

Meteorological Applications of Unmanned Aerial Systems

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Outline

Unmanned Aerial Systems and payload:

- M²AV
- ALADINA

Meteorological Applications:

- Afternoon transition (BLLAST)
- Polar boundary layer (Polarstern campaign)
- New particle formation (Melpitz)





Meteorological Mini Aerial Vehicle (M²AV)



- In operation since 2005
- Wing span: 2 m
- Air speed 22 m/s
- Weight: ca. 6 kg
- Payload: 1,5 kg
- Automatic turbulence
 - measurement system
 - (3D wind, temperature, humidity)
- Data acquísition rate: 100 Hz







Payload M²AV



3D Wind:

5-hole probe, GPS, IMU:

- 100 Hz data acquisition
- High accuracy during level flights

Humidity:

Vaisala Humicap:

- 0...98 %
- Response time: 1 s during flight
- High accuracy

Temperature:

Vaisala Pt1000:

- -40...+60 °C
- Respone time: 1 s im Flug
- High accuracy

Thermocouple:

- -40...+60 °C
- Response time 0,05 s
- Bad long-term stability
- Development and fabrication at TU Braunschweig
- \rightarrow Payload developed by Jens Bange, now professor at University Tübingen

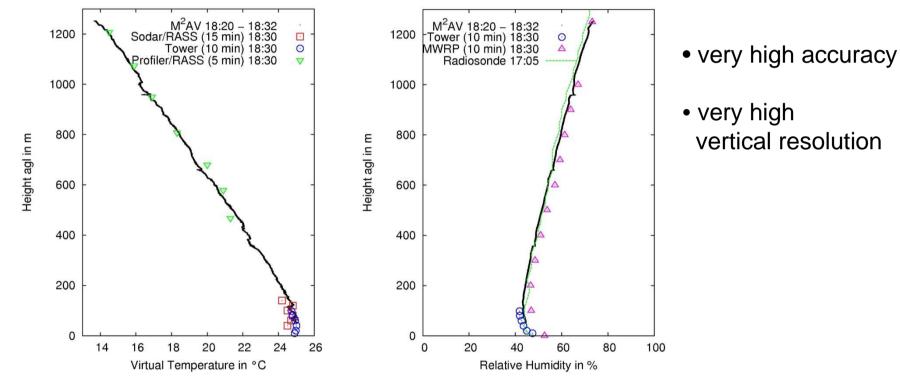






Validation M²AV – Temperature, humidity

LITFASS-2009 (21.07.2009)



Martin et al., 2011

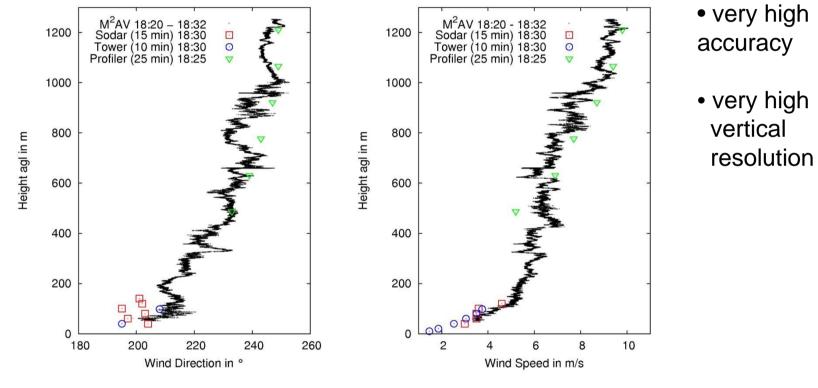


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Validation M²AV – Wind

LITFASS-2009 (21.07.2009)



Martin et al., 2011

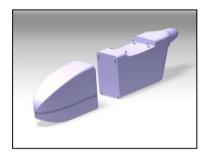


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Application of Light-Weight Aircraft for Detecting In-situ Aerosol (ALADINA)







- Based on Carolo P360 airframe
- Wing span: 3,6 m
- Air speed 20 30 m/s
- max. take off weight: 25 kg
- Payload: 3 kg
- ALADINA in operation since 2013
- Data acquísition rate: 100 Hz
- Automatic turbulence measurement system (3D wind, temperature, humidity)
- Aerosol, black carbon, irradiance...

Project with Uni Tübingen, TROPOS Leizig, funded by German Research Foundation





ALADINA operation

- Flight permission of local CAA authorities
- Automatic flight (Research Onboard Computing System, ROCS of University Stuttgart)
- Takeoff / landing manually, visual contact with safety pilot required
- Maximum flight altitude 1000 1500 m (depending on CAA regulations)
- Maximum radius of operation 1 km



Ground control station (data / autopilot)



Safety pilot



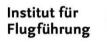
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Research objective ALADINA

- Formation of new particles in the atmospheric boundary layer
- Vertical variability of aerosol, depending on thermal structure
- Horizontal variability on a small scale

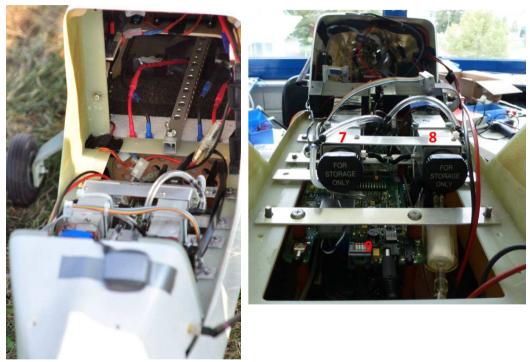






Payload ALADINA

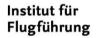




1 five-hole probe, 2 temperature sensor (Thermocouple) and humidity sensor P14 Rapid, 3 aerosol inlet, 4 fast temperature sensor (Fine wire platinum resistance thermometer), 5 GPS antenna, 6 telemetry antenna 7 first CPC 8 second CPC 9 OPC



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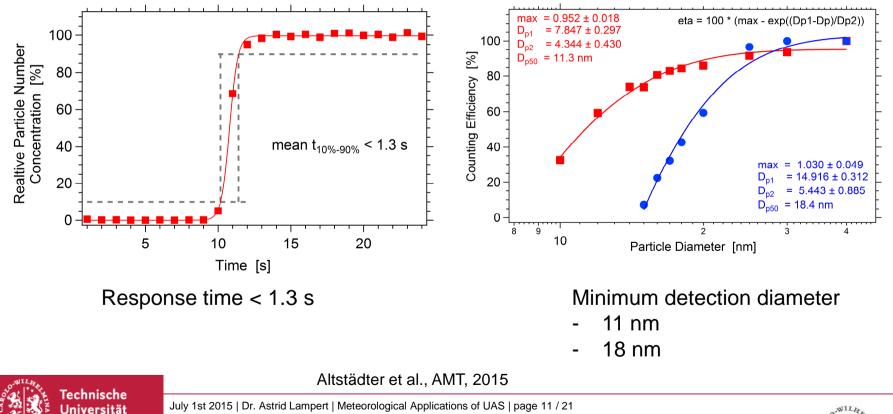




Characterisation modified aerosol sensors

2 CPC (condensation particle counter) 1 OPC (optical particle counter)

Braunschweig

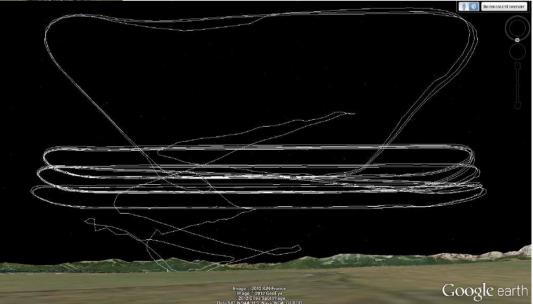




Afternoon transition (BLLAST)



MMAV operation at "Site 1" during BLLAST 2011

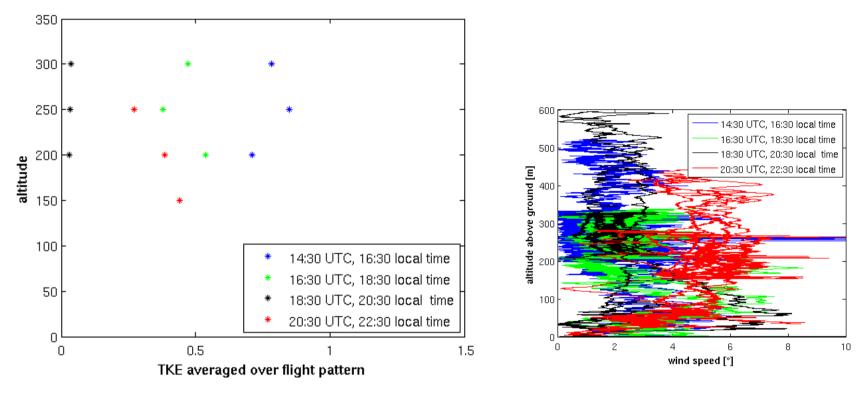




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Afternoon transition (BLLAST)



Preliminary results!



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MMAV Antarctica, Polarstern 2013



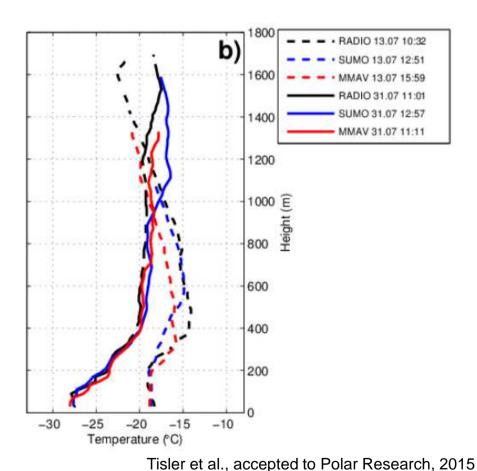
Pictures: M. Hoppmann, M. Krüger, AWI



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MMAV Antarctica, Polarstern 2013



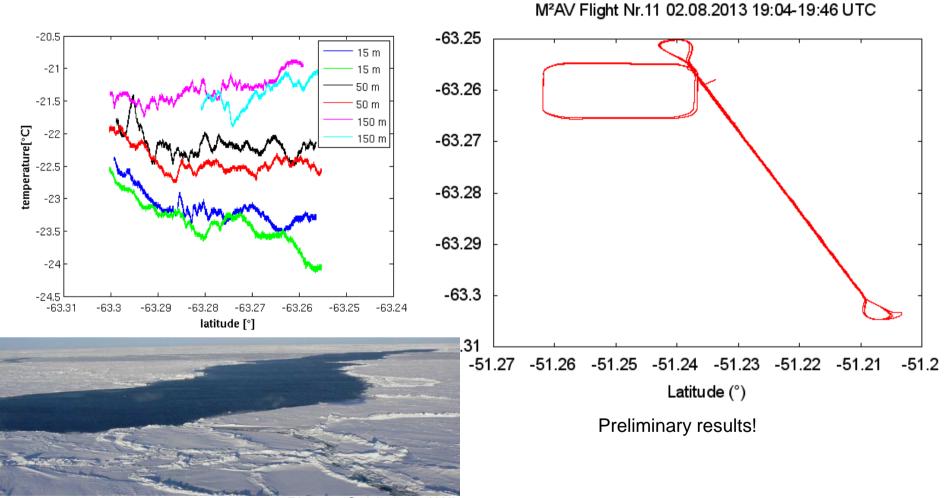
- Winter atmosphere above sea ice
- small-scale structure of the atmospheric boundary layer
- Ground-based temperature inversions
- Intercomparison UAS/ radiosonde
- Influence of leads







MMAV Antarctica, Polarstern 2013



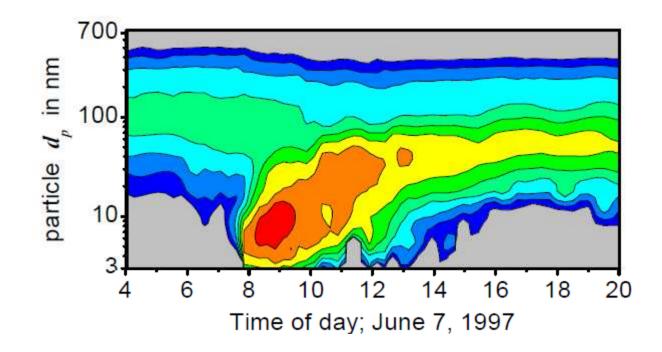
Picture: C. Lüpkes, AWI



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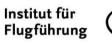
Ground-based observations:



Birmili and Wiedensohler, GRL, 2000

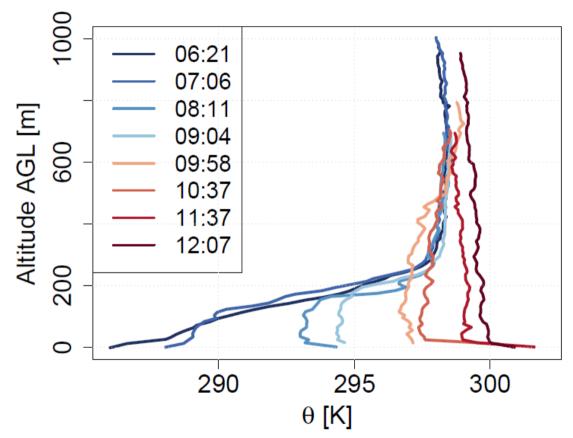


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Vertical profiles of potential temperature during morning transition



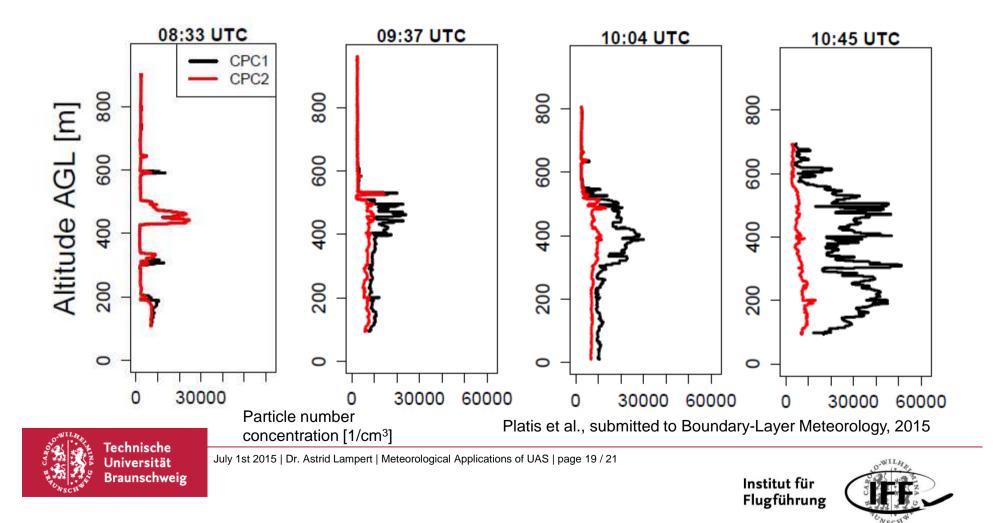
Platis et al., submitted to Boundary-Layer Meteorology, 2015

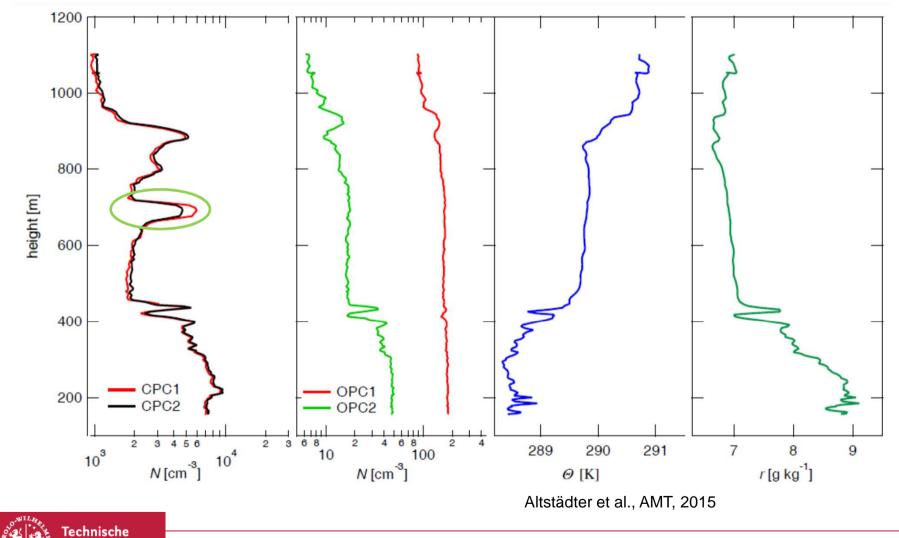


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Vertical profiles of aerosol concentration (CPC1 > 5 nm, CPC2 > 10 nm)







Universität Braunschweig



... ready for new projects

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