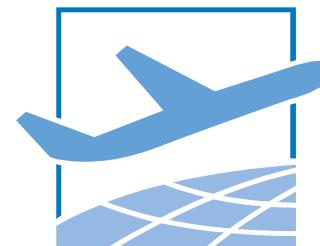
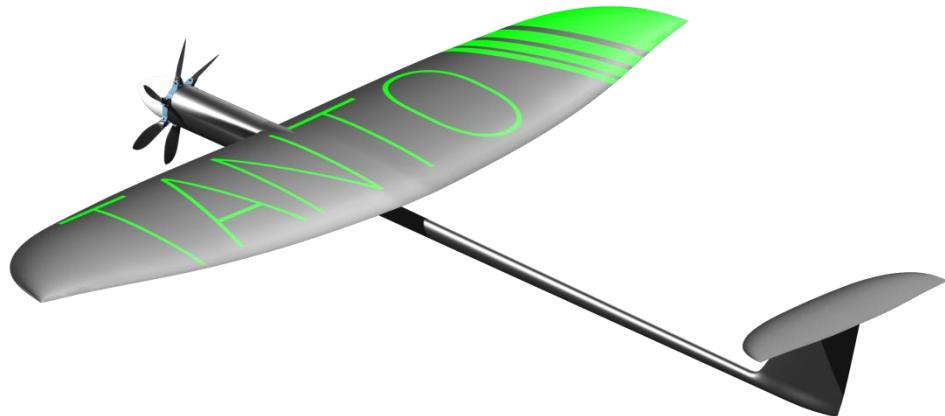


On the design of a 500 km/h electrically driven Mini-UAV

Dr.-Ing. Christian Rößler



Institute of Aircraft Design

01.July 2015

Contents

- **Introduction and design goals**
- Design methodology
- Results
- Manufacturing
- Current State
- Outlook

UAS Research

Research at the Institute for Aircraft Design at TU München focuses on

- derivation of consistent UAV concepts from operational requirements through an integrated conceptual design of airvehicle and mission payload
- exploration and design of modular/multi-mission capable air vehicles
- exploration, design and test of novel energy and propulsion concept for increased operational performance, incl. requirements derived from civil operations (e.g. noise and visual signature, emissions)
- provision of demonstrators (ground and airborne) for verification of systems and operations

Integrated Design Environment

To optimize UAV the Institute of Aircraft Design works on:

- An integrated UAV design environment
- The integration of propulsion systems in coherence with airframe design
- The integration of general avionics and mission systems in coherence with airframe design
- The operational analysis of UAV designs (performance, sensor integration, environmental impact) in the operational context



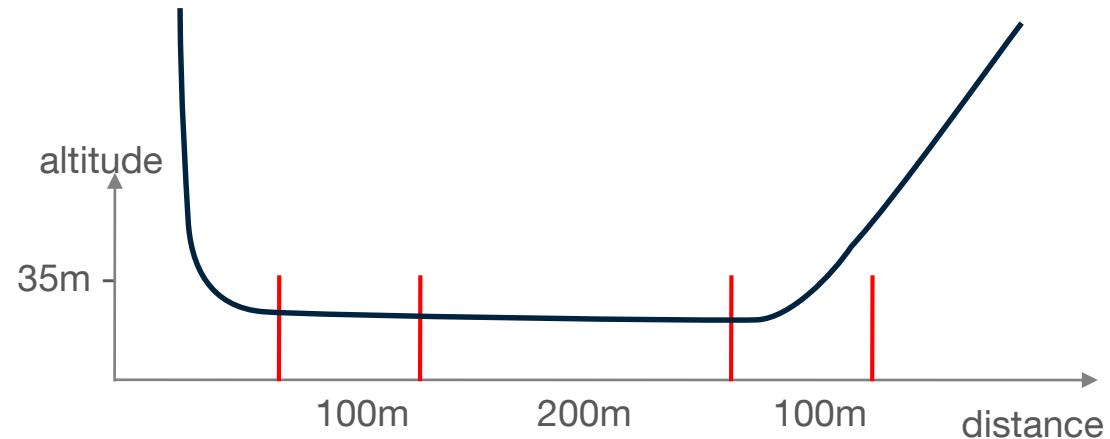
On the design of a 500 km/h electrically driven Mini-UAV

Goal:

Set a new speed world record for electrically powered airplanes!

Rules (FAI sub-class 175):

- Max. wing loading 75 g/dm^2
- Max. Takeoff weight 5 kg
- Max. Voltage 72 V
- Timeframe 4 min
- Average of fastest flight over 200m distance from both directions



Current Speed World Records

Manned electric speed records

- | | | | |
|---------------------|-------------------|-------------------------------|-----------------|
| • 10.06.2009 | Maurizio Cheli | SkySpark | 250 km/h |
| • 05.09.2010 | Hugues Duval | MC15E CriCri "E-Cristaline" | 262 km/h |
| • 25.06.2011 | Hugues Duval | MC15E CriCri "E-Cristaline" | 283 km/h |
| • 19.07.2012 | Chip Yates | modified Rutan Long-EZ | 324 km/h |
| • 06.10.2013 | Chip Yates | modified Rutan Long-EZ | 347 km/h |

Officially approved speed records electrical motor rechargeable sources (model airplanes) (from Fédération Aéronautique Internationale (FAI) - the governing body for aviation records)

- | | | |
|---------------------|-----------------------|-------------------|
| • 10.06.2007 | David Dzida | 361.0 km/h |
| • 27.08.2009 | Jakob Karpfinger | 420.24 km/h |
| • 17.09.2011 | David Dzida | 439.14 km/h |
| • 15.09.2013 | Niklas Kahlich | 477.3 km/h |

Actual speed record combustion engine category F3

- | | | |
|--------------|---------------------|-------------|
| • 17.09.2011 | Dag Cammann-Walczak | 405.30 km/h |
|--------------|---------------------|-------------|



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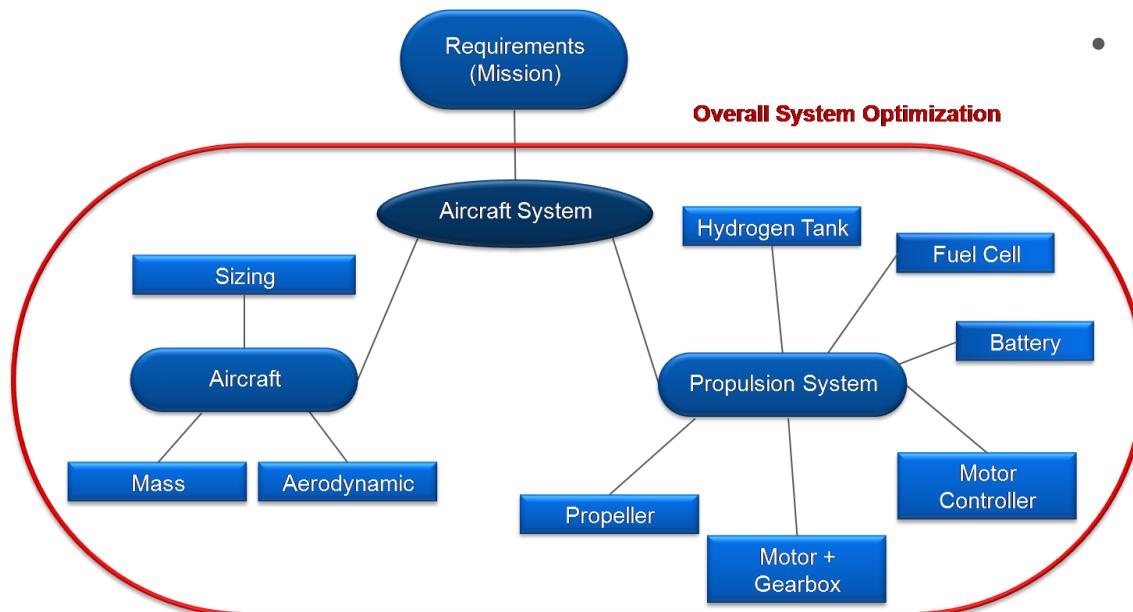


Hybrid Propulsion UAVs – Design Methodology for small UAV

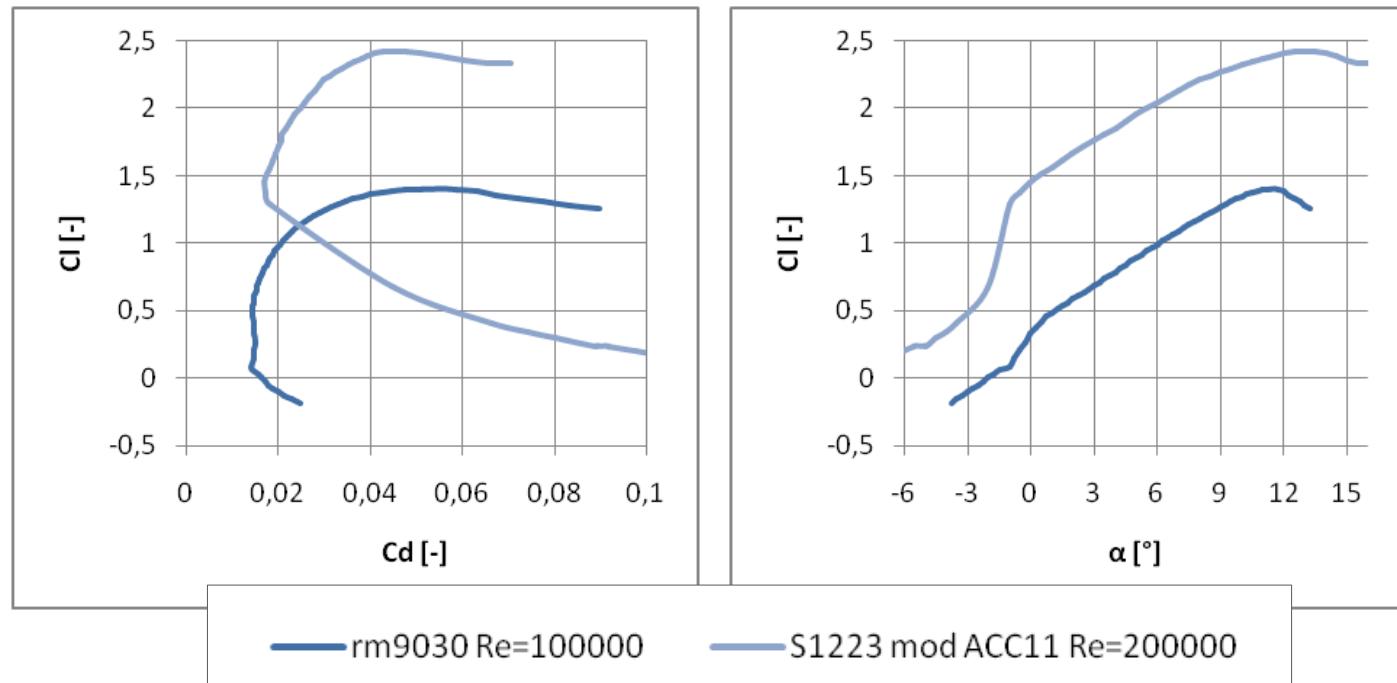
- Integrated Design Methodology mandatory
- Model matching from off-the-shelf and generic systems

Design models required and developed for:

- Aerodynamics
- Structure / mass estimation
- Weight and balance
- Electric propulsion (incl. motor and propeller efficiency matching)



Aerodynamic

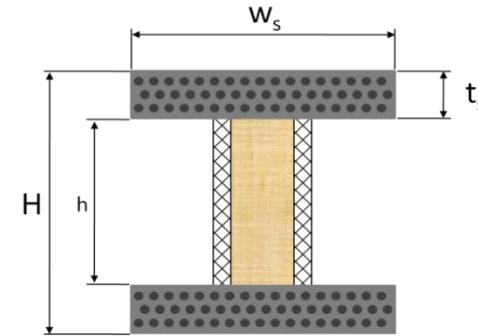
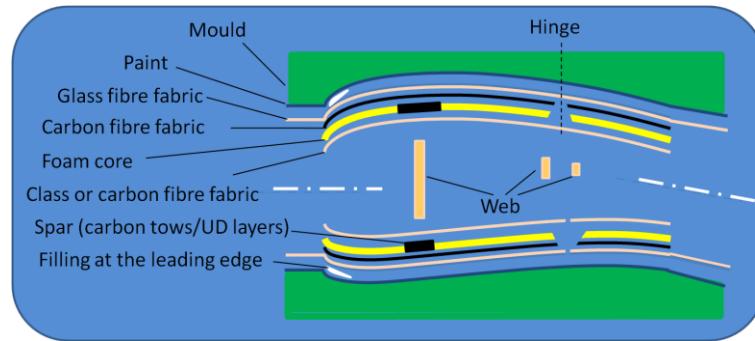


- PAWAT: Extended lifting line theory combined with viscous airfoil data from xfoil or wind tunnel
- Non - linearity because of viscous effects due to low Reynolds numbers can be modeled



Mass calculation

- Combination of sizing of components (spar, wing shell) ...



- And empirical measurement results (paint, glue)

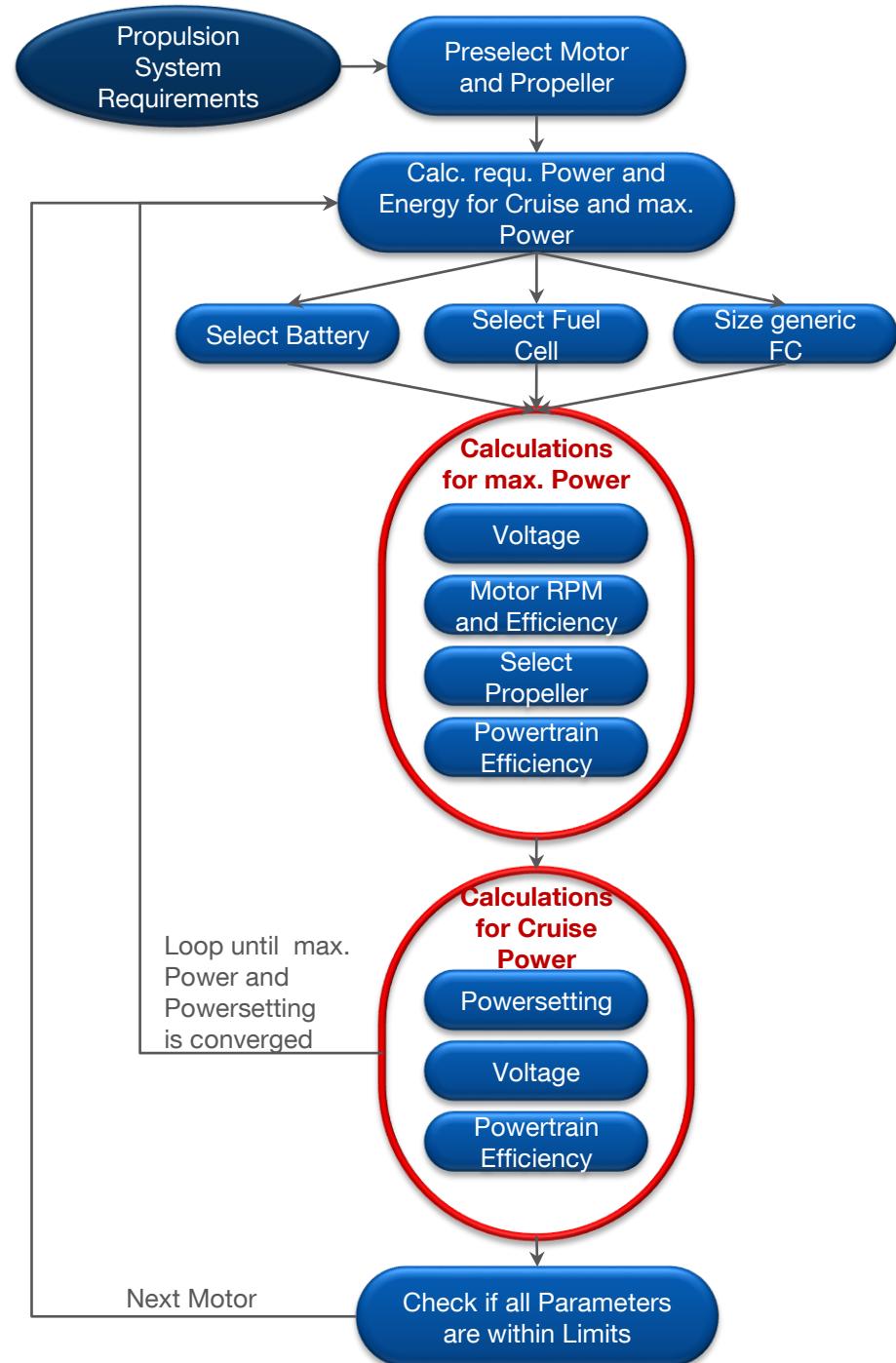
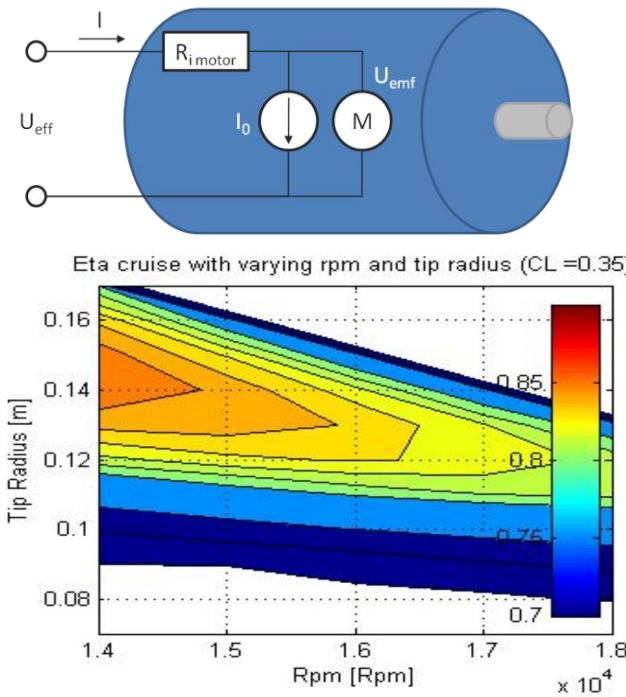
Name	Value and Unit	Normalized by
Filling at the Leading Edge	36 g/m/m	Span [m], Chord [m]
Bonding Leading Edge	4 g/m/mm	Span [m], Core Material Thickness [mm]
Bonding Trailing Edge	5 g/m	Span [m]
Bonding Webs	4 g/m/mm	Span [m], Web Width [mm]
Paint	54 g/m ²	Surface [m ²]

Summarizing of all masses:

$$m_{component} = \sum m_{sized} + \sum k_{empirical} \cdot D$$

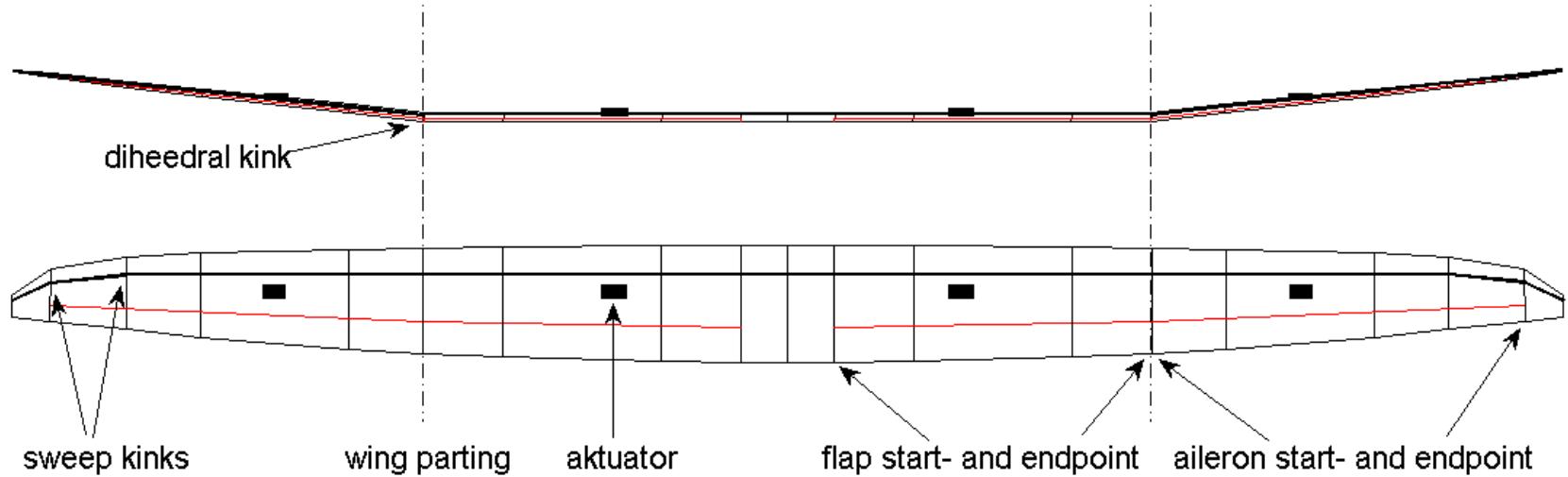
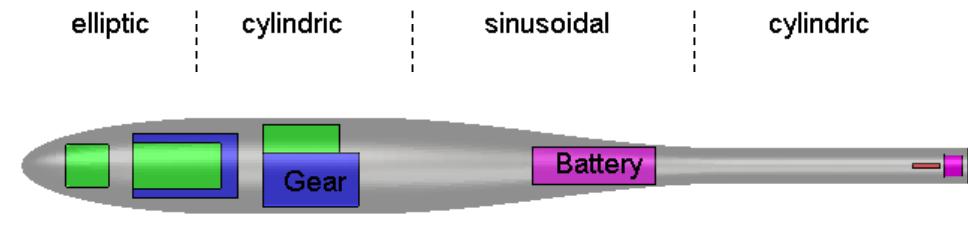
Propulsion System

- Matching of components is important
- Finding the lightest propulsion system to match the requirements

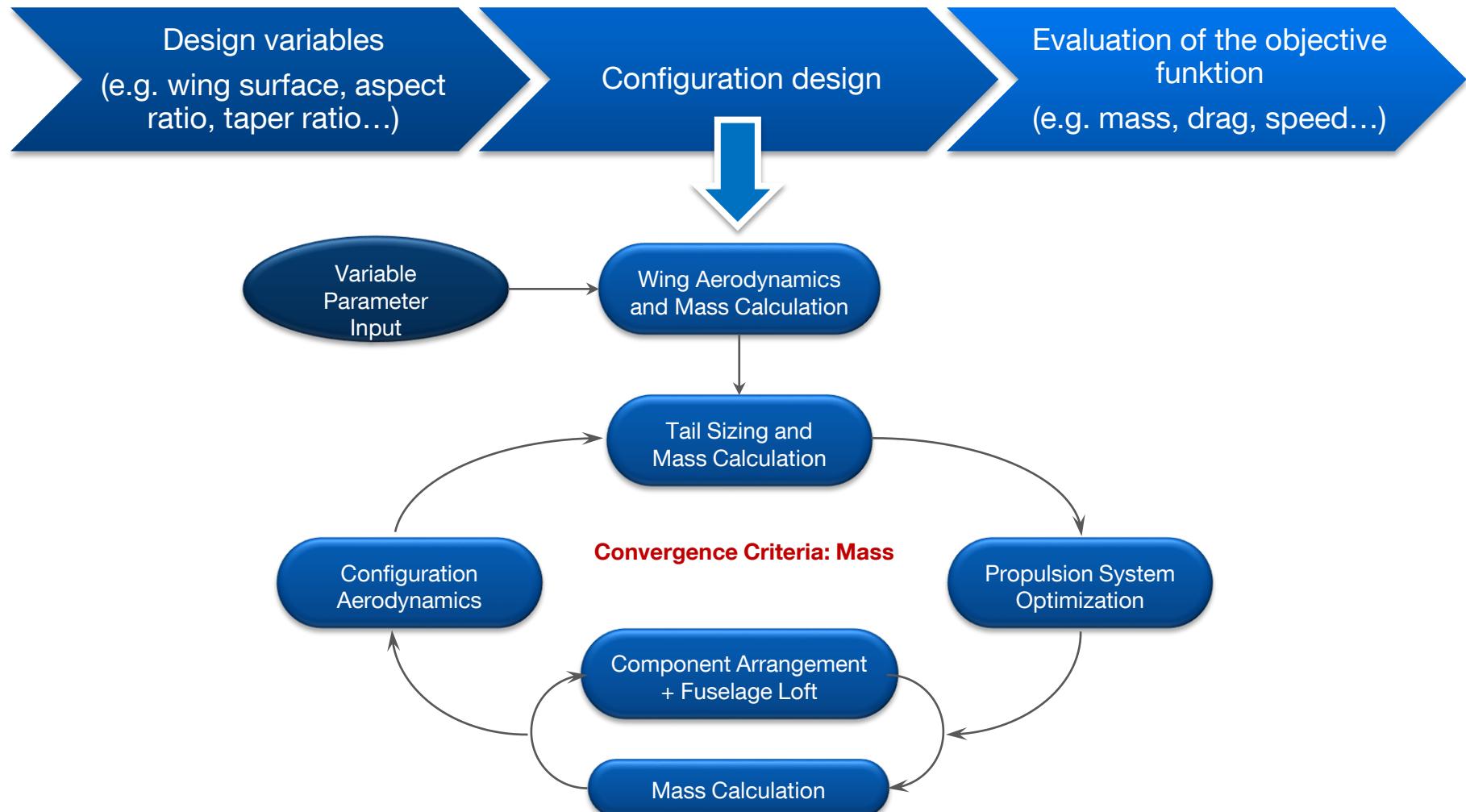


Sizing

- Alignment of components
- Adjustment of center of gravity
- Fuselage sizing
- Empennage sizing



Configuration design is only possible iteratively



Contents

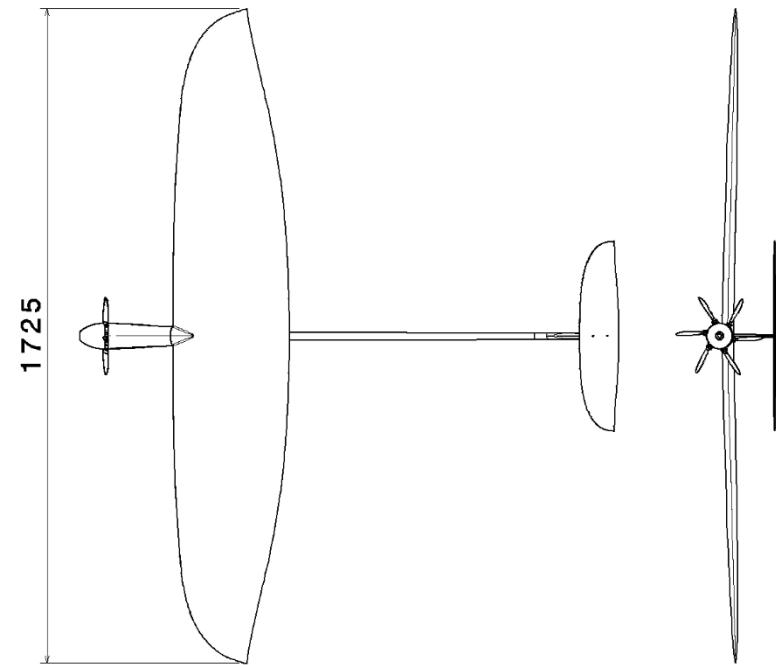
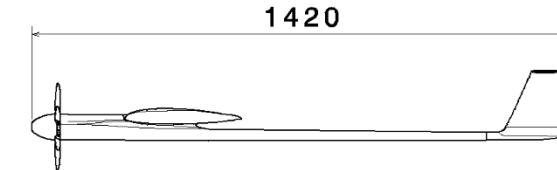
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F3S Airplane Tanto – Technical Data

Take off weight:	3.5 kg
Wing loading:	74.9 g/dm ²
Span:	1.73 m
Aspect ratio:	7
Wing surface:	0.43 m ²
Horizontal tail surface:	0.04 m ²
Vertical tail surface:	0.018 m ²

Max. speed > 500 km/h ~ 140 m/s



F3S Airplane Tanto – Propulsion System

Technical Data:

Design cruise power 13 kW

Propeller:

- Self made 6 blade 9.5 x 26 inch

Motor:

- Kontronik Pyro 800 modified
- Mass 540 g

Controller

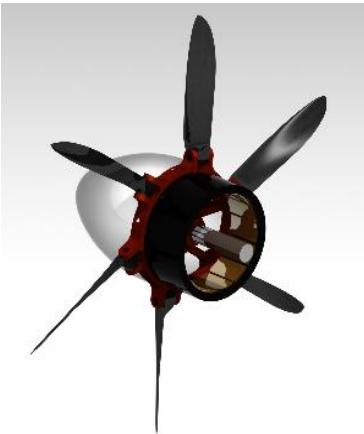
- Kontronik Kosmik 200 HV+
- Mass 290g

Batteries

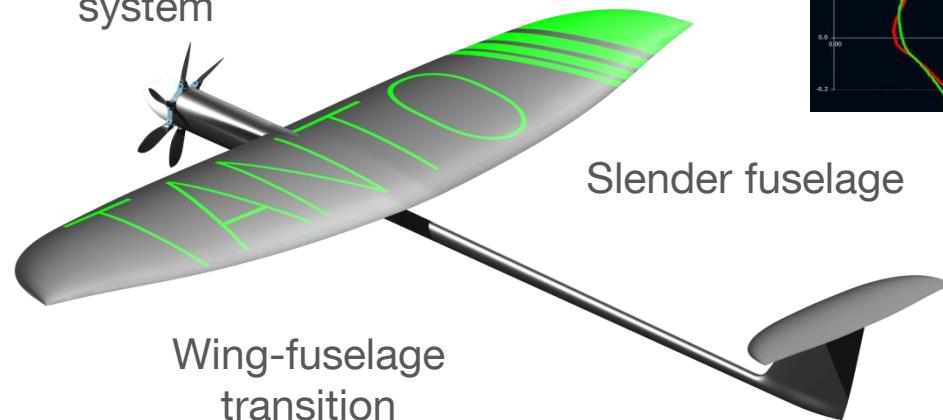
- 13S 4000 mAh GensAce 60/120C
- Mass 1.7 kg



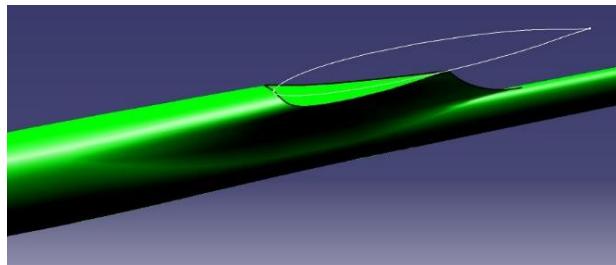
F3S Airplane Tanto - Features



6-blade
propulsion
system



Batteries integrated
in the wing



Long tail moment arm

Contents

- Introduction and design goals
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The Team

Akademic Aeromodelling Group of Munich

→ Association of students and academic researchers of Universities in Munich

Our Motto: **Design, build and fly!**

One new project every year:

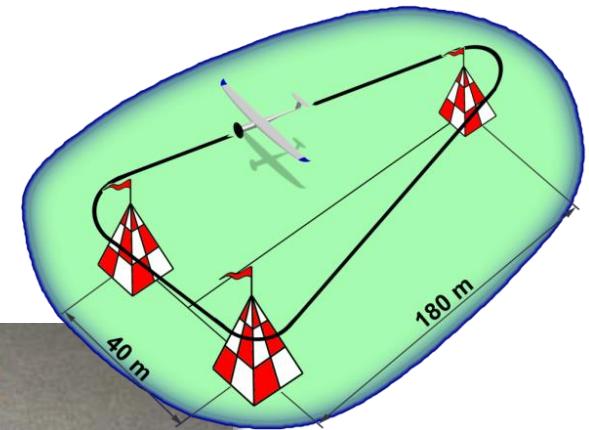
- Model Competition Airplanes: F5D, F3K
- Student Competitions: Air Cargo Challenge
- Research: Airfoil Development, Building methods etc.
- Fun projects: Aircombat flying wing, Aero towing airplane etc.



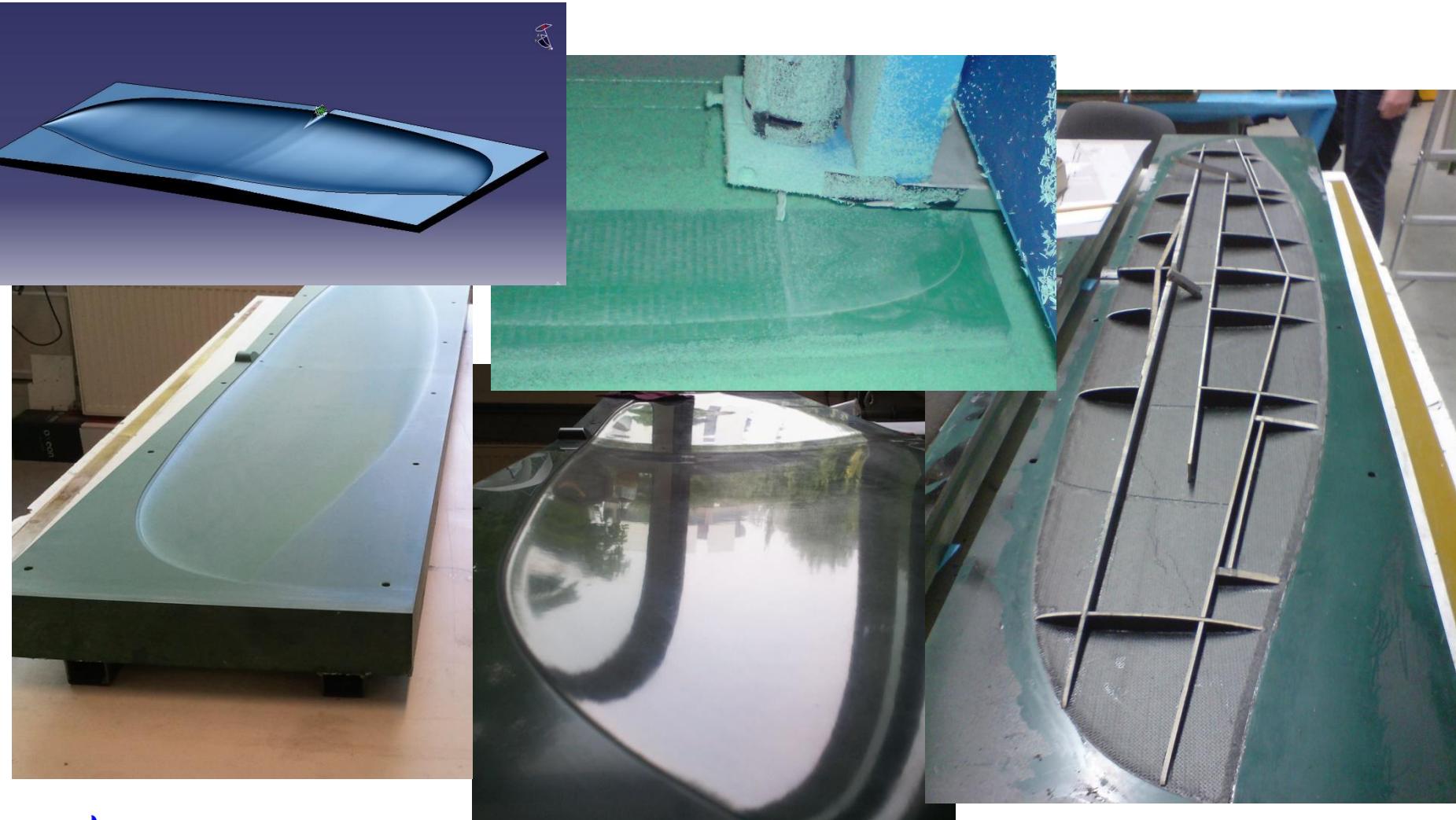
Previous Experience

F5D: Electro-Pylonracing

- 10 rounds in a triangular course – the fastest wins
- Speeds over 300 km/h
- 50 g turns
- **World champion 2006**
- **New World record** with 63,4 seconds



F3S Airplane Tanto – Manufacturing



Contents

- Introduction and design goals
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F3S Airplane Tanto – Current State



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- Introduction and design goals
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Outlook

- Test Flights up to 6 kW of power and 420 km/h
- Ground tests for 9 kW successful
- **Ground tests up to 13 kW successful (30s)**
- More funding required
- Flight tests
- World record attempt



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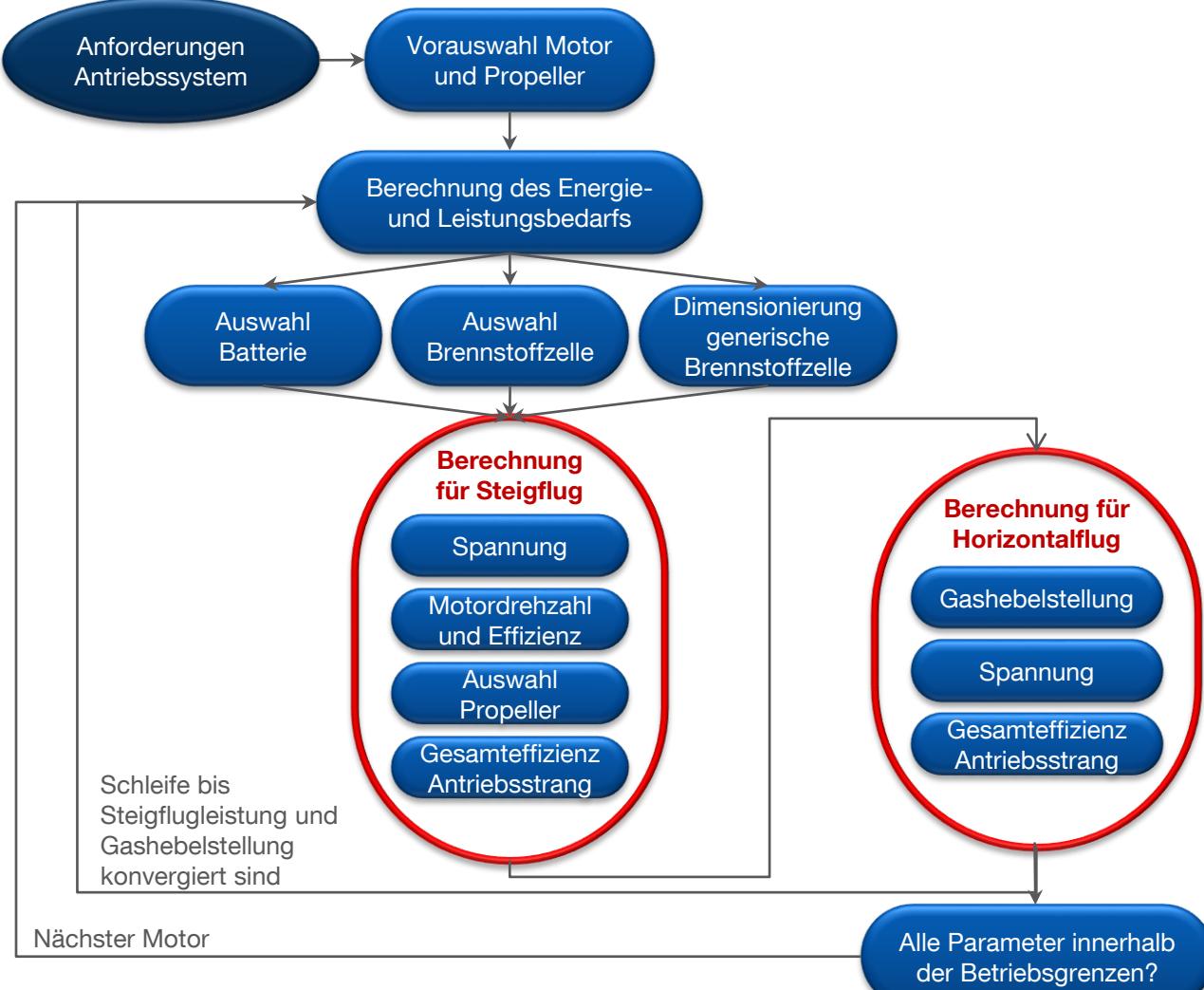
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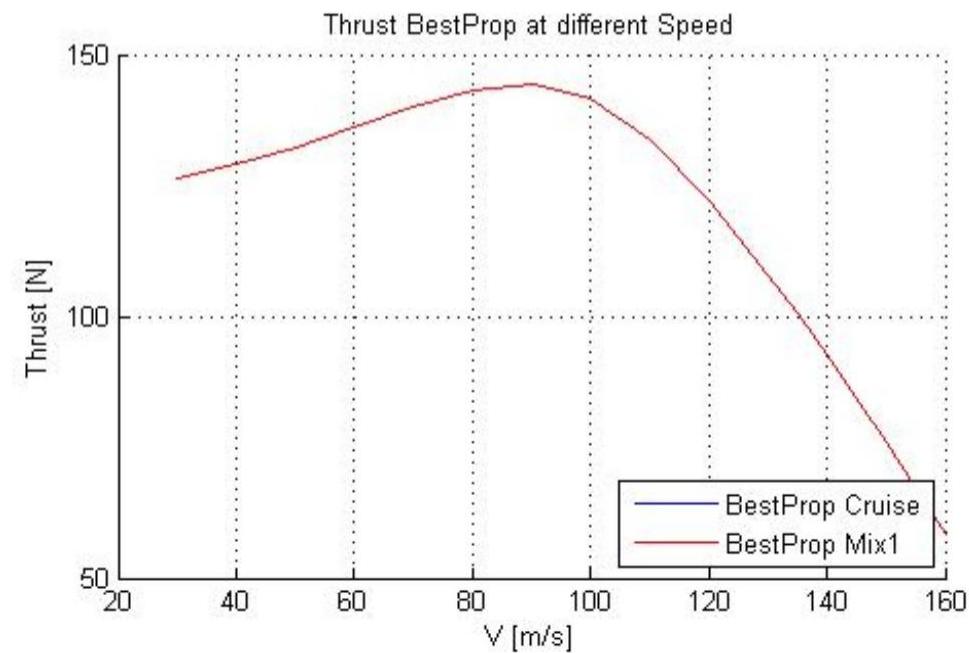
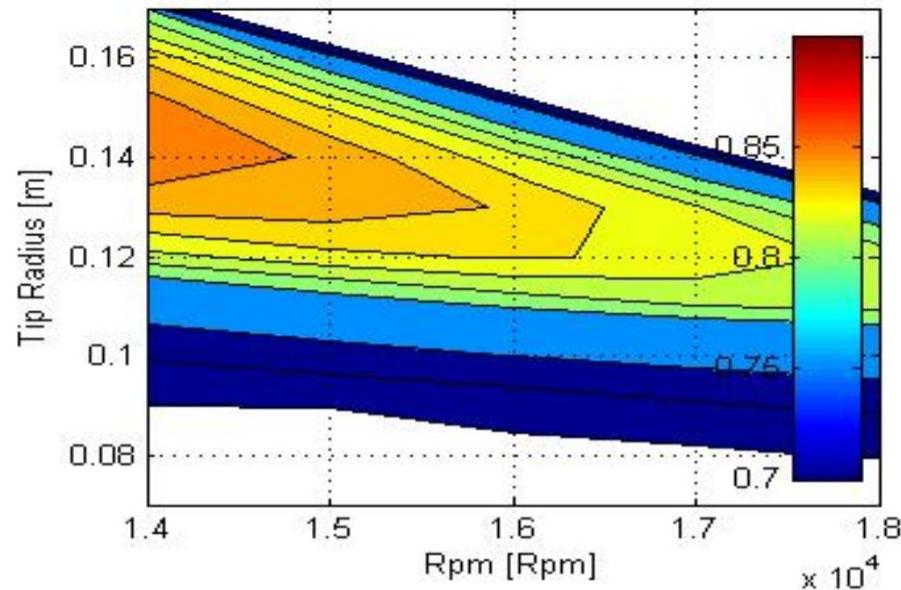
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Antriebssystem

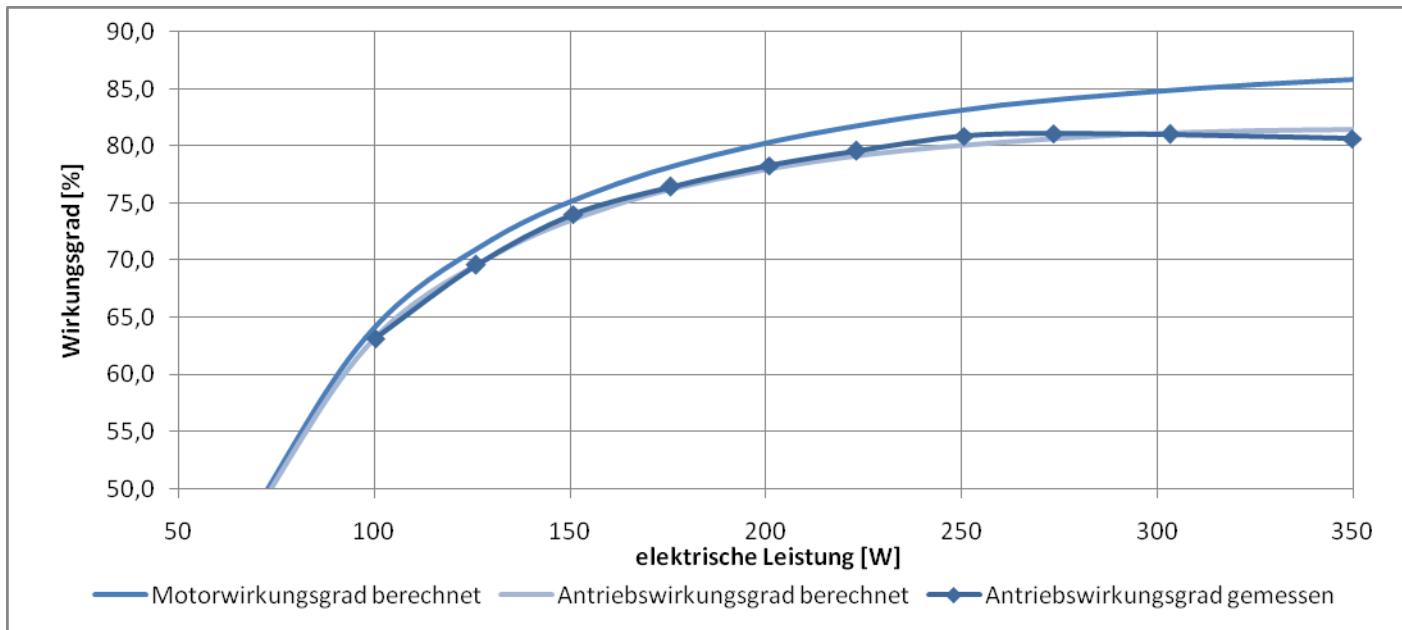
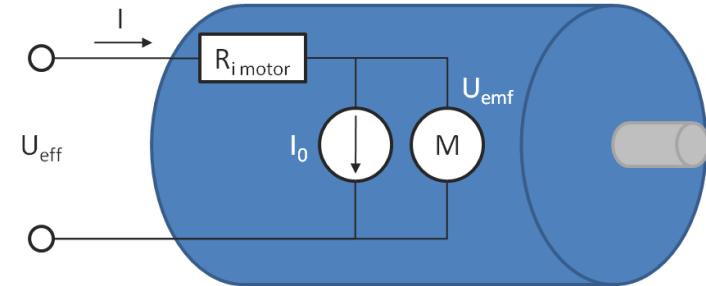


Eta cruise with varying rpm and tip radius ($CL = 0.35$)

Berechnungsmethode für elektrische Antriebe

Vollgas:

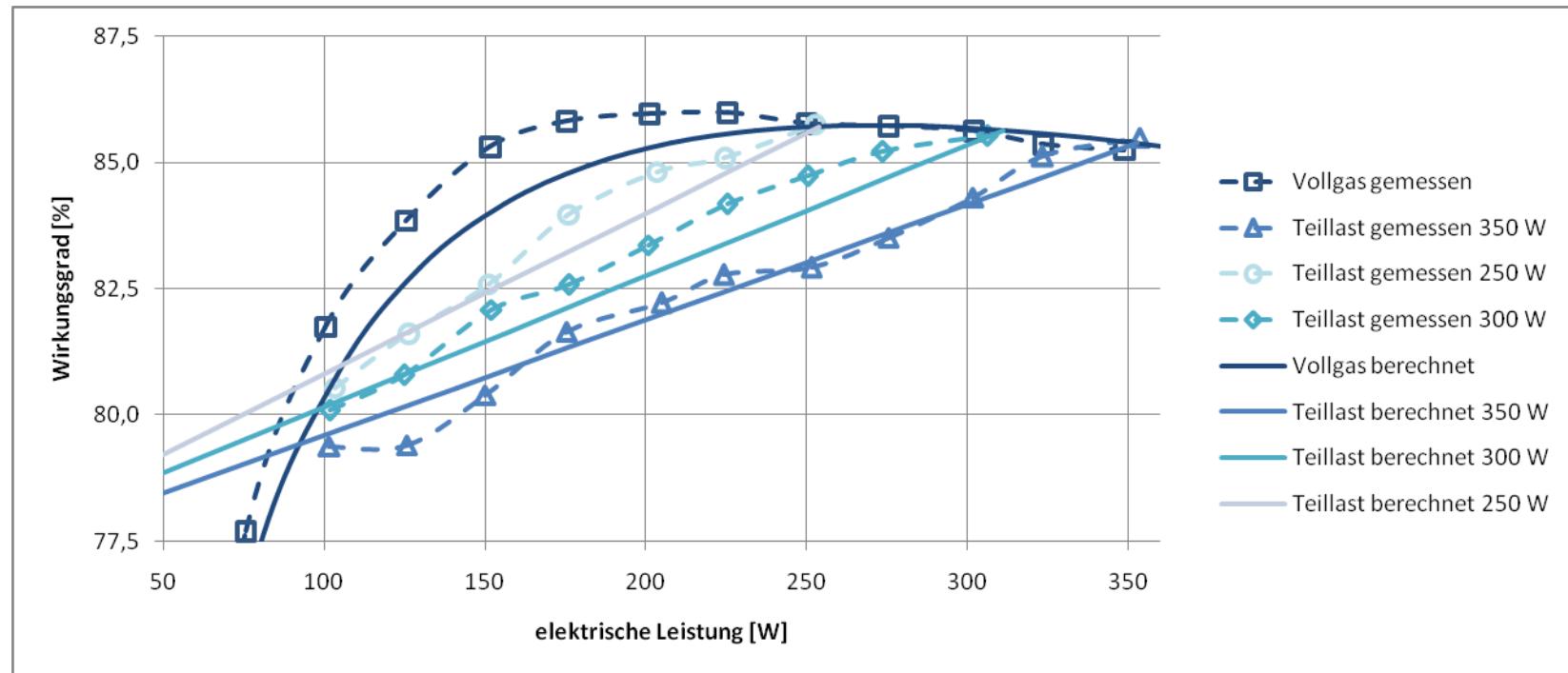
- Motorparameter durch drei Motorkonstanten (R_i , I_0 und K_v) berechenbar
- Motorregler durch zusätzlichen Innenwiderstand erfassbar



Berechnungsmethode für elektrische Antriebe

Teillast

- Messungen am Motorprüfstand
- Zusätzliche Verluste, hauptsächlich durch Schaltvorgänge im Regler
- Ableitung eines mathematischen Zusammenhangs



Stress Test

- Sand sacks and weights
- Design limit at -2/+5 g
- Test limit at 4.2 g due to extensive sag
- Stress test passed

+126 kg
4.2g

