



CENTRE EUROPÉEN DE RECHERCHE ET DE FORMATION AVANCÉE EN CALCUL SCIENTIFIQUE

2019 Drone Garden Workshop | GIS Micro-drones

Data assimilation for wildland fire behavior

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Inria, Université de Bordeaux & Université Paris Saclay

Didier Lucor

LIMSI, CNRS, Université Paris Saclay



Talk's introduction

Data assimilation in a nutshell



Rochoux et al. (2017),
Wildfire Magazine



Observations



Numerical simulations

Talk's introduction

Data assimilation in a nutshell



Rochoux et al. (2017),
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Observations

- Sparse
- Limited spatial coverage and resolution



Numerical simulations

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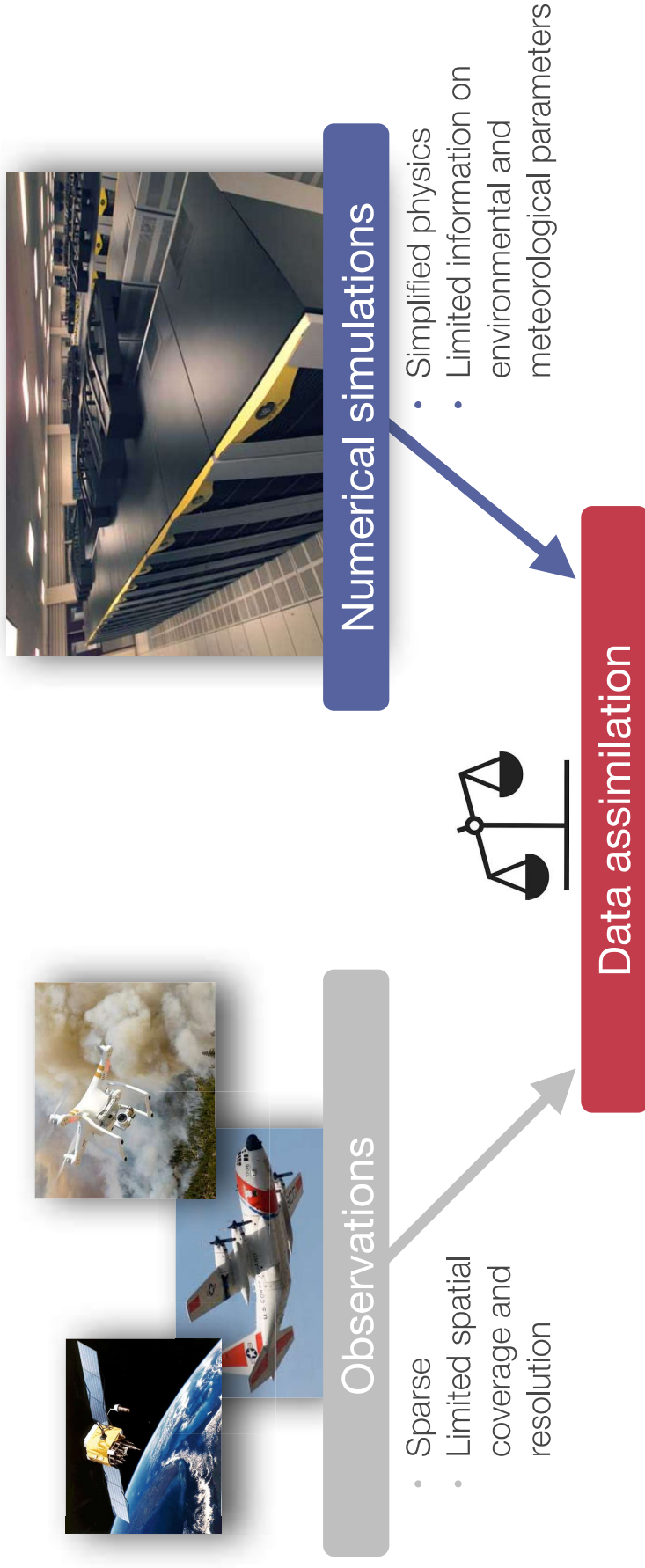
Numerical simulations

- Simplified physics
- Limited information on environmental and meteorological parameters

Data assimilation in a nutshell



Rochoux et al. (2017),
Wildfire Magazine

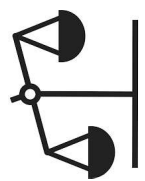


Data assimilation in a nutshell



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Data assimilation

Statistical aggregation of different sources of information

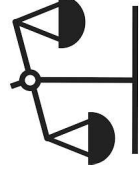
- Uncertainty quantification (error model)
- Inverse modeling (estimation)
- Forecast capability (using the model to extrapolate the system dynamics beyond observation times)

Data assimilation in a nutshell



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Talk's introduction Observations



Paugam et al. (2013), IEEE transactions on geoscience and remote sensing



Paugam et al. (2019), EGU General Meeting

How to extract and assimilate information from infrared imagery?



KING'S
College
LONDON
University of London



2014 Kruger National Park

- 7-hectare savannah fire
- Operated from helicopter
- Multiple channels: MIR-LWIR-VIS
- High resolution (1 m, 1 Hz)

Datasets:
controlled burn
experiments

Talk's introduction Observations

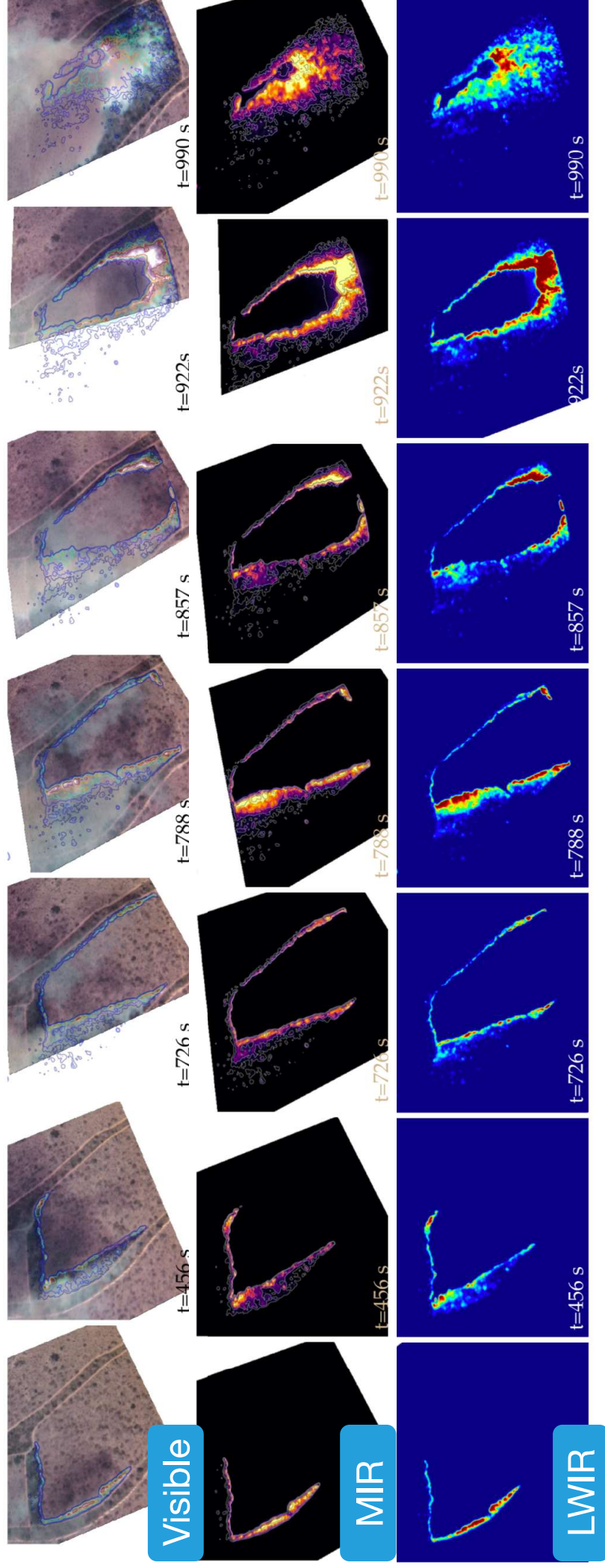


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Talk's introduction

Model and uncertainties



Wildfire complexity
Current burnt-area models are far from being predictive

- A fire creates its own weather.
- Strong interactions between wind and terrain topography
- Limited knowledge on biomass

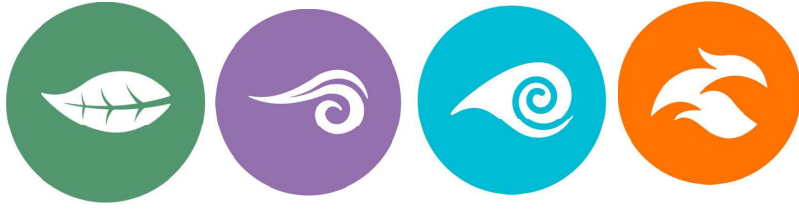
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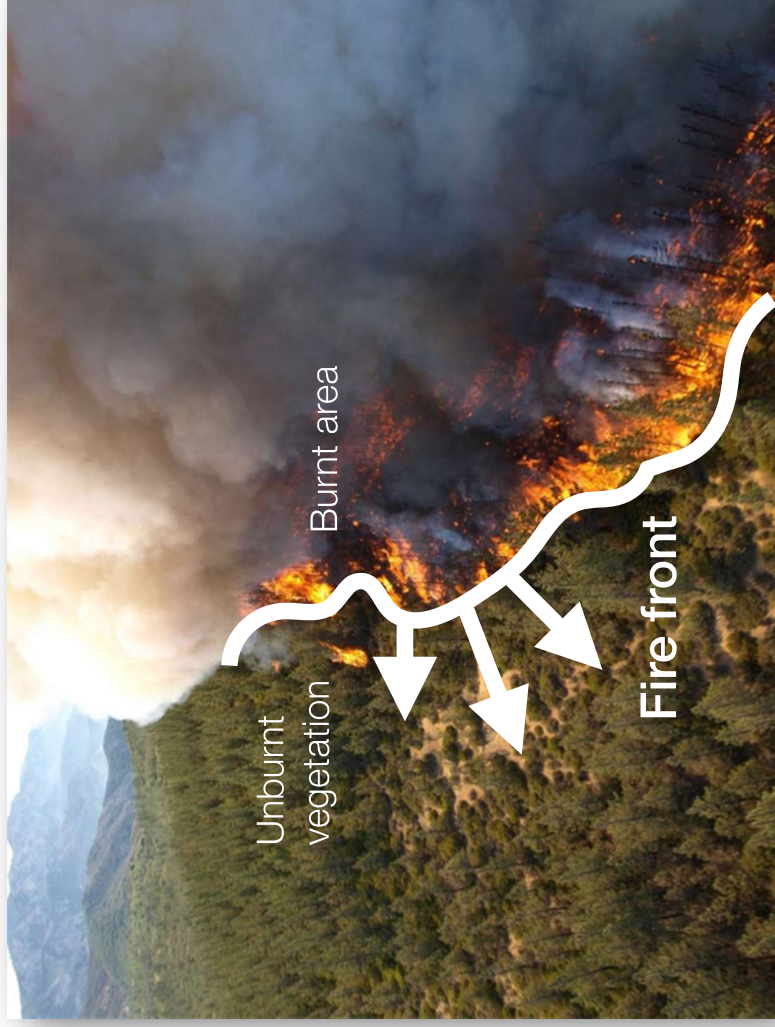
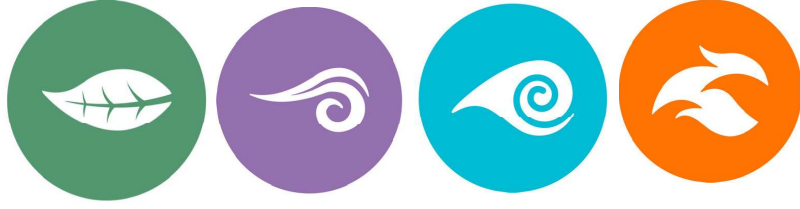
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Physical parameters

Talk's introduction

Model and uncertainties

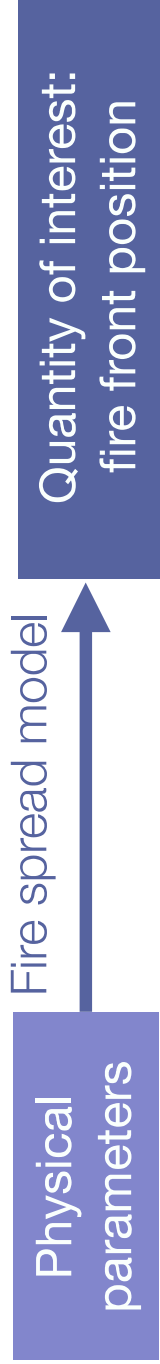


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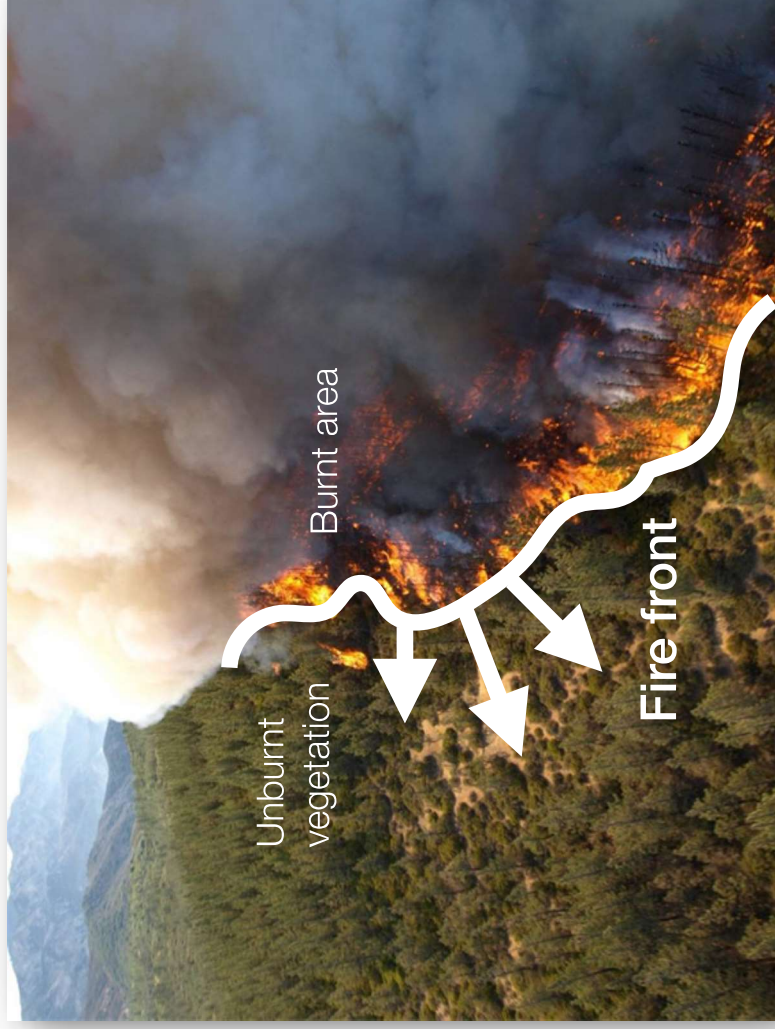
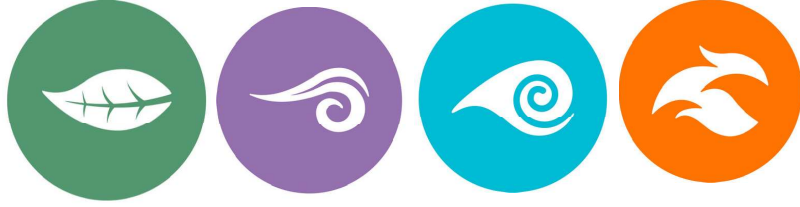
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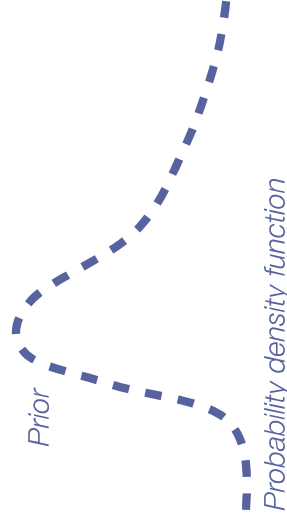
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Sources of uncertainty

Quantity of interest: fire front position

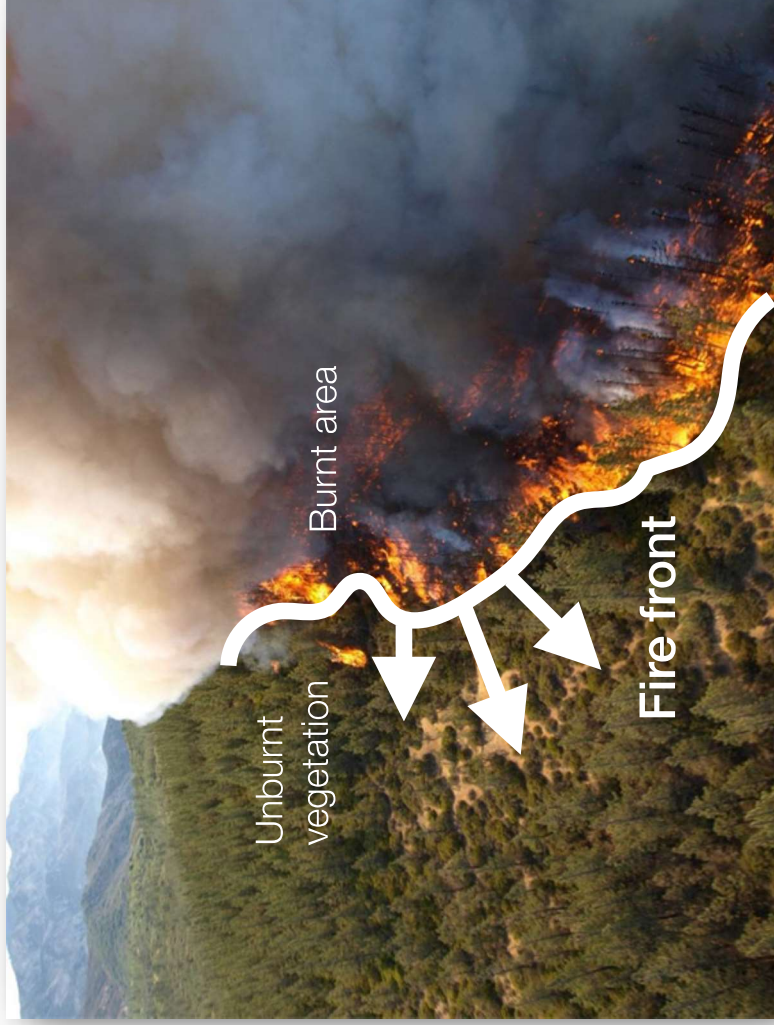
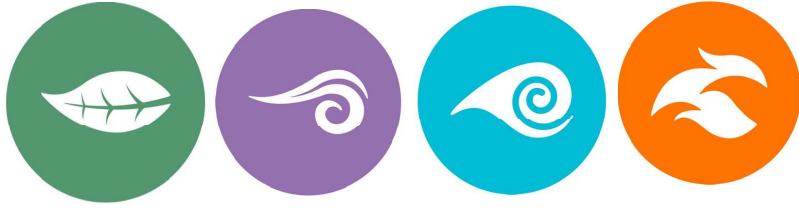
Uncertainty quantification



Model and uncertainties



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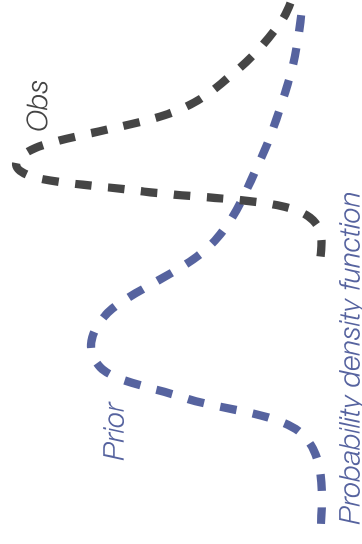
Physical parameters

Fire spread model
Uncertainty propagation

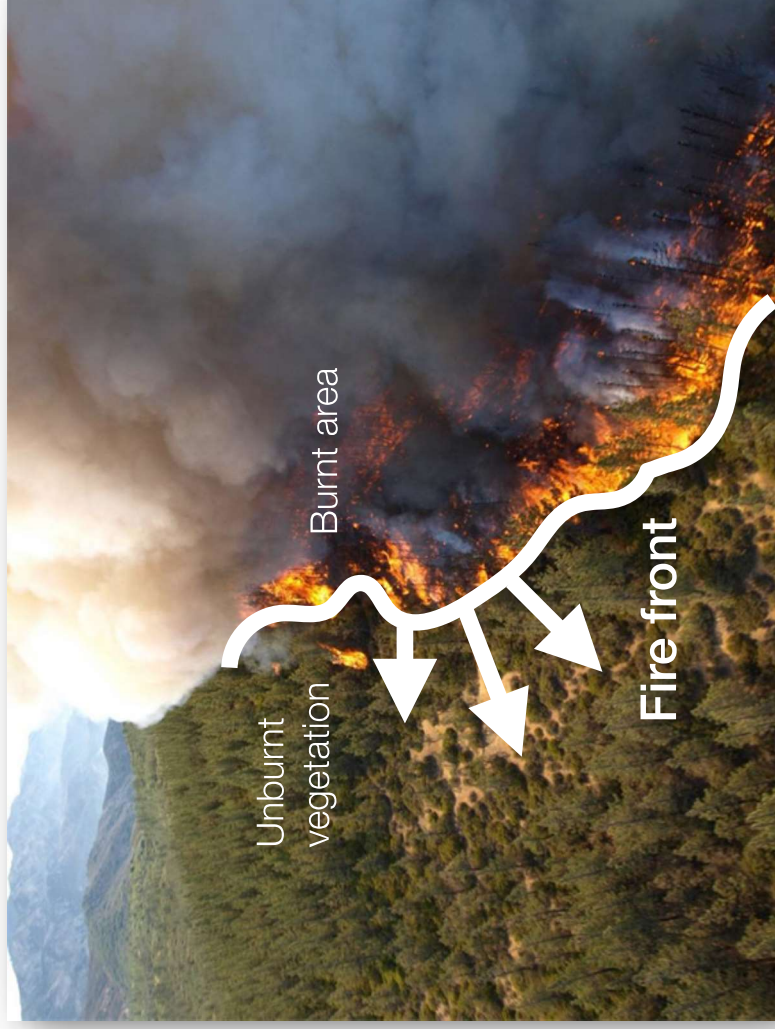
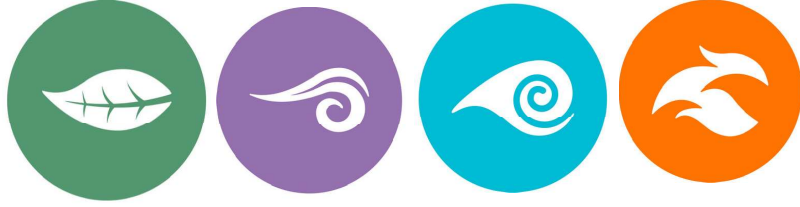
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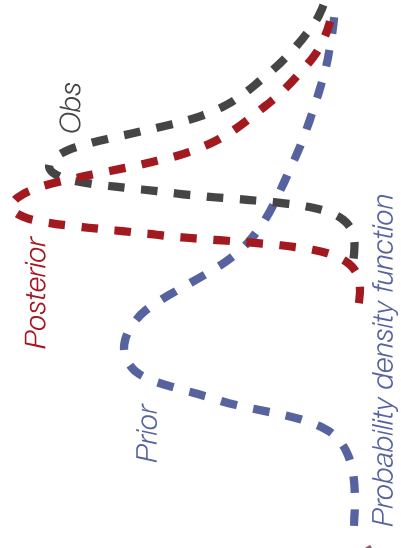
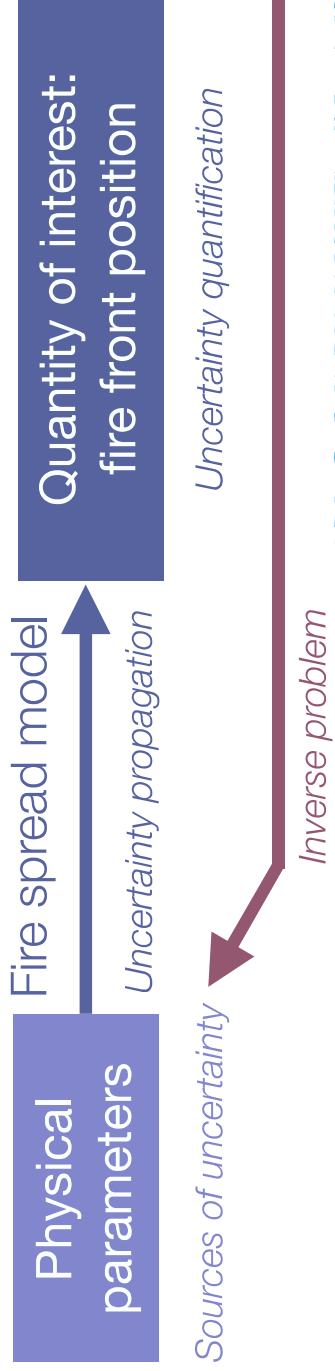
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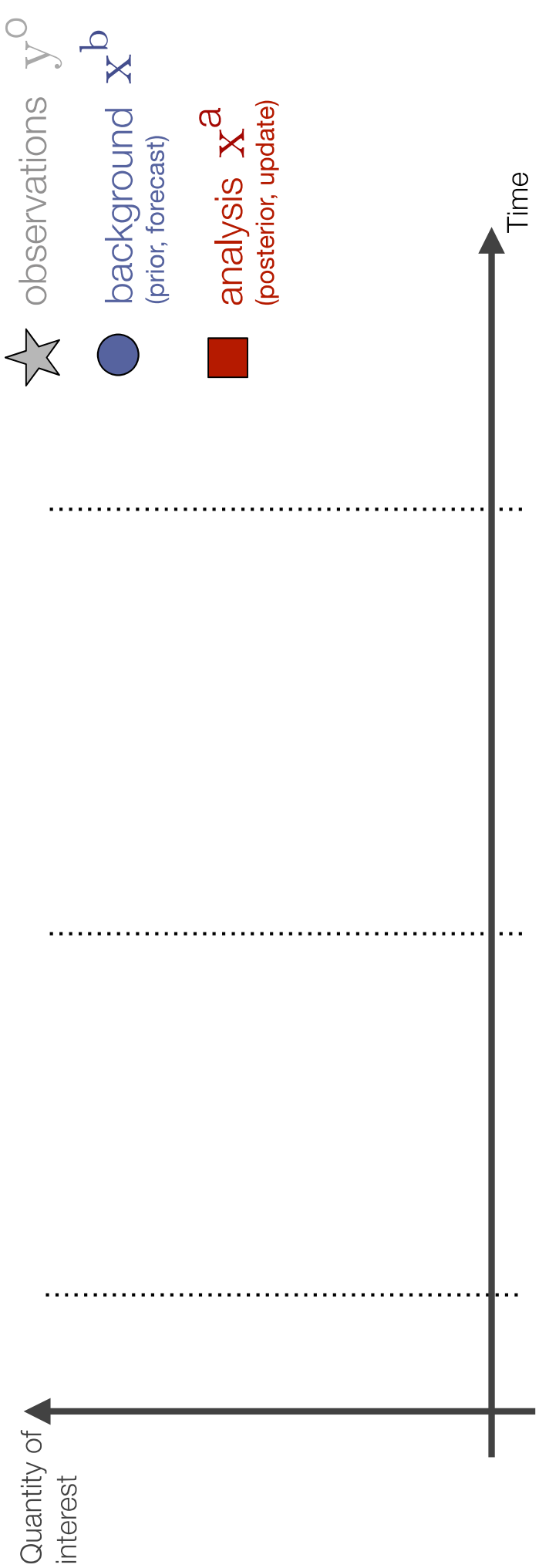
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Back to data assimilation



Sequential data assimilation



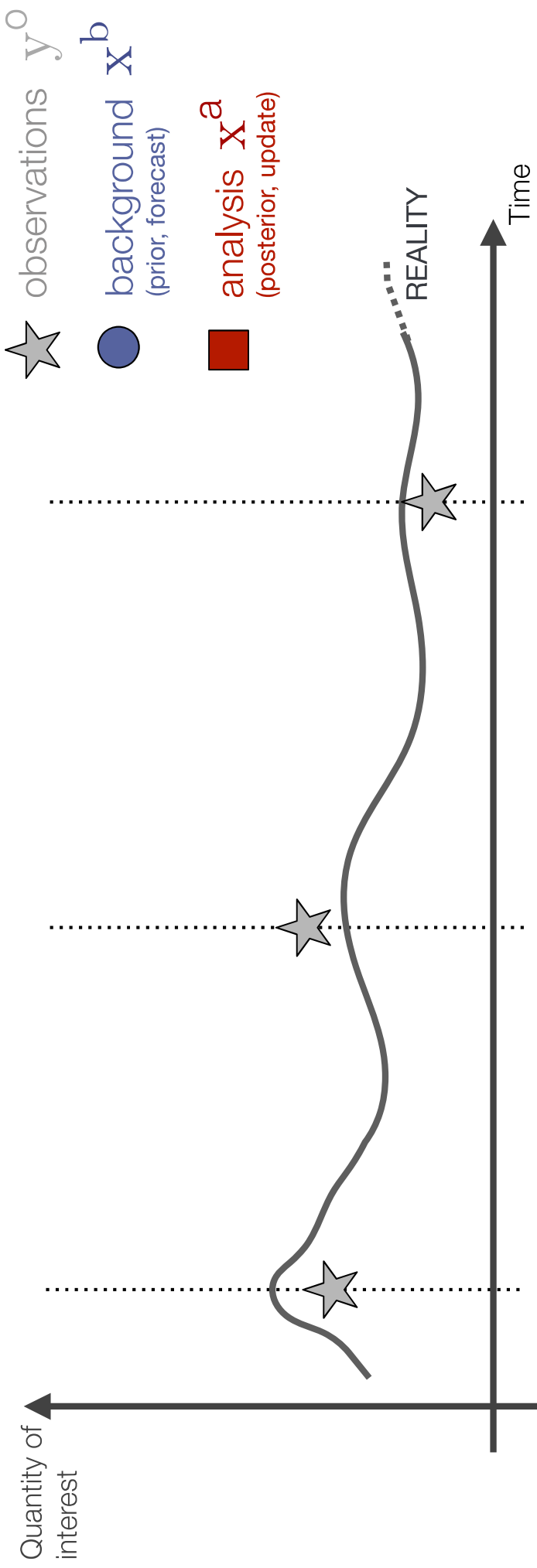
Generalized least-squares problem

$$\mathcal{J}(\mathbf{x}) = \|\mathcal{G}(\mathbf{x}) - \mathbf{y}^o\|_{\mathbb{R}^{r-1}}^2 + \|\mathbf{x} - \mathbf{x}^b\|_{\mathbb{B}^{n-1}}^2 \rightarrow \mathcal{J}(\mathbf{x}^a) = \min \mathcal{J}(\mathbf{x})$$

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Sequential data assimilation



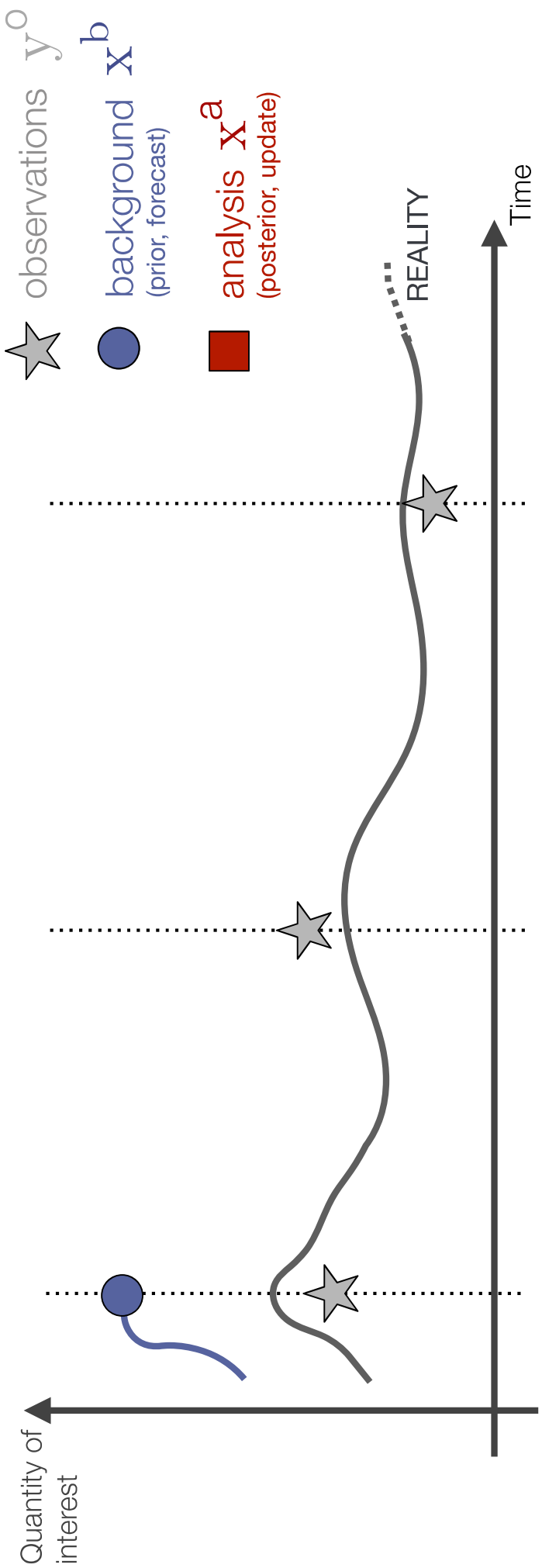
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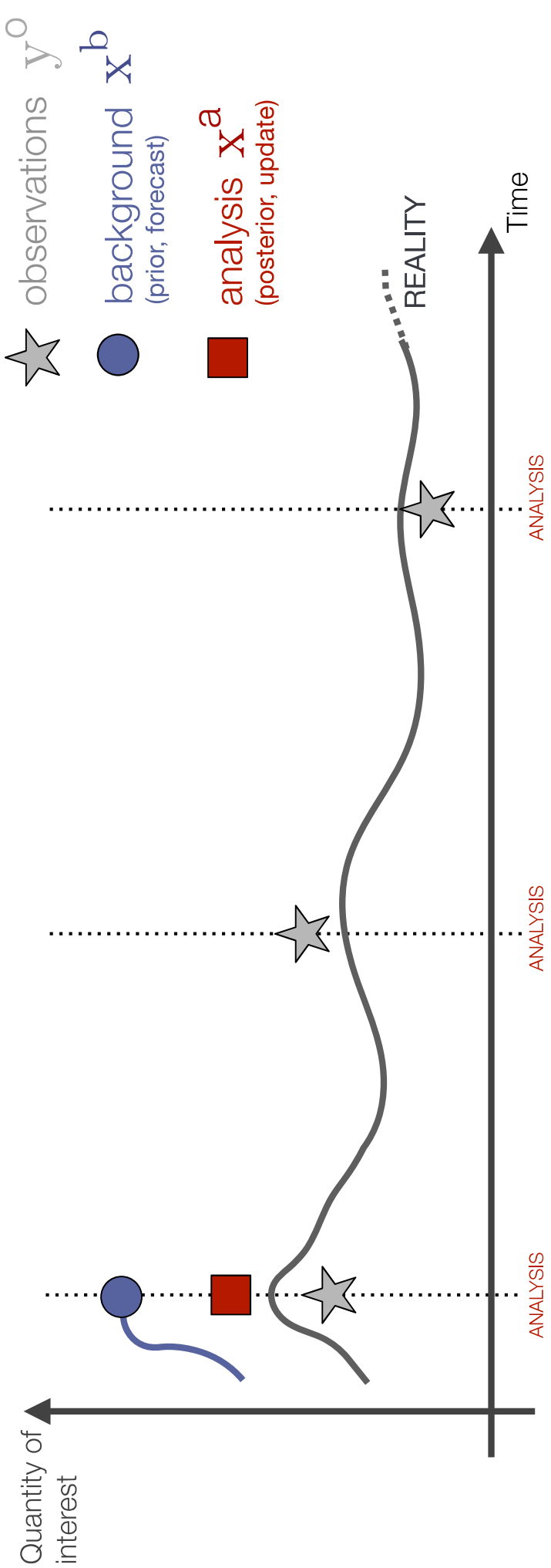
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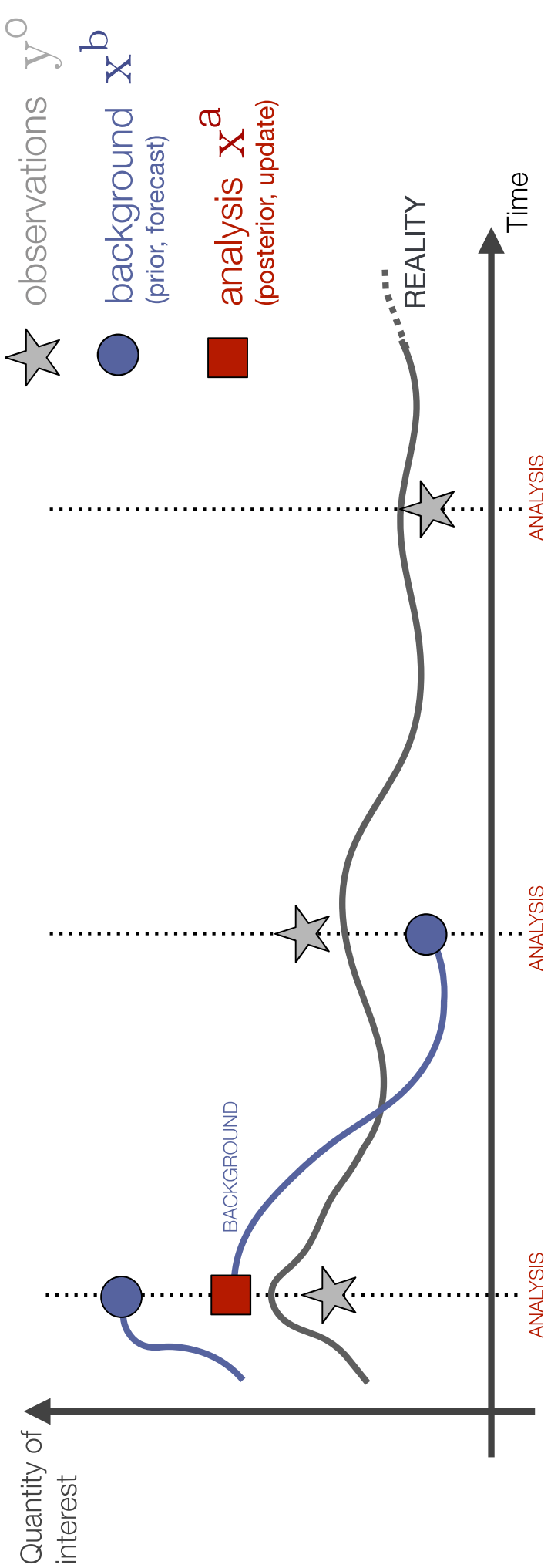
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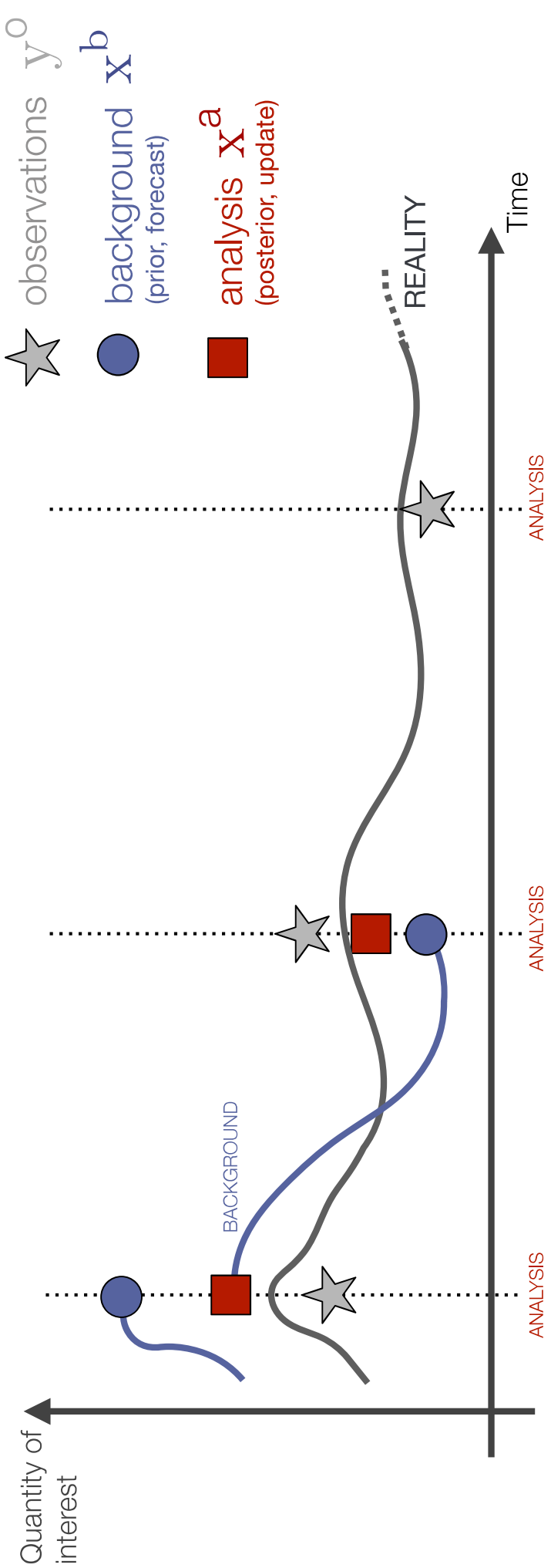
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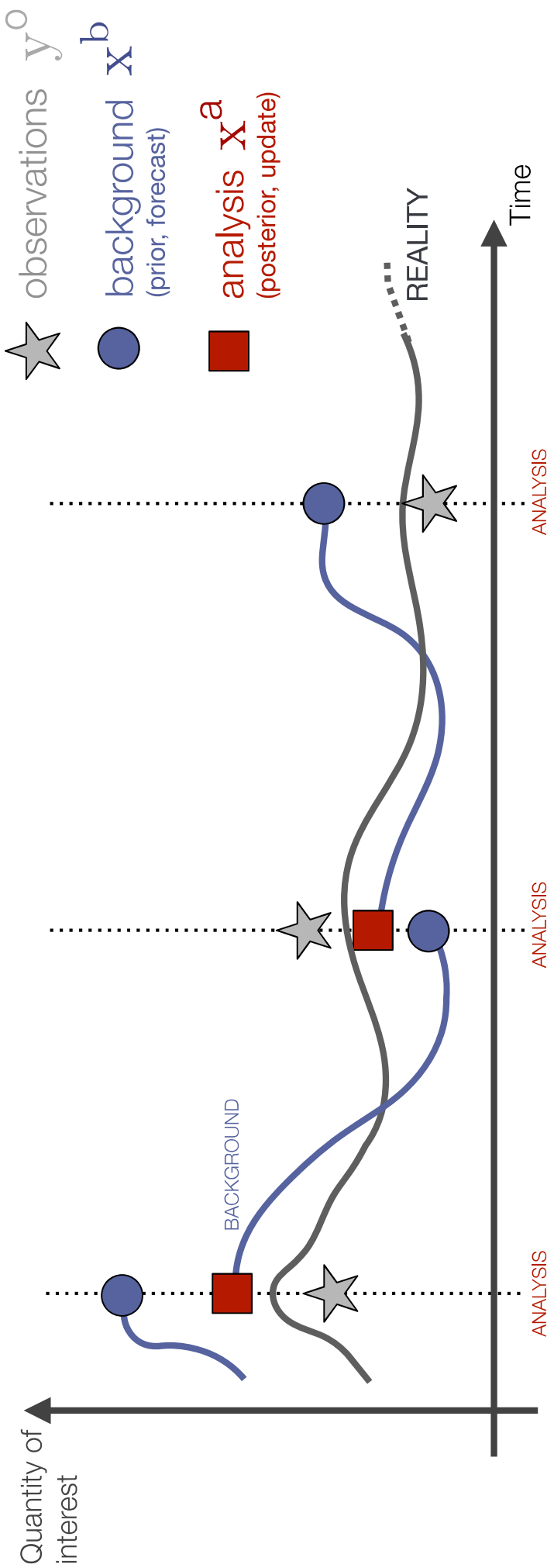
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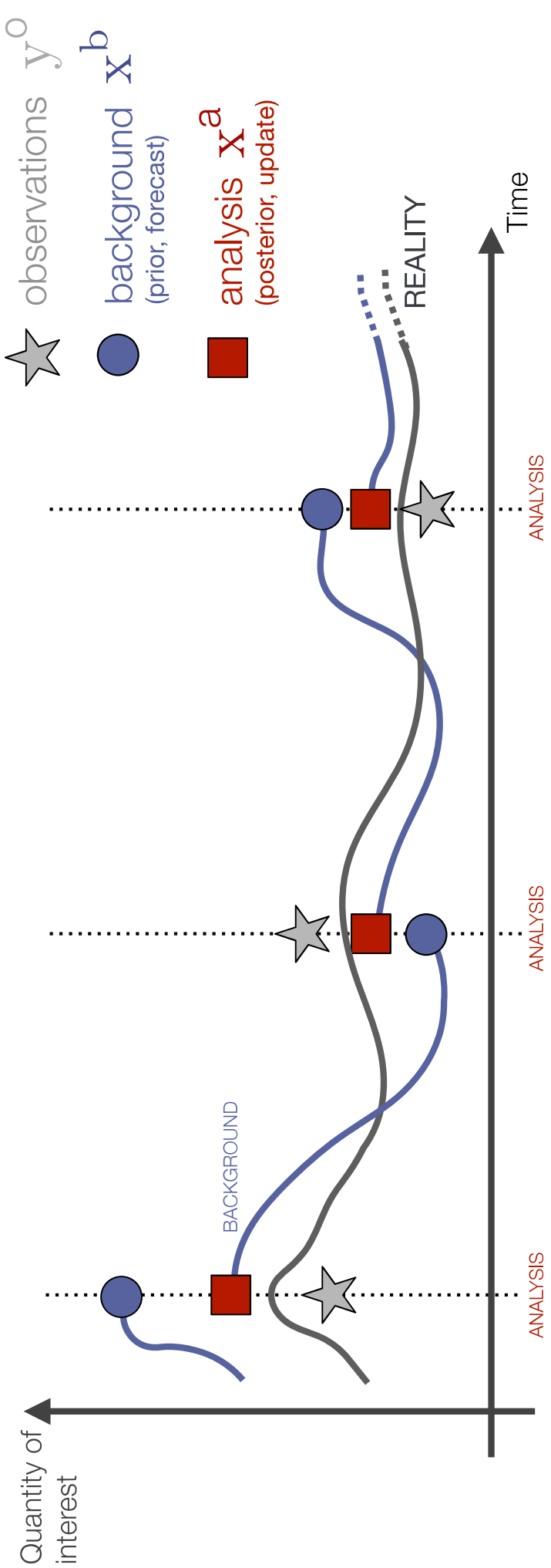
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Sequential data assimilation

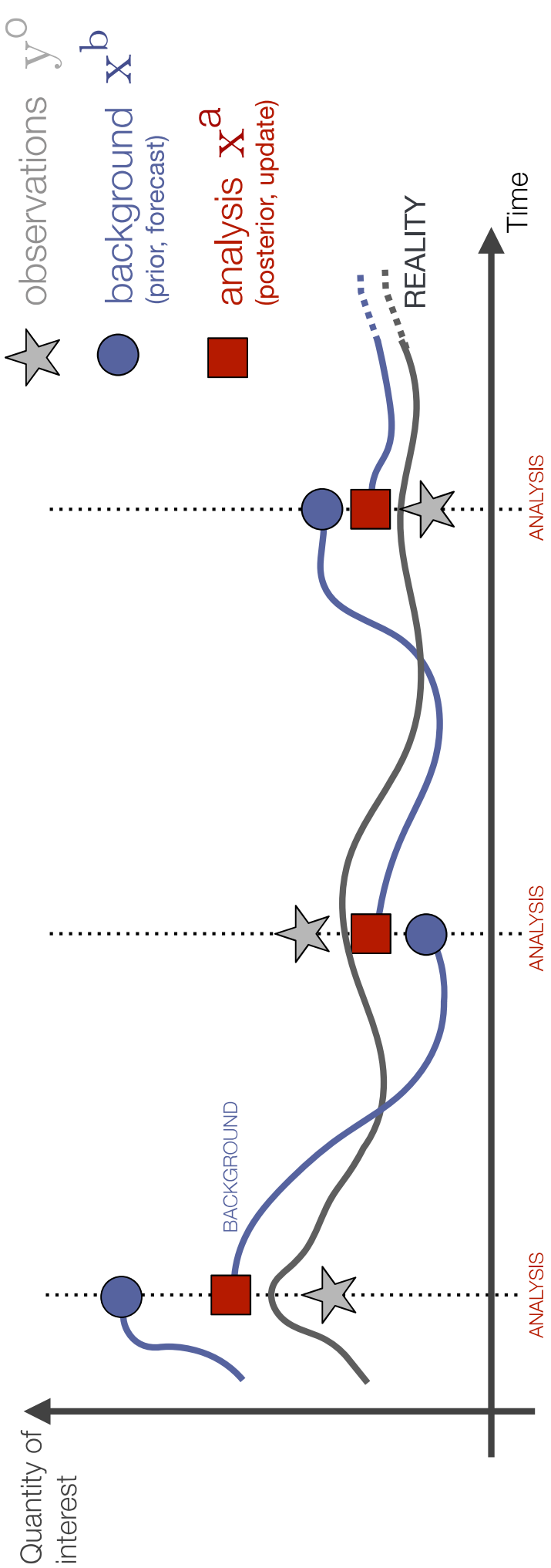


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Sequential data assimilation



Kalman filter

$$\boxed{x^a} = \boxed{x^b} + \mathbf{K} (y^o - \mathcal{G}(x^b)) \rightarrow \mathbf{K} = \boxed{\mathbf{B}\mathbf{G}^T (\mathbf{G}\mathbf{B}\mathbf{G}^T + \mathbf{R})}^{-1}$$

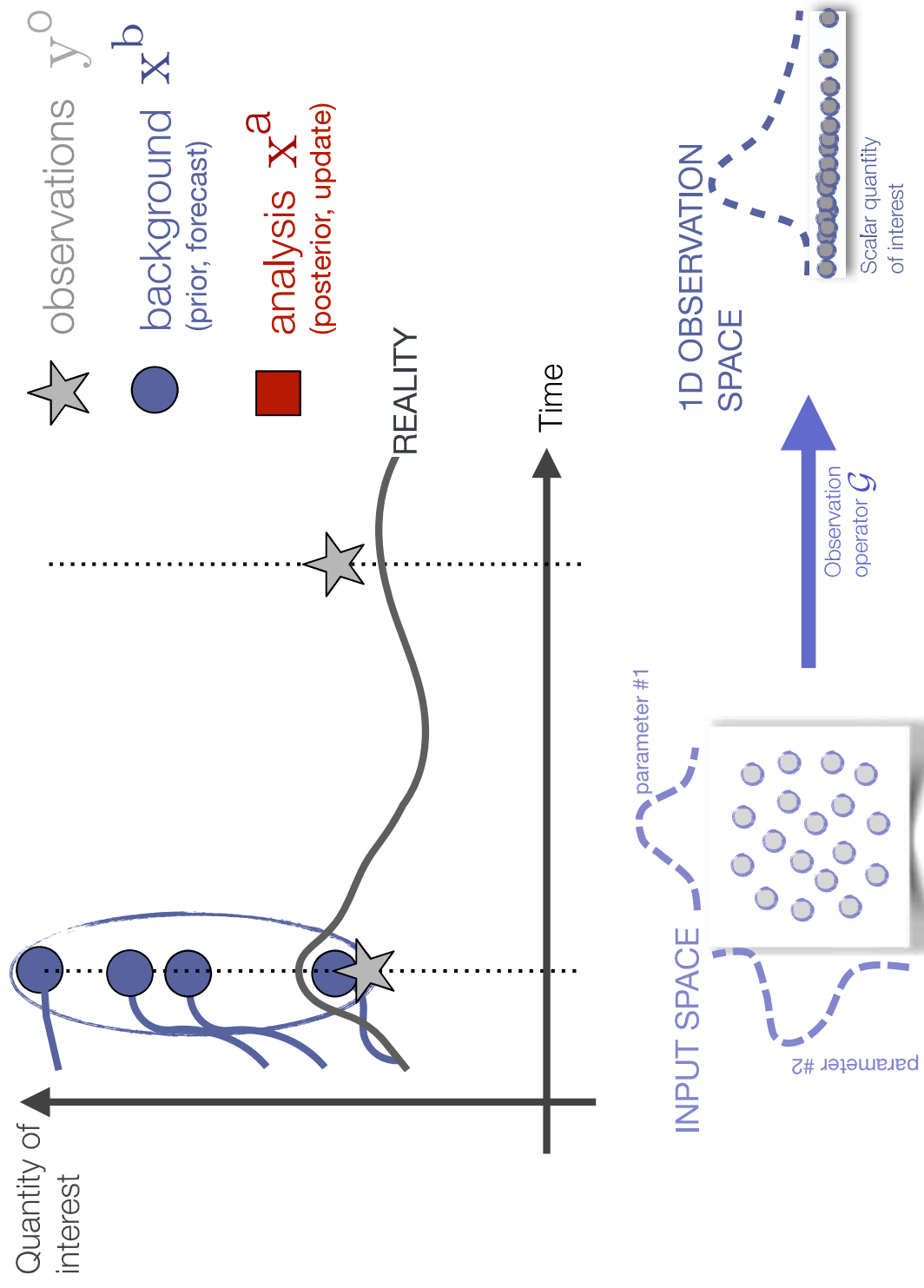
Analysis as a correction of the background

Gain matrix \triangleright Weight \triangleright Error model for model/observation Gaussian error statistics (error covariance model), additive errors

Back to data assimilation



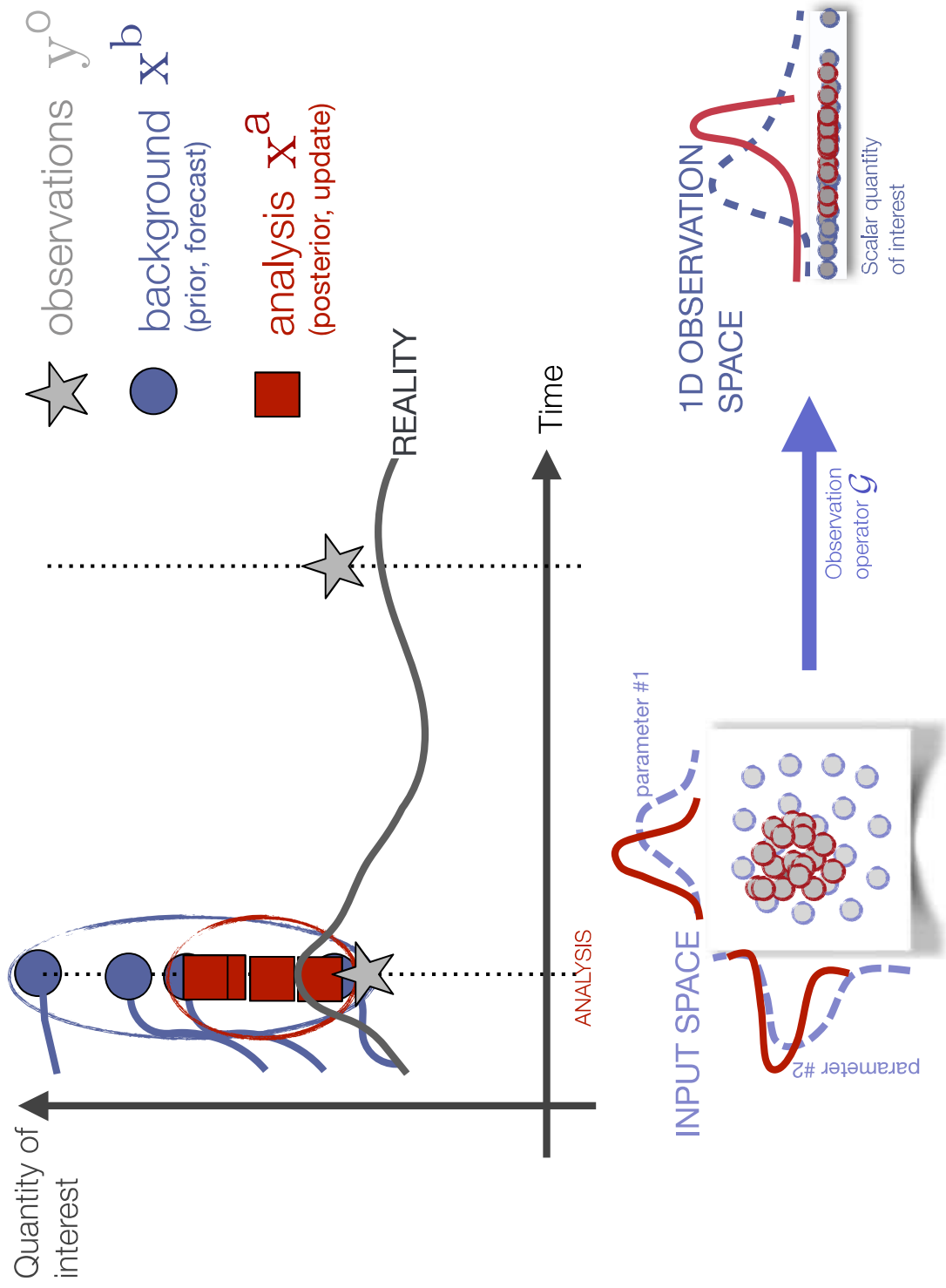
Stochastic viewpoint



Back to data assimilation



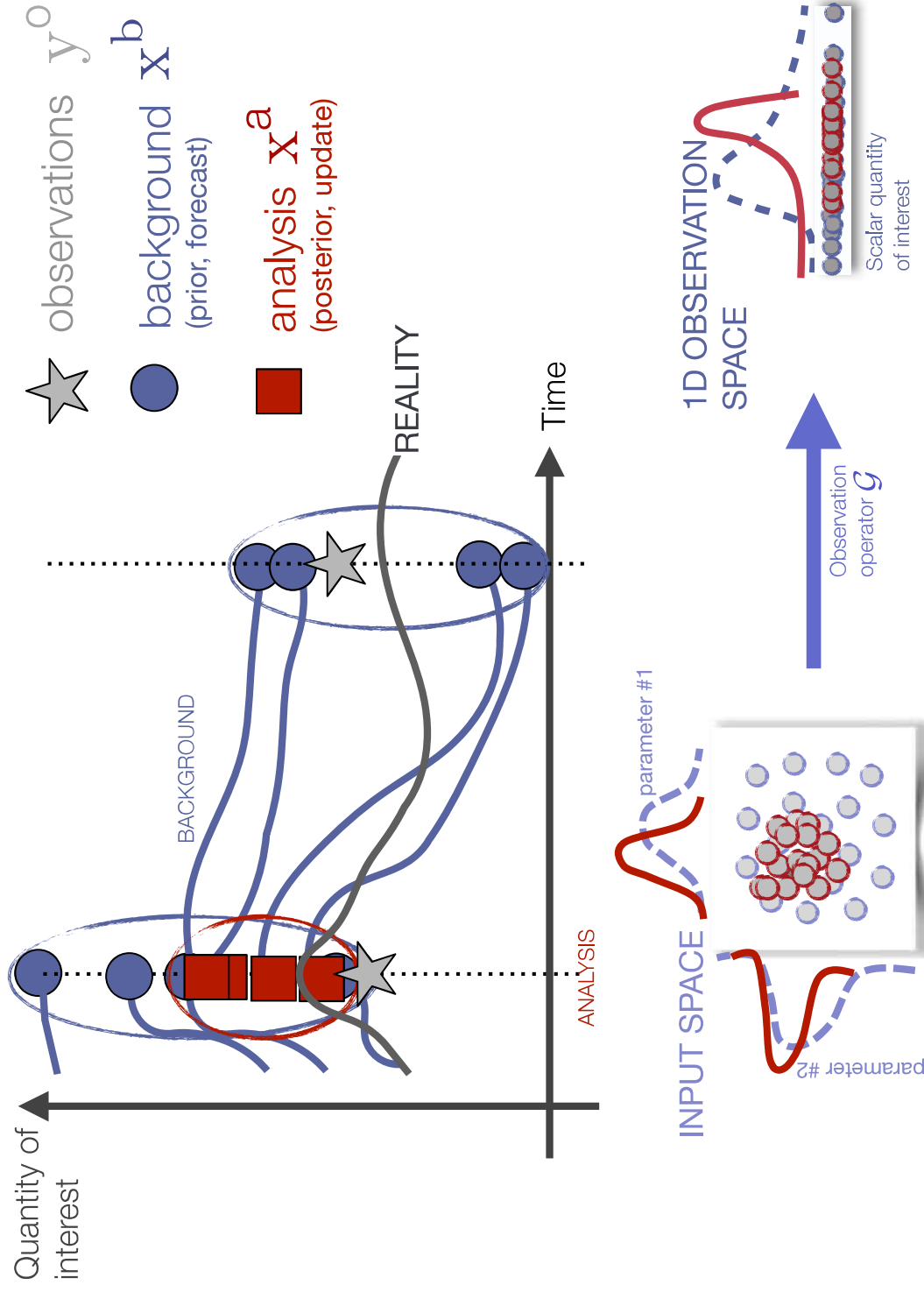
Stochastic viewpoint



Back to data assimilation



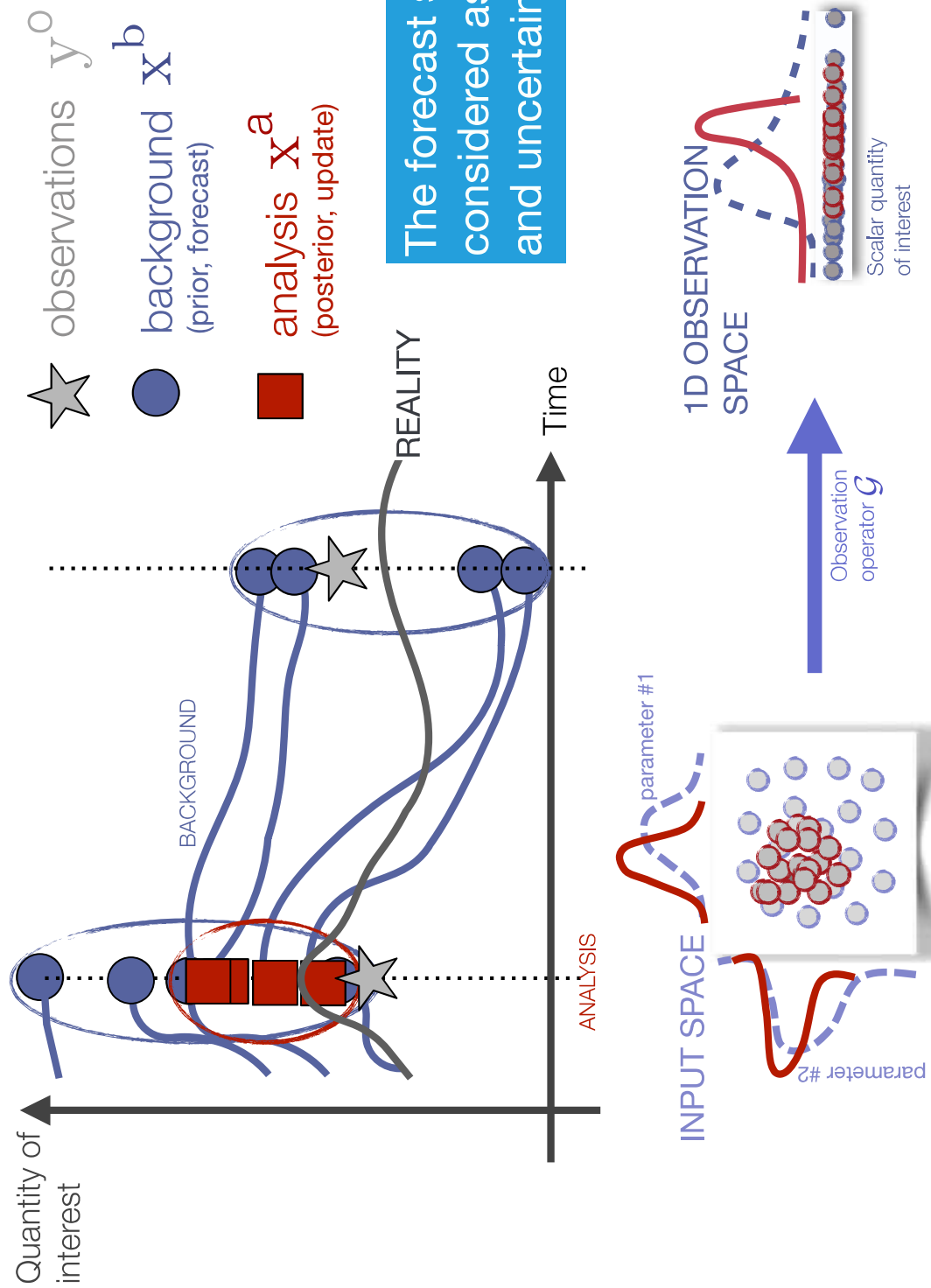
Stochastic viewpoint



Back to data assimilation



Stochastic viewpoint



The forecast step can be considered as a sensitivity analysis and uncertainty quantification step.

- Important questions**
- Choice of perturbed variables
 - Size/variety of the ensemble
 - Sampling strategy
 - Physical model sensitivity

Talk's introduction

Scientific issues

Design of a data assimilation approach for wildfire behavior forecasting

“algorithm”

“estimation targets”

“prior information”

“front observations”

Talk's introduction

Scientific issues

Design of a data assimilation approach for wildfire behavior forecasting

- (1) Design of front data assimilation method “algorithm”
- (2) Choice of control variables “estimation targets”
- (3) Improvement of physical model predictions “prior information”
- (4) Extraction of information from infrared observations “front observations”

Talk's introduction

Scientific issues

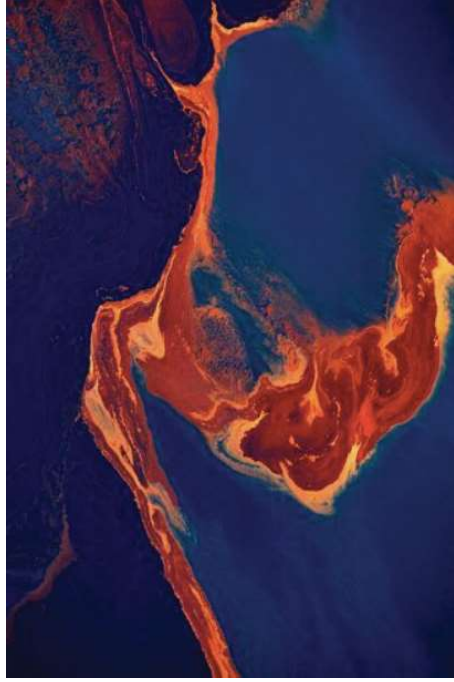
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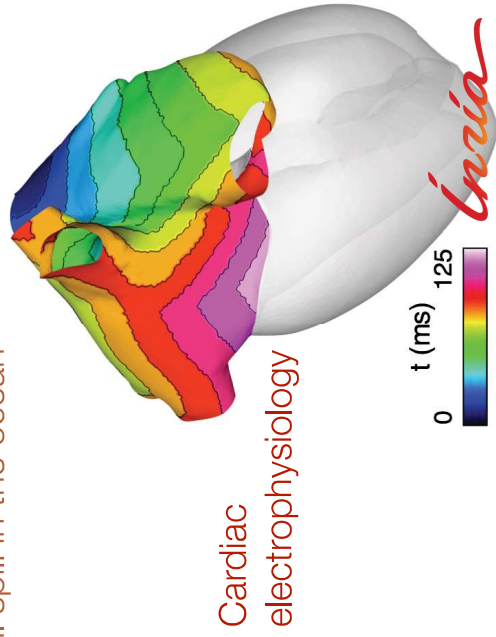
1 Algorithm

Pattern tracking

It is easy to perceive coherent structures by eye, but a full precise mathematical description is still a challenge.



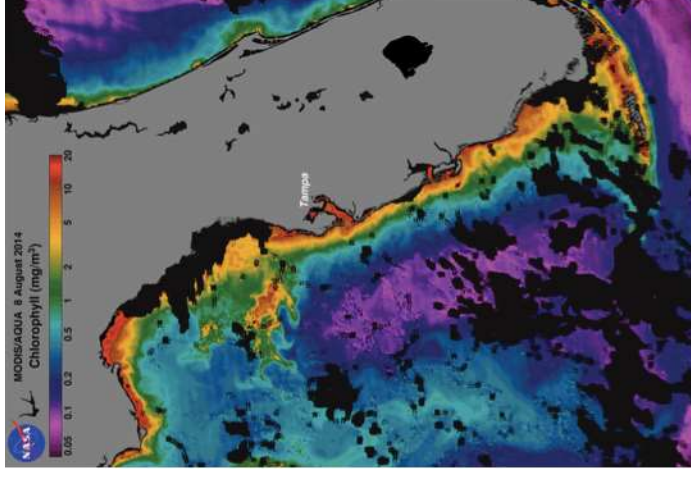
Oil spill in the ocean



Cardiac electrophysiology



Precipitation pattern in meteorology



Chlorophyll concentration in the ocean with cloud occlusion



Flaming combustion

Data assimilation limitations

Limitation of point-wise local metrics

- Several metrics are usually required to satisfyingly compare fields
- Double penalty effect
 - A misplaced structure is predicted where it should not be and is not predicted where it should be
- Small spatial and temporal shift of the structure position
- Failure of standard data assimilation methods when position errors are large, for instance when observations are not frequent
 - Standard treatment of amplitude errors (Euclidean metrics)
 - Generation of artificial patterns

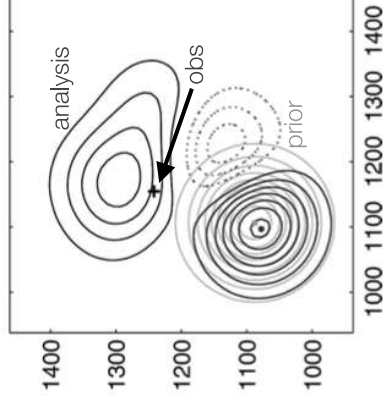
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Example of hurricane tracking with ensemble Kalman filter (EnKF)



Chen and Snyder (2007), Monthly
Weather Review
Beezley and Mandel (2008), Tellus

1 Algorithm

Image segmentation



Rochoux et al. (2018),
ESAIM: Proceedings
and Surveys

What can we learn from image segmentation theory?

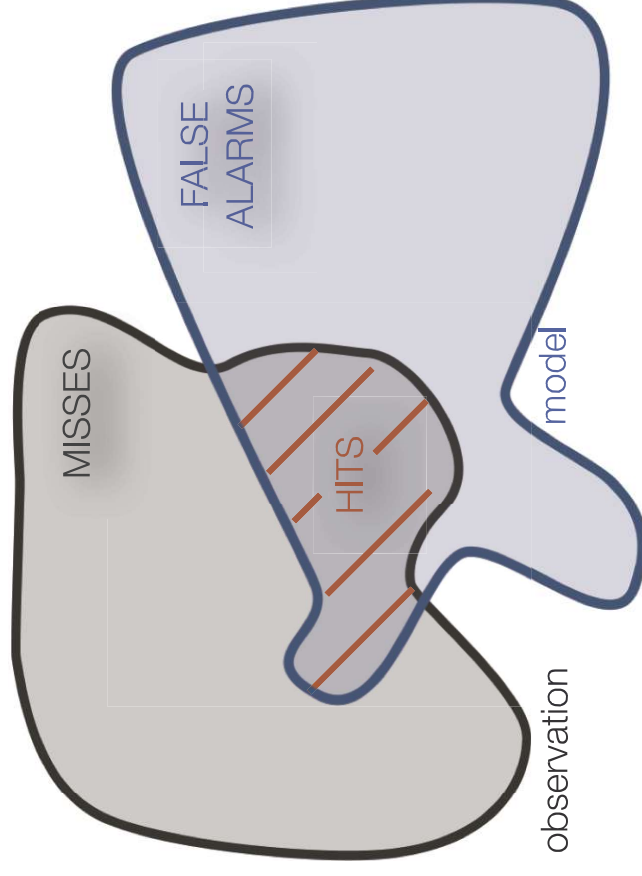
- Identification and comparison of main field features (which criteria?)
- Scale separation (ex: wavelet transform)
- Fuzzy method (ex: prior field smoothing)
- Field deformation or field displacement (ex: Wasserstein distance, Chan-Vese data-fitting functional)



Nelson Feyeux (2016), Transport optimal
pour l'assimilation de données d'images.
Thèse de doctorat, Communauté Université
Grenoble Alpes



Collin et al. (2015), Journal of
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1 Algorithm

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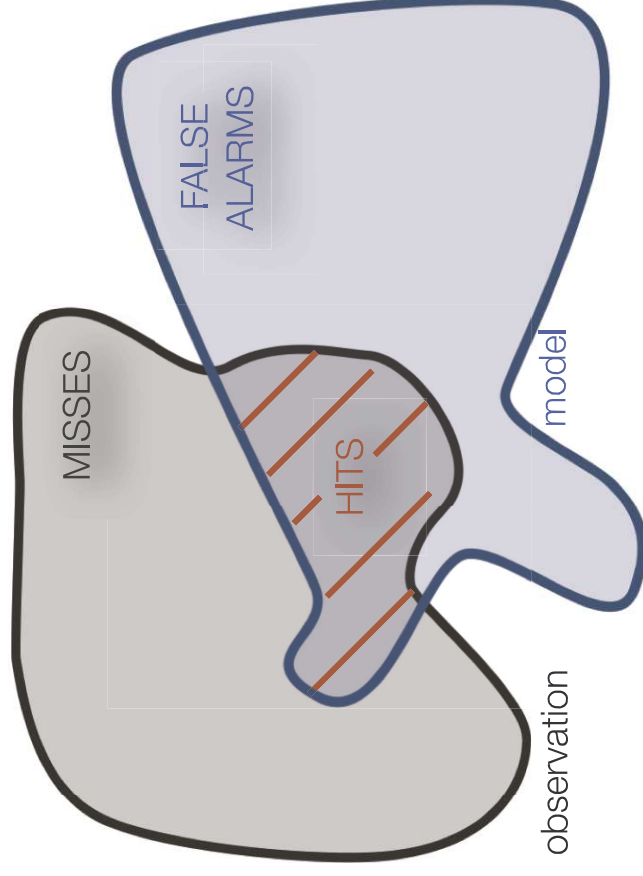


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Typical image
segmentation problem



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Analogy with data assimilation

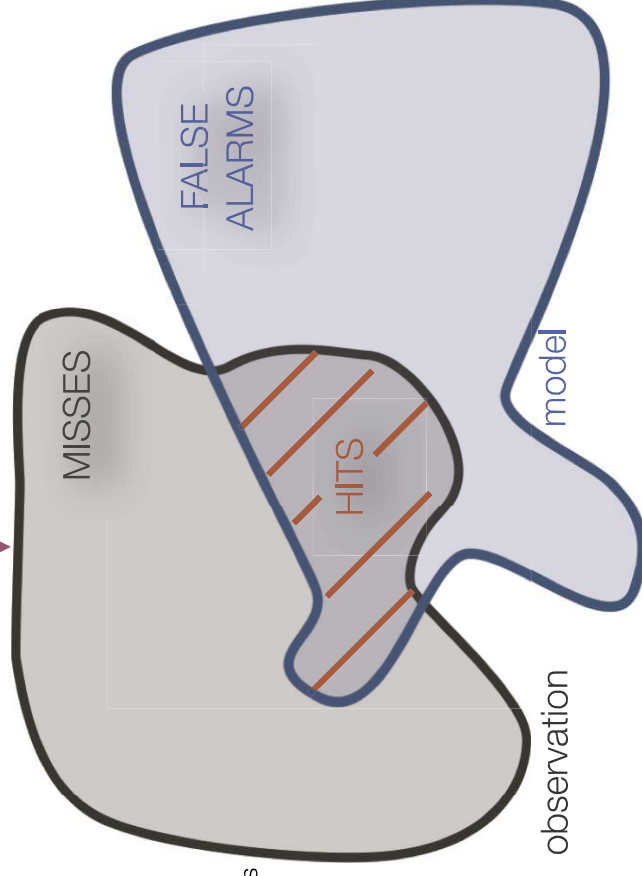
The "airplane object" is the
observation.

The green square is the prior
information.

The objective of image
segmentation is to find the
contour of the "airplane object".

Objectives

- maximization of hits
- minimization of misses



$$\mathcal{J}(\phi, y^o) = \int_{\Omega} H_v(\phi) [y^o - C_1(y^o, \phi)]^2 + (1 - H_v(\phi)) [y^o - C_0(y^o, \phi)]^2 dx$$

- Functional dependency
- Level-set function (prior)
- Observation

1 Algorithm

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Analogy with data assimilation

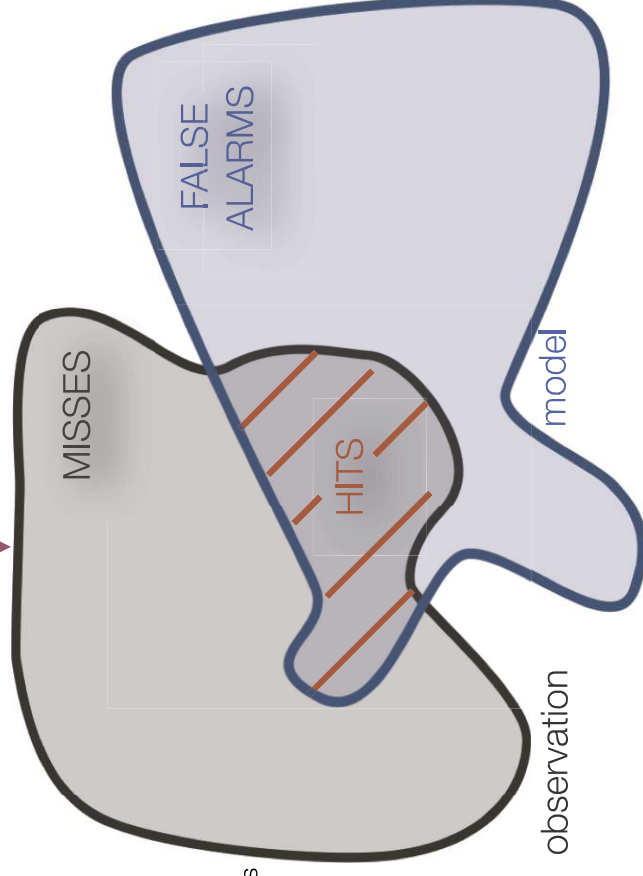
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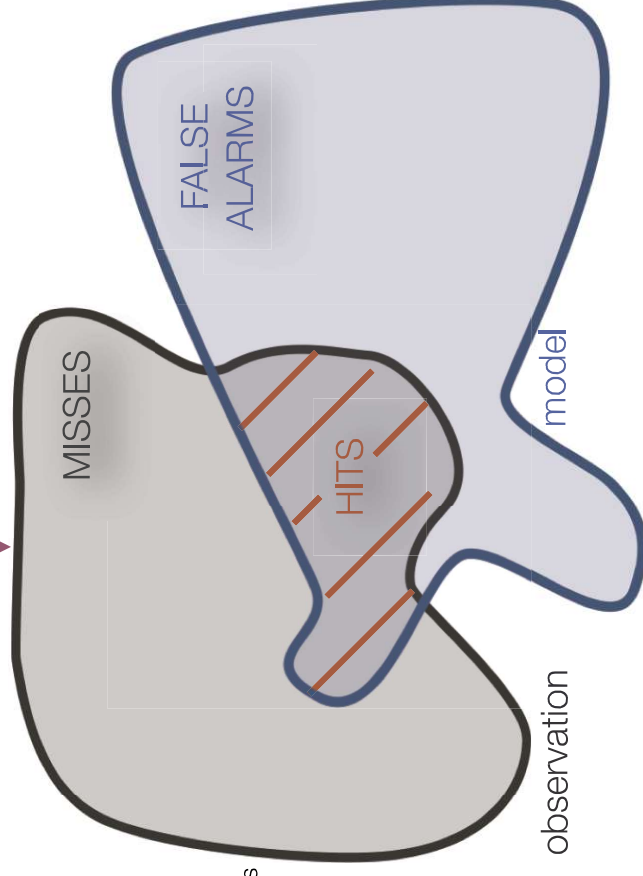
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Analogy with data assimilation

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Functional dependency

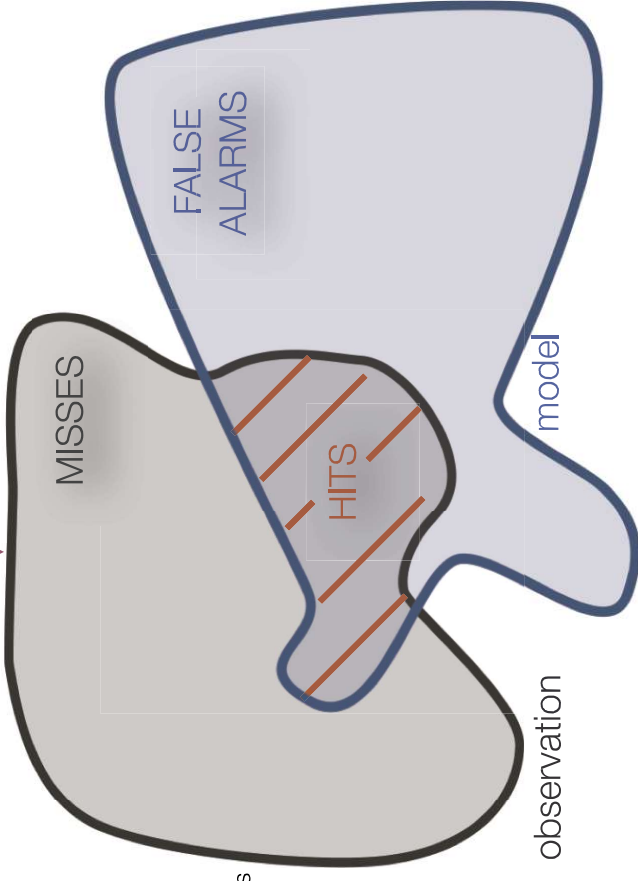
- Level-set function (prior)
- Observation



Nelson Feyeux (2016), Transport optimal pour l'assimilation de données d'images. Thèse de doctorat, Communauté Université Grenoble Alpes



Collin et al. (2015), Journal of Computational Physics
Arbogast et al. (2016), Quarterly Journal of the Royal Meteorological Society



1 Algorithm

Image segmentation



Rochoux et al. (2018),
ESAIM: Proceedings
and Surveys

What can we learn from image segmentation theory?

- Identification and comparison of main field features (which criteria?)
- Scale separation (ex: wavelet transform)
- Fuzzy method (ex: prior field smoothing)
- Field deformation or field displacement (ex: Wasserstein distance, Chan-Vese data-fitting functional)



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Grenoble Alpes



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Arbogast et al. (2016), Quarterly Journal
of the Royal Meteorological Society



Chan and Vese (2001),
IEEE Transactions on
Image Processing

Typical image
segmentation problem



Analogy with data assimilation

The "airplane object" is the
observation.

The green square is the prior
information.

The objective of image
segmentation is to find the
contour of the "airplane object".

Objectives

- maximization of hits
- minimization of misses

$$\mathcal{J}(\phi, y^o) = \int_{\Omega} \underbrace{H_V(\phi)}_{\text{measuring HITS}} [y^o - C_1(y^o, \phi)]^2 + \underbrace{(1 - H_V(\phi))}_{\text{measuring MISSES}} [y^o - C_0(y^o, \phi)]^2 dx$$

Functional dependency

- Level-set function (prior)
- Observation

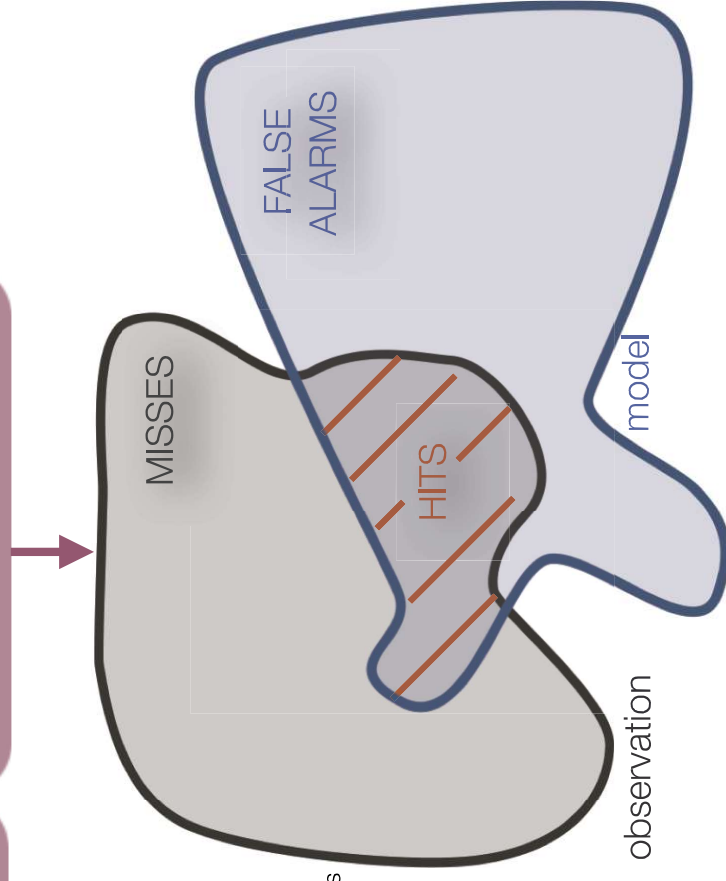
Inside the simulated burnt area

Outside the simulated burnt area

measuring HITS (mean of obs. in simulated burnt area)

measuring MISSES (mean of obs. outside of simulated burnt area)

Minimizing the functional acts on the contour of the simulated area to match the shape of the observed front.



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2 Control variables

State-parameter estimation



Rochoux et al. (2014, 2015), Natural Hazards and Earth System Sciences

State of the fire spread model

- Way to address all sources of uncertainty beyond parametric uncertainties (e.g. model error)
- Better accounting for anisotropy in the fire front propagation

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Rochoux et al. (2014, 2015), Natural Hazards and Earth System Sciences

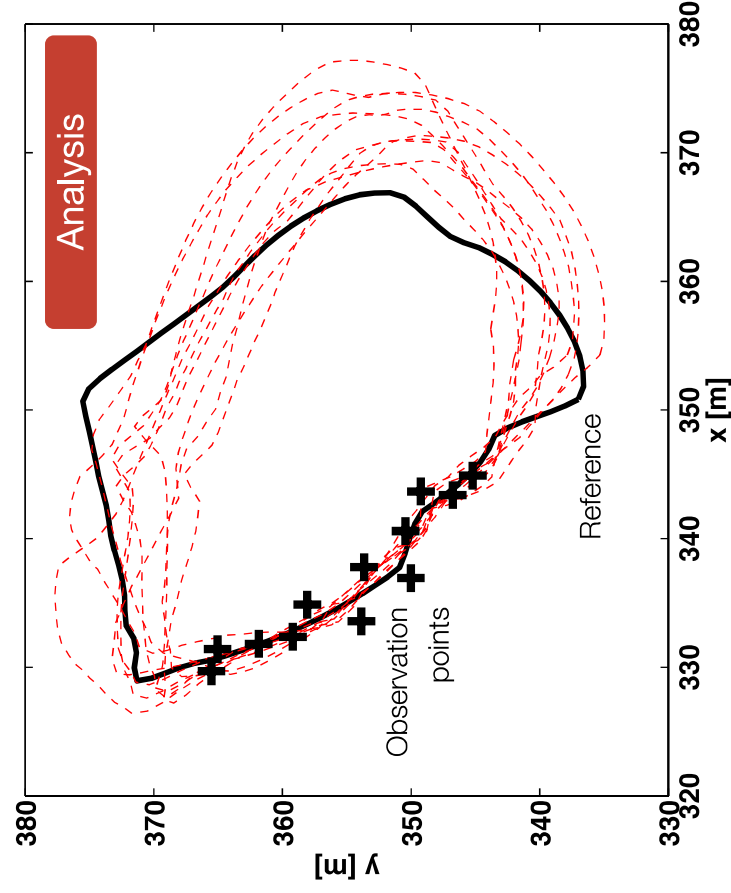
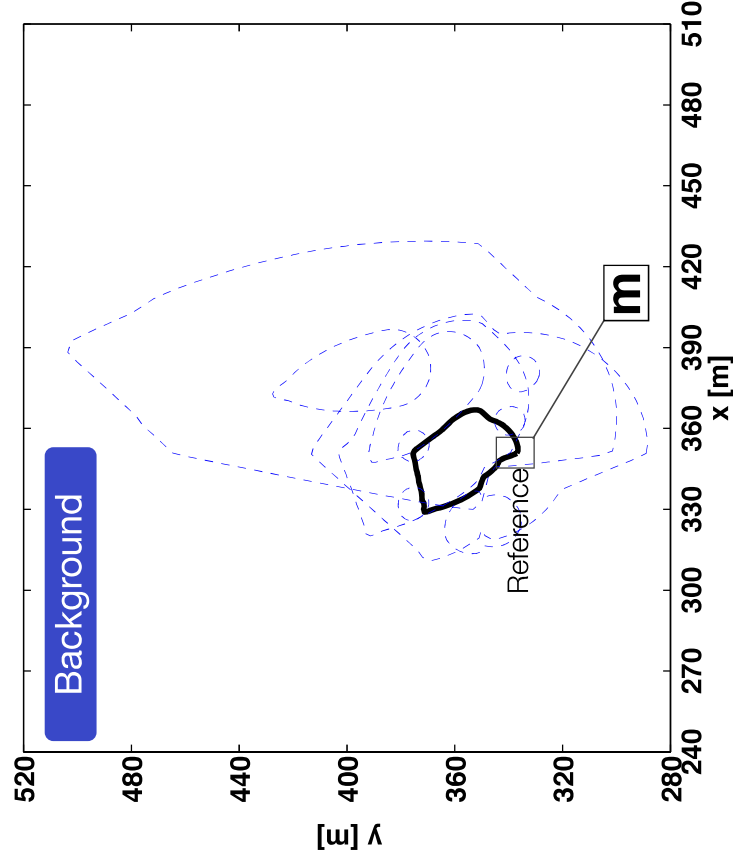
State of the fire spread model

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Synthetic experiments (OSSE)

Synthetic experiments (OSSE)

Assumed sources of uncertainty
Fire initial condition, fuel properties (layer thickness, aspect ratio, moisture content), wind magnitude and direction



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State-parameter estimation



Rochoux et al. (2014, 2015), Natural Hazards and Earth System Sciences

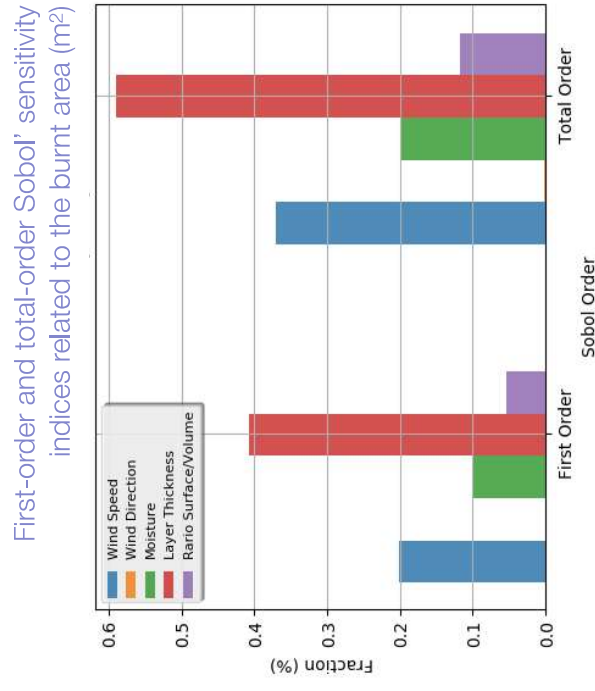
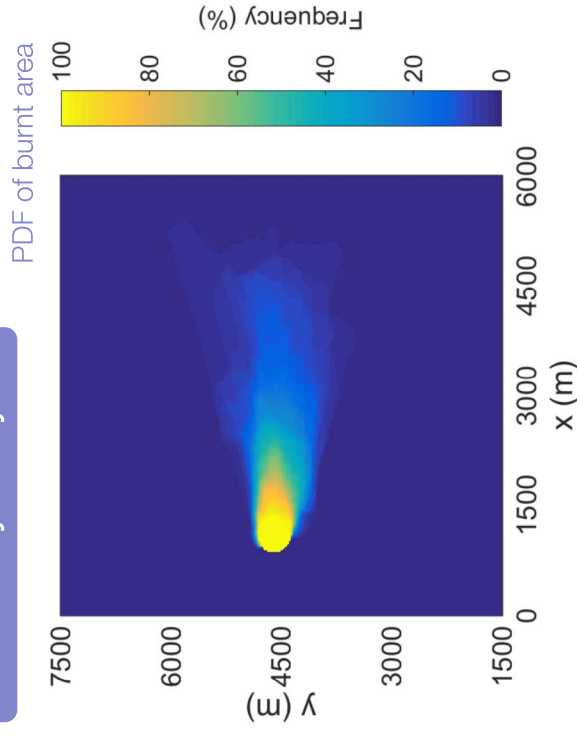
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Parameters of the rate of spread model

- Reduced model bias
- Improved forecast performance

Sensitivity analysis



State-parameter estimation

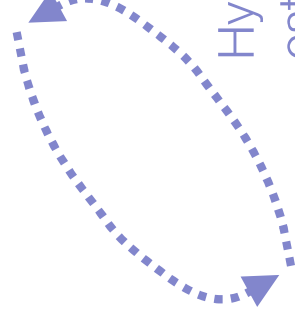


State of the fire spread model

- Way to address all sources of uncertainty beyond parametric uncertainties (e.g. model error)
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- Algorithm: Luenberger observer

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- Algorithm: Ensemble Kalman Filter (ETKF version)
- Note: case-dependent parameter estimation (no generic learning)



Hybrid state-parameter estimation

1/ State estimation

Correcting the observer state c through the control feedback in the advection equation

2/ Parameter estimation

Using the observer state to derive updated control parameters using ensemble Kalman filter (ETKF)

State-parameter estimation

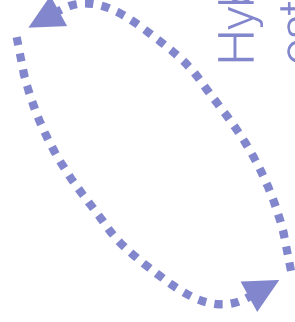


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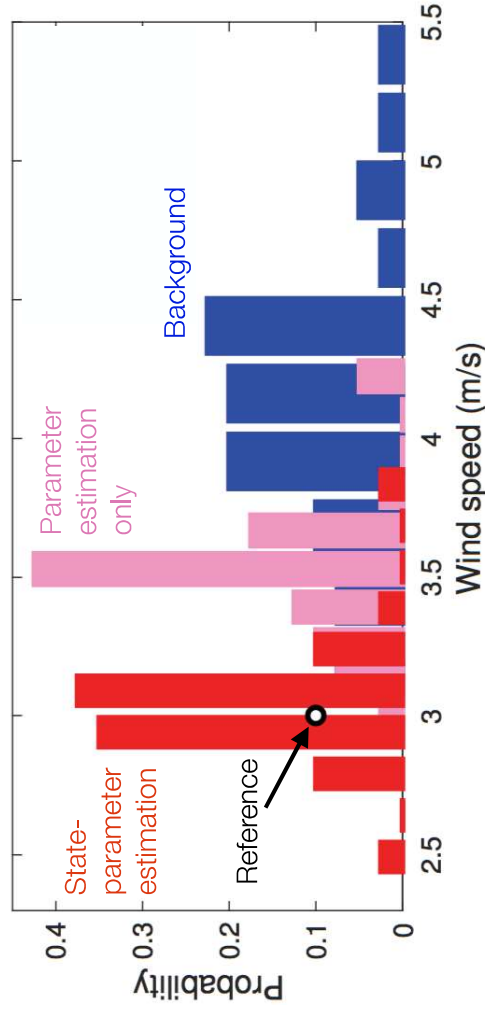
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Probability distribution



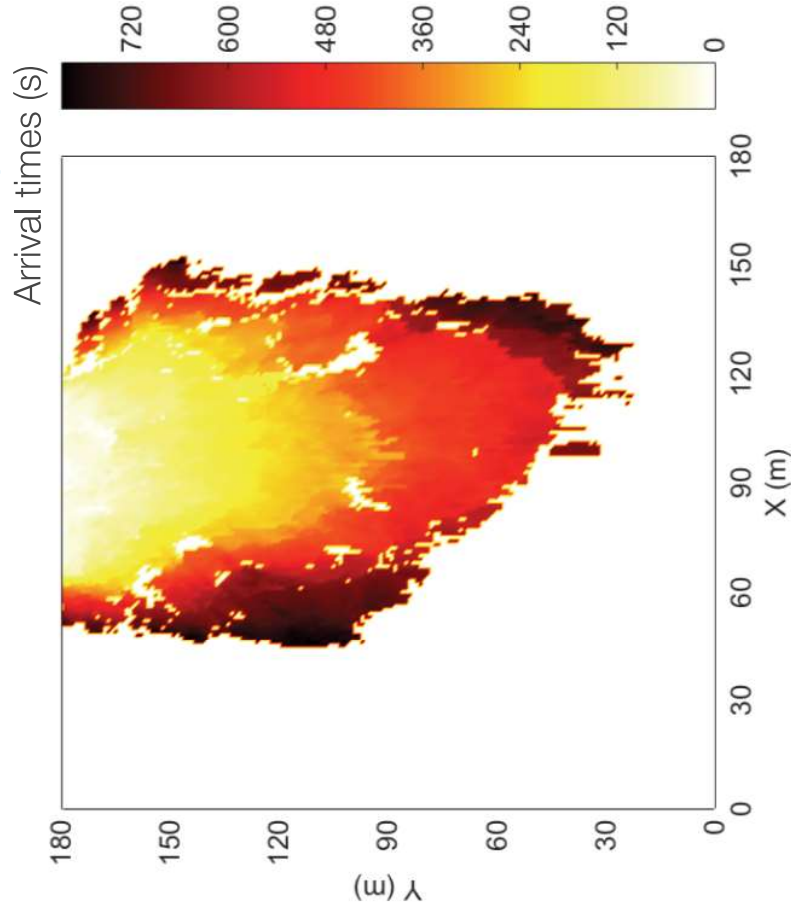
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State-parameter estimation



Zhang et al. (2017, 2019), Fire Safety Journal

RxCADRE controlled burn experiments



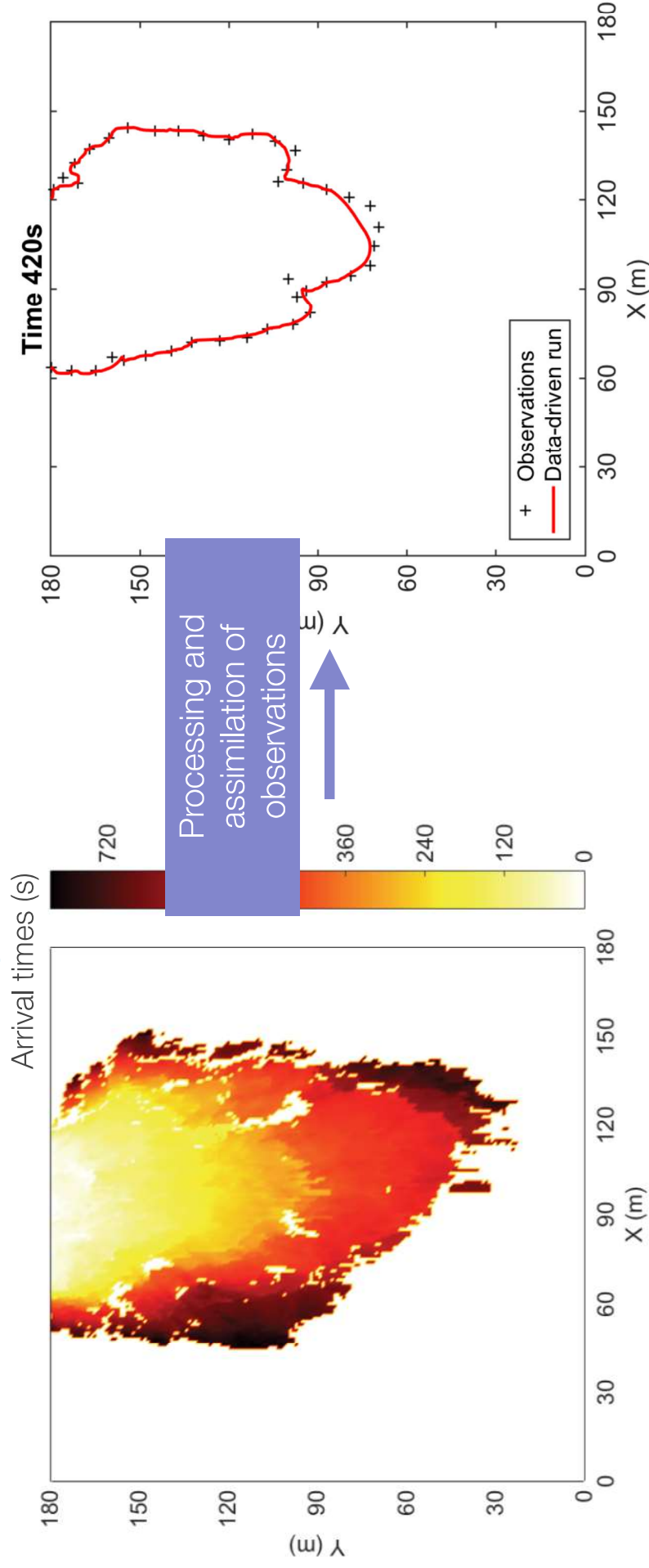
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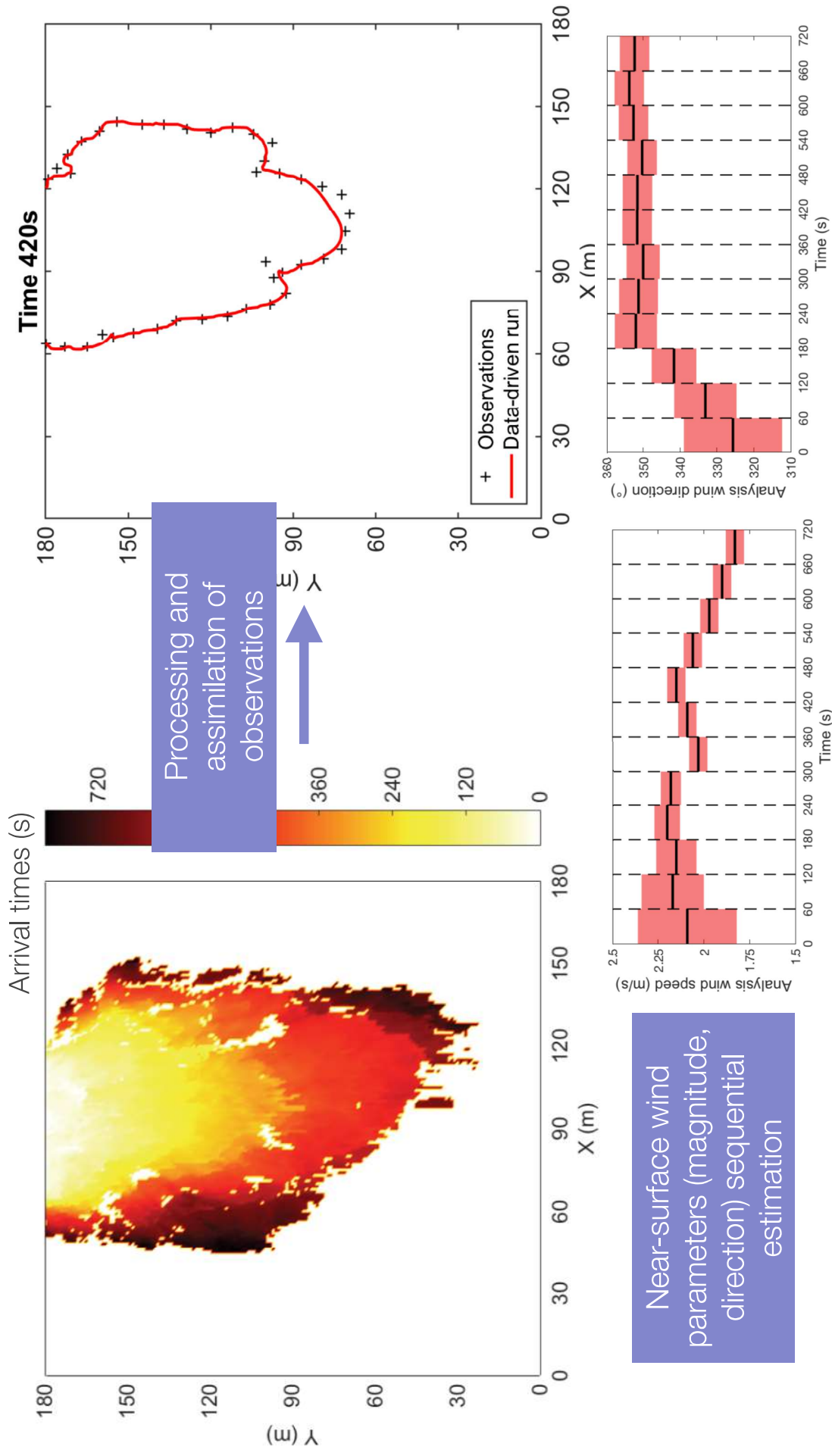
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3Prior information

Fire-atmosphere simulation



Costes et al. (2018),
International Conf on
Forest Fire Research

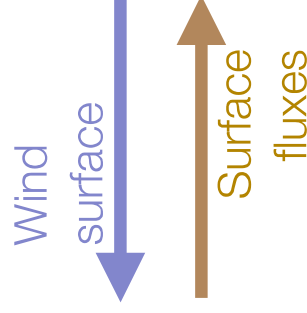


Filippi et al. (2018),
Atmosphere

Fireline position

FOREFIRE (SPE/Univ. de Corse)

- Fire spread model
- Rate-of-spread parameterization
- Front-tracking solver (Lagrangian)



Atmospheric dynamics

MesoNH (CNRM-Laboratoire d'Aérodynamique)

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Geophysical data

(IGN BD TOPO/BD ALTI, ONF
dead fuel classification)

SURFEX/ISBA model

(Interaction Soil-Biosphere-
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- Sensible/latent heat fluxes
- Parameters: fixed nominal values, burning duration

Wind interpolation

from the first grid level along
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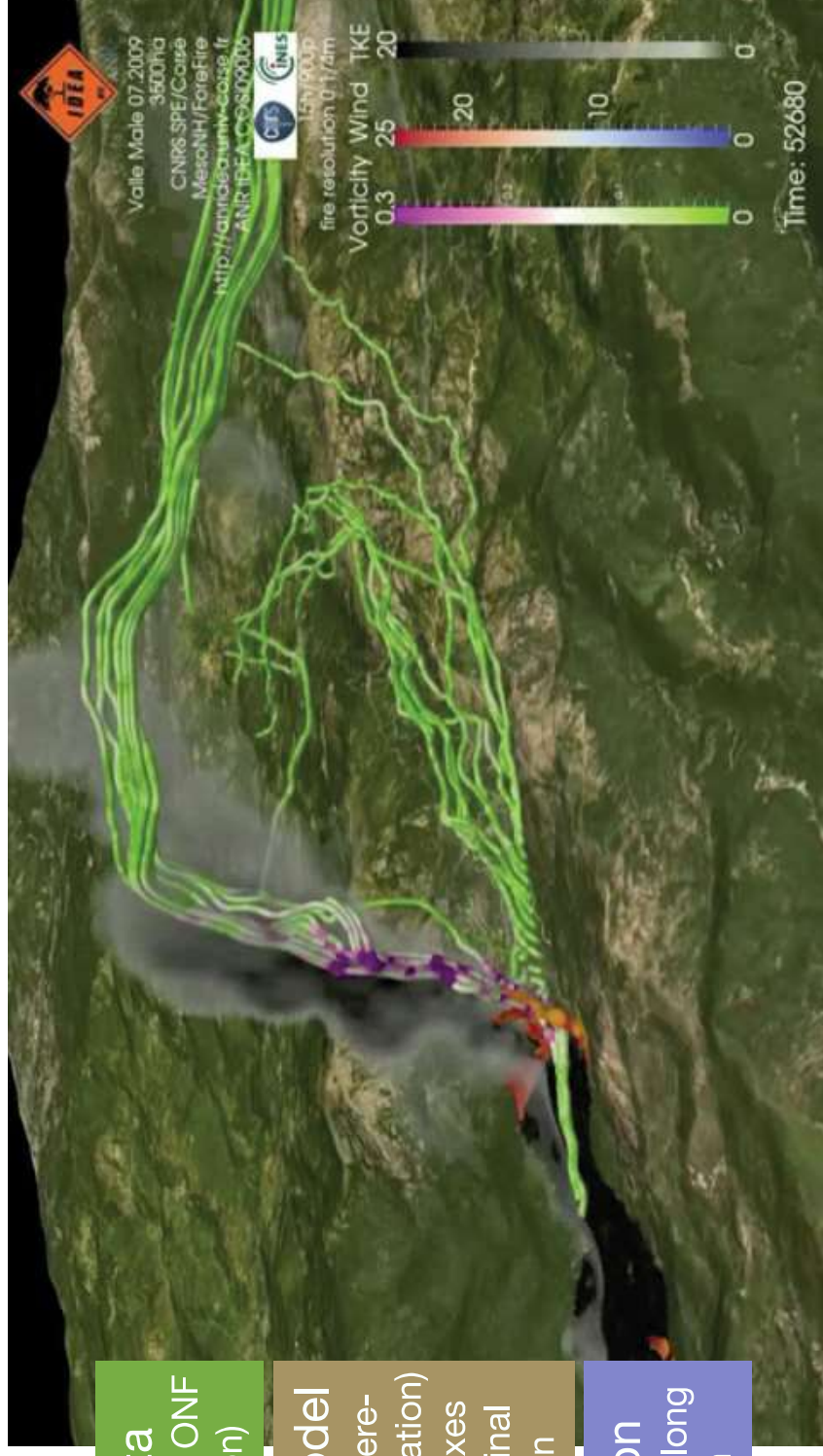
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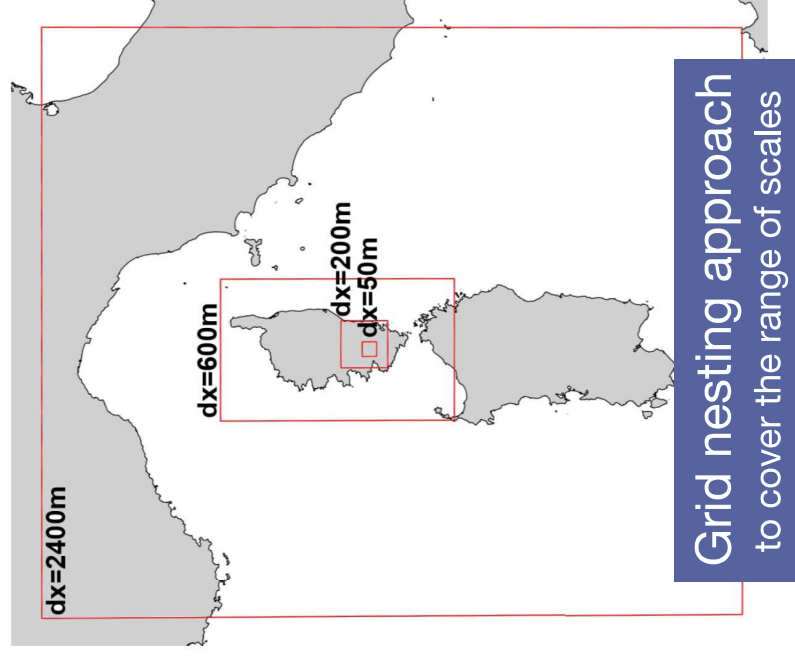
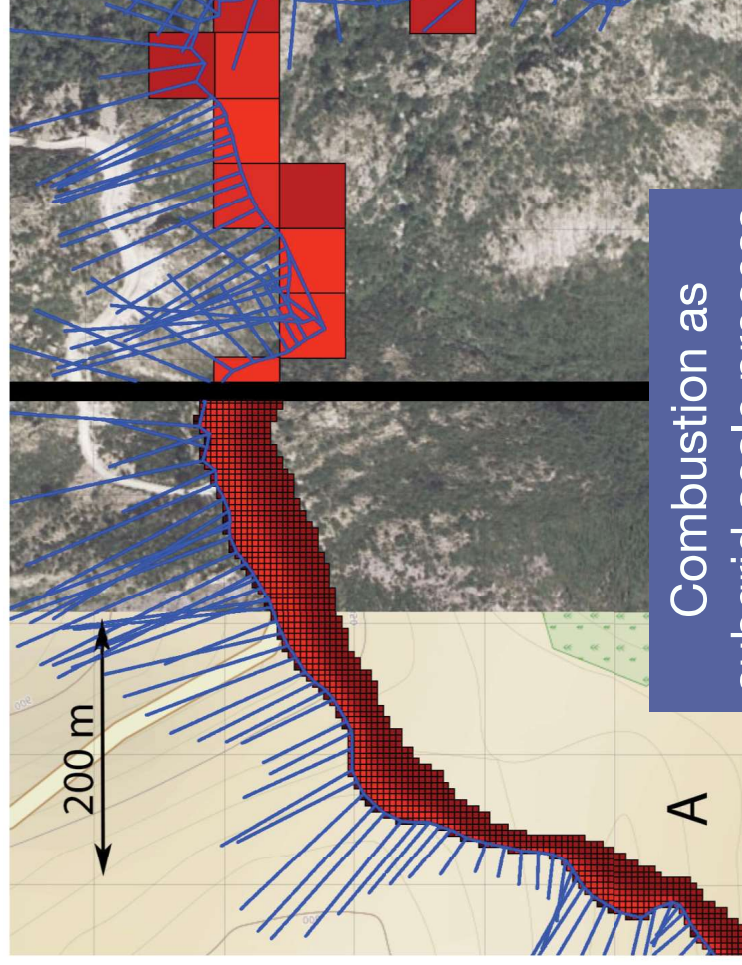
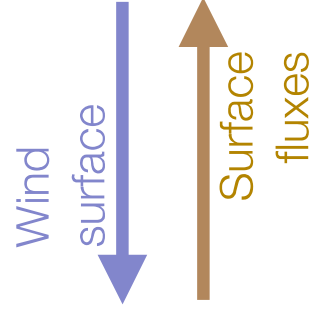
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4Observations

Infrared images



Paugam et al. (2013), IEEE transactions on geoscience and remote sensing



Paugam et al. (2019), EGU General Meeting

Image segmentation

1- Automated orthorectification

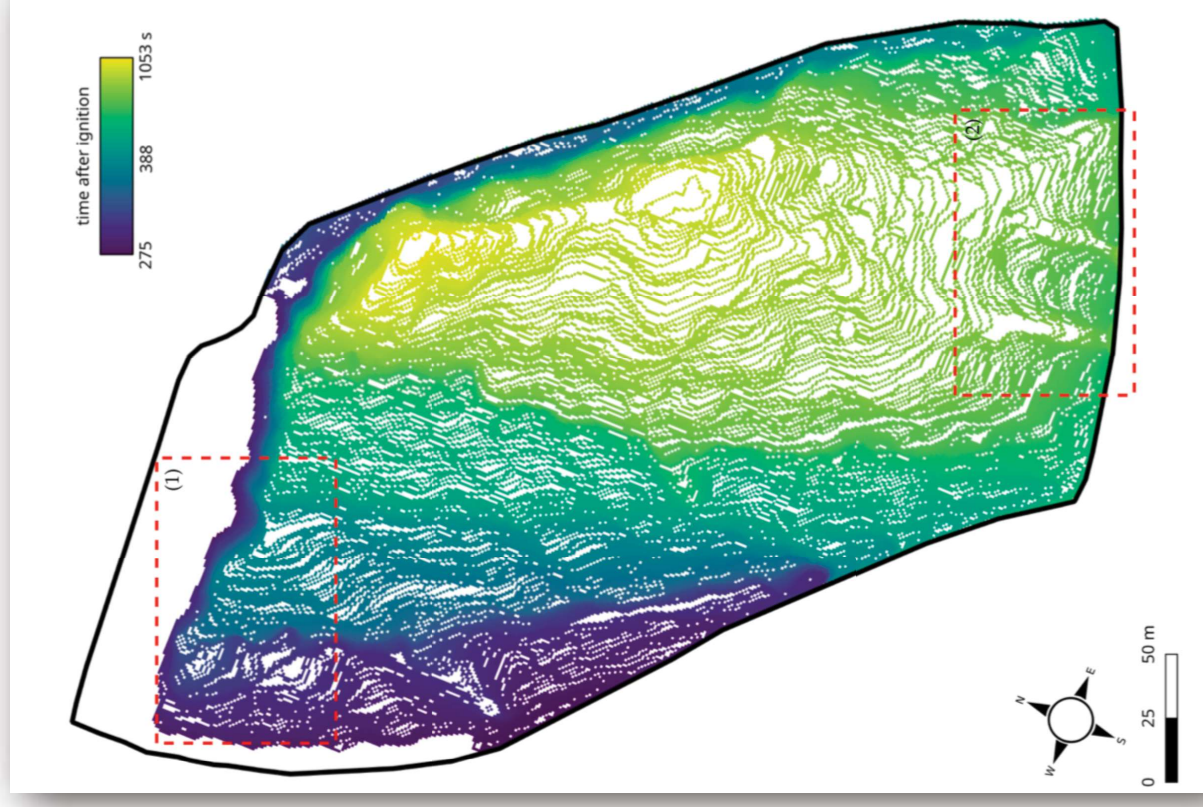
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- Objective: Extracting the fire front location out of the orthorectified radiance field
- Method: Training of a Unet neural network to annotate infrared images

- Starting from a small number of manually annotated images (11)
- Moving to a full annotated data set using data augmentation

3- Fire behavior metrics

Rate of spread, fire radiative power, fireline intensity, flame depth



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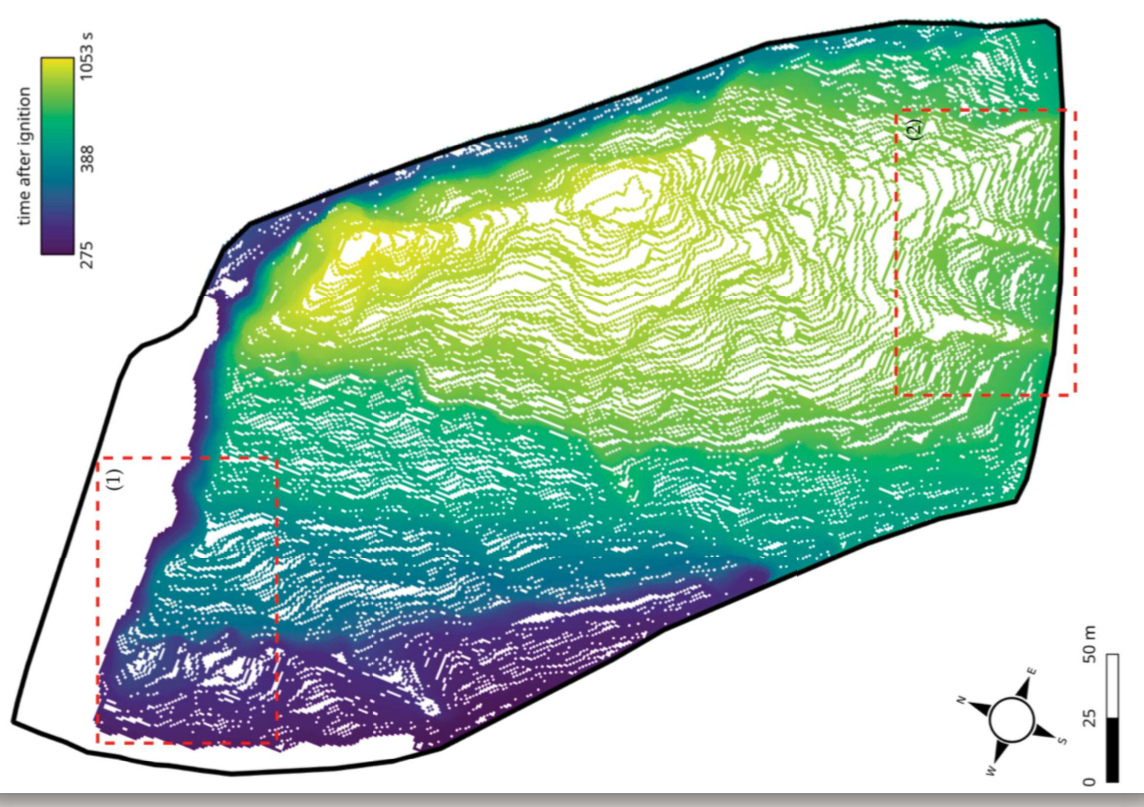
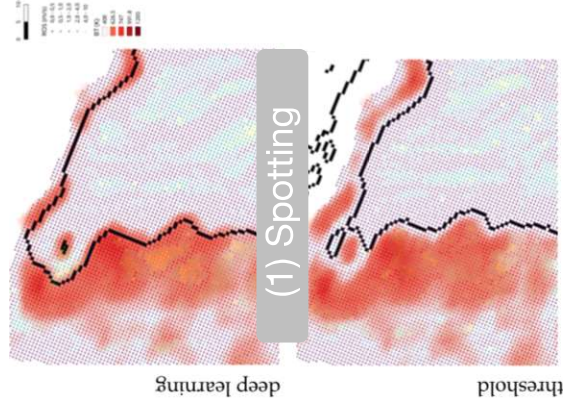
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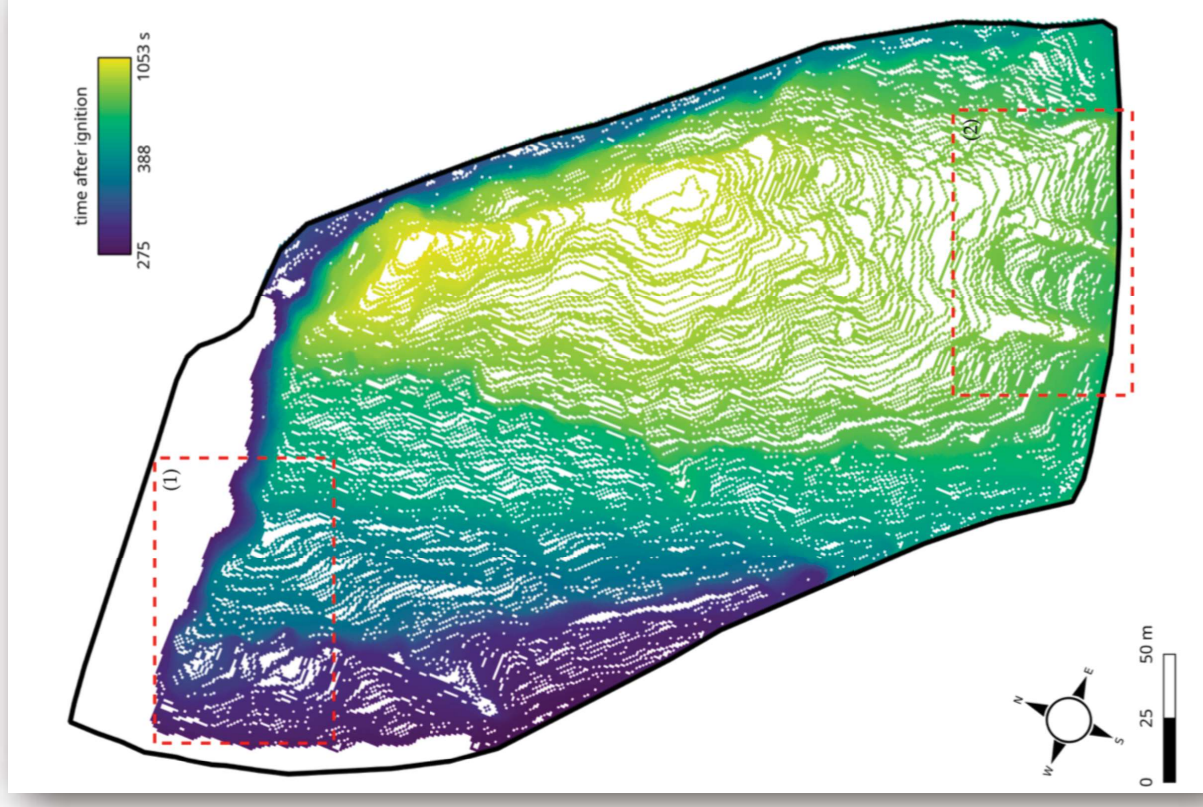
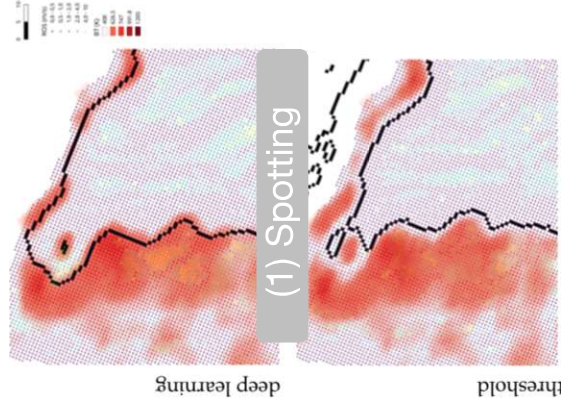
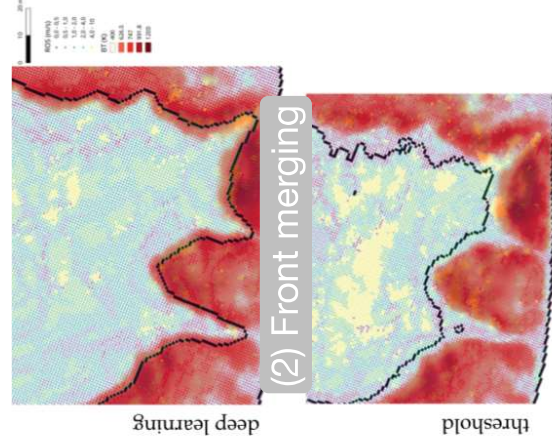
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Talk's conclusion

Data assimilation for wildland fire behavior



Strategy: Aggregate information from
observed and simulated fire fronts

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Data assimilation for wildland fire behavior



Strategy: Aggregate information from observed and simulated fire fronts

- ▶ Front observations
- ▶ Front data assimilation
- ▶ State-parameter estimation
- ▶ Coupled fire-atmosphere simulations

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Perspective: Re-analysis of wildfire events

- ▶ Test on a large dataset of wildland fires
 - Extension to wildfire hazards
 - Sensitivity of the data assimilation results to the observation frequency and resolution

Data assimilation for wildland fire behavior



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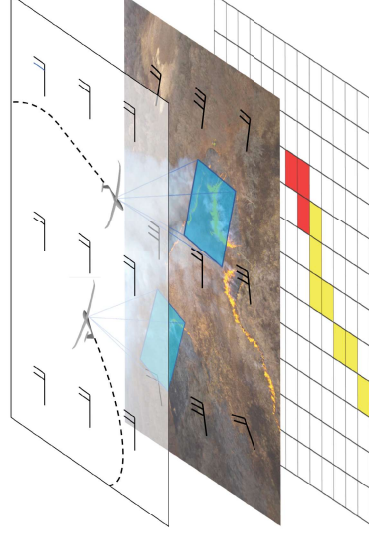
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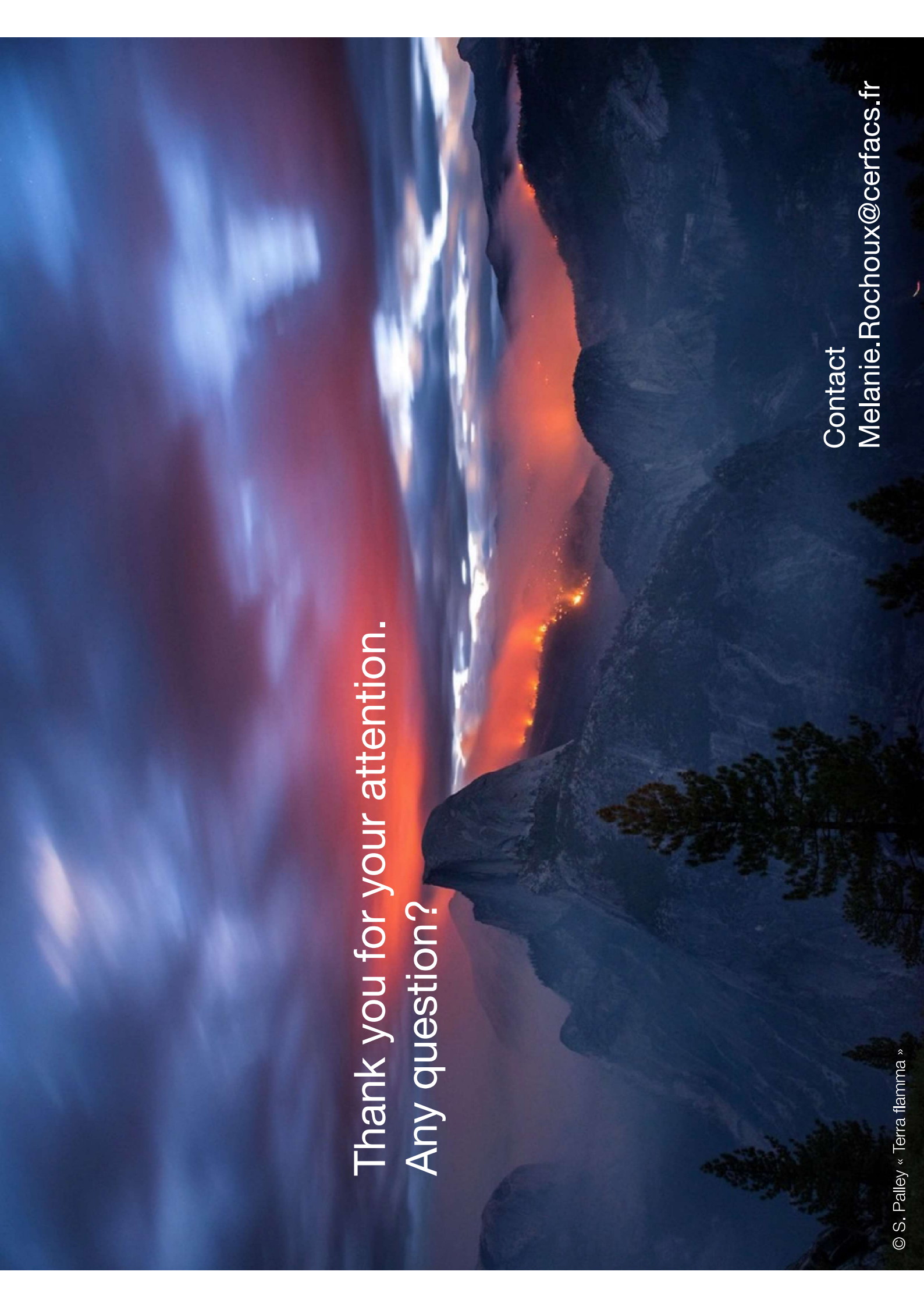
- ▶ Test on a large dataset of wildland fires
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Prospective: Assimilating UAV data?

- ▶ Ideas/questions
 - Idea: adjustment of drone flight plan according to data-driven simulations
 - Feasibility? Flight altitude? Turbulent conditions near the fire
 - Data resolution/quality?



Data assimilation can be used to design an observation network using “synthetic” experiments.



Thank you for your attention.
Any question?

Contact
Melanie.Rochoux@cerfacs.fr