristics			
$\Delta V$ required for orb2 $\rightarrow$ orb3 $\Delta V$ required for orb3 $\rightarrow$ earth	+ 79 m/s + 2.60 km/s (incl. margin)	Ballistic coefficient	700 kg/m <sup>2</sup>		
Propulsion system (OME & RCS)					
Fuel / Oxidizer	Hydrazine / MON-3	AOT guidance			
O/F ratio	0.8	Guidance algorithm	APC + lateral control		
Specific impulse	315 sec	Attitude control	PID yaw/pitch controller		
Structural factor	0.25	<i>L/D</i> control method	Bank-angle modulation		
Ballistic	coefficient ka/m <sup>2</sup>	Control device	bipropellant RCS		

Damslic Coemclent,

# Aerodynamic Design

## System requirements

- L/D > 0.3 (up to 0.4 for  $\alpha < 12$ )
- $\beta \approx 700 \text{ kg/m}^2$
- Equipped with light-weight TPS
- Equipped with RCS's
  - Nose radius = 0.38 m
  - Half cone angle = 20<sup>o</sup>
  - Base diameter = 1.62







JAX

## **TPS** Design



## Development of non-ablative light-weight TPS (NALT)

- Non-ablative TPS is favorable for dust sampling during hypersonic flight
- NALT consists of C/C skin, thermal insulator, and honeycomb structure

### Conceptual design of MASC aeroshell

- 1D TPS analysis along a flight trajectory (search for solutions by trial-&-error method)
- Resulting in TPS area density of 9.0 kg/m<sup>2</sup> at stagnation point, 7.5 kg/m<sup>2</sup> in average, and total aeroshell mass of 133 kg





ted C/C composite ski

#### 1D TPS analysis along flight trajectory



#### AXA CO

## Design of GNC Subsystem

### GNC subsystem configuration

- Effective descent/ascent rate control by bank-angle modulation using RCS's
- Analytic predictor-corrector (APC) controller for primary GNC architecture
- Lateral controller to minimize lateral deviation
- Proportional-integral-derivative (PID) controller for yawing/pitching stabilization

### Assessment of designed GNC controller robustness

- Monte-Carlo simulation by taking into account uncertainties in atmospheric density, aerodynamics of vehicle, orbit determination, and guidance to entry I/F point
- Results have shown sufficient robustness of designed GNC controller
- Fuel used in bank-angle modulation is minimized by optimizing RCS's operation



$3\sigma$ in $\Delta V$	Apoapsis altitude (km)			Orbit inclination (deg)			Success rate	
(m/s)	minimum	average	maximum	minim	num	average	$\max$ imum	(%)
0.3	222.6	564.9	703.9	-0.4	404	0.135	1.632	99.8
0.5	232.1	561.9	782.42	-0.5	576	0.144	1.777	99.8
0.7	200.7	557.4	897.2	-0.8	899	0.149	1.813	99.8
			$3\sigma$ in $L/L$	D (%)	Succe	ess rate (%	)	
			5.0			99.8		
			10.0	)		99.8		
K-W			20.0	)		98.2		

## **Dust Sampler Design**

#### Approach

- Retractable samplers (currently 2) are exposed for a few seconds
- Samplers are located near aeroshell base to reduce heat transfer rate
- Silica aerogel is used for capturing sample particles (like STARDUST)
- Aerogel cells are transported to the reentry capsule inside MASC

#### Key issues

- 1. Damages inflicted on dust particles by high-temperature shock layer
- 2. Damages inflicted on aerogel exposed to high-temperature shock layer
- 3. Dust capturing capabilities of aerogel
- 4. damages inflicted on dust particles by impingement
- 5. capabilities of detecting & extracting dust samples stuck in the aerogel



**Dust particles** 







# Assessment of Sample Damages

## Trajectory & heat transfer analysis of sample dust particles

- Particles rush almost straightly across the shock layer and reach the aeroshell surface.
- Particle temperature remains below the critical temperature since flight time < 5  $\mu$ s.
- Temperature raise can be reduced by optimizing position of the sample collector in



#### JAXA C

11

# Assessment of Aerogel Damages

#### Arcjet heating test campaign

- 1<sup>st</sup> circular : aerogel surface was vitrified to the depth of several μm & charred materials were formed on the surface by oxidation of hydrophobizing agents
- 2<sup>nd</sup> circular : an aerogel cell to shore up structural strength as well as to reduce heat transfer rate was successfully demonstrated with non-hydrophobic aerogel
- 3<sup>rd</sup> circular : non-silica aerogel specimens are tested to improve heat resistance

# 1<sup>st</sup> test campaign





#### 2<sup>nd</sup> test campaign





#### 3<sup>rd</sup> test campaign

 Carbon aerogel (CA)
 CASA: CA/SA 2-layer aero-gel for higher heat-resistance





## Assessment of Dust Capturing Capabilities

### LGG dust capture tests (at Space Plasma Lab., ISAS)

- Alumina/montmorillonite particles of 10-30 μm in diameter were successfully captured by aerogel cells before/after arcjet-heating
- Scan, extraction, & SEM/EDS analysis of samples has been successfully demonstrated

#### VdG dust capture tests (at HIT)

 Argental particles of 1 μm in diameter were successfully captured by aerogel cells both before/after arcjet-heating.

#### VdG dust capture tests





SEM/EDS Analysis (montmorillonite, 10 μm) Particle surface is seen to somehow contaminated by melted aerogel.





## System Configuration

#### Conceptual system design

- Conducted based on the latest status of subsystem development, and on heritages of HAYABUSA sample return system
- Further reduction of system mass may be realized by introducing new instruments

Total mass	593		
Orbit insertion subsystem	175		
Aeroshell	133		
RCS (dry)	15		
Hydrazine (fuel)	15		
MON-3 (oxidizer)	12		
Orbiter subsystem	358		
OME propellant for departure	190		
Hydrazine (fuel)	105		
MON-3 (oxidizer)	85		
Earth return subsystem	168		
OME (dry)	48		
Hydrazine (fuel)	15		
Structure	35		
Sampler	10		
Electronics	44		
Earth reentry capsule	16		
Margin	60		







14

## Development Plan (if applied to MELOS1)



## Conclusion



15

Mars Aeroflyby Sample Collection (MASC) using AOT technologies is proposed as a part of MELOS mission

#### Feasibility study of MASC has been conducted

 The trajectory calculations have shown that a wide AOT corridor acceptable for the state-of-the-art GNC technologies in planetary explorations can be achieved by use of a lifting aeroshell with L/D > 0.3.

#### Preliminary R & D of the MASC subsystems are in progress

- The integrated aeroshell with the TPS is designed to have a 7.5 kg/m<sup>2</sup> area density
- Robustness of developed GNC controller has been demonstrated
- Overall examinations of dust sampling & analyzing techniques have been conducted
- The dust particles are expected to reach the collector across the shock layer without fatal damages
- Silica aerogel cell is found to capture dust samples of sub-µm in diameter, regardless of heat transfer from the high-temperature gases

### MASC system is feasible with a minimum total mass of 600 kg

MASC is also applicable to other missions, or even solely